# M.SC. PHYSICS - I YEAR <br> DKP11 : CLASSICAL AND STATISTICAL MECHANICS <br> SYLLABUS 

## Unit 1: Lagrangian and Hamiltonian formulations

Hamilton's principle - Derivation of Lagrange's equations from Hamilton's principle Principle of Least Action and its applications, Canonical Transformation : The Hamiltonian Formalism, Canonical formalism, Hamiltonian equations of motion, Cyclic coordinates, Rauthian procedure and equations, Derivation of Generating functions, examples, properties, Derivation of Hamiltonian equations from variational principle.

## Unit 2: Poisson bracket and theory of small oscillations

Poisson bracket, Special cases of Poisson bracket, Poisson theorem, Poisson bracket and canonical transformation, Jacobi identity and its derivation, Lagrange bracket and its properties, the relationship between Poisson and Lagrange brackets and its derivation, the angular momenta and Poisson bracket, Liouville's theorem and its applications; Theory of small oscillations:

Formulation of the problem, Eigenvalue equation and the principle axis transformation, frequencies of free vibration and normal coordinates, free vibrations of a linear triatomic molecule

## Unit 3: Two - body central force problem and $\mathbf{H}$ - J theory

Two body central force problem: Reduction to the equivalent one body problem, the equation of motion and first integrals, classification of orbits, the virial theorem, the differential equation for the orbit, integral power law in time in the Kelper's problem ,scattering in central force field;

H-J Theory: H-J equation and their solutions, use of H-J method for the solution of harmonic oscillator problem, Hamilton's principle function, Hamilton's characteristic function and their properties, Action angle variable for completely separable systems, the Kelper's problem in action angle variables

## Unit 4: Classical Statistical Mechanics

Foundation of Statistical Mechanics: The macroscopic and microscopic states, postulate of
equal a priori probability, Contact between statistics and thermodynamics; Ensemble theory: Concept of ensemble, phase space, Density function, Ensemble average, Liouville's theorem, Stationary ensemble; The microcanonical ensemble, Application to the classical ideal gas; The canonical and grand canonical ensembles, Canonical and grand canonical partition functions, Calculation of statistical quantities; Thermodynamics of a system of noninteracting classical harmonic oscillators using canonical ensemble, and of classical ideal gas using grand canonical ensemble, Energy and density fluctuations; Entropy of mixing and the Gibb's paradox, Sackur-Tetrode equation .

## Unit 5: Quantum Statistical Mechanics

Quantum-mechanical ensemble theory: Density matrix, Equation of motion for density matrix, Quantum- mechanical ensemble average; Statistics of indistinguishable particles, Two types of quantum statistics- Fermi-Dirac and Bose-Einstein statistics, Fermi-Dirac and Bose-Einstein distribution functions using microcanonical and grand canonical ensembles (ideal gas only), Statistics of occupation numbers; Ideal Bose gas: Internal energy, Equation state, Bose-Einstein Condensation and its critical conditions; Bose-Einstein condensation in ultra-cold atomic gases: its detection and thermodynamic properties: Ideal Fermi gas: Internal energy, Equation of state, Completely degenerate Fermi gas.

## Books for Study and Reference

1.Classical Mechanics ( $3^{\text {rd }}$ ed.,2002) by H. Goldstein, C.Poole and J. Safko, Pearson Edition
2. Classical Mechanics - J. C. Upadhyaya- Second Edition-2005-Himalaya Publishing House
3.Classical Mechanics - G. Aruldhas-2008-PHI Learning Pvt.Ltd.
4.Classical Mechanics-A Text Book-Suresh Chandra-Narosa Publications
5.Statistical Mechanics by R. K. Pathira (2 $2^{\text {nd }}$ edition)
6.Statistical Mechanics by R.K. Pathira and P.D. Beale ( ${ }^{\text {rd }}$ edition)
7.Statistical Mechanics by K.Huang
8.Statistical Mechanics by L.D.Landau and I.M.Lifshitz

## UNIT 1: LAGRANGIAN AND HAMILTONIAN FORMULATIONS

Hamilton's principle - Derivation of Lagrange's equations from Hamilton's principle Principle of Least Action and its applications, Canonical Transformation : The Hamiltonian Formalism, Canonical formalism, Hamiltonian equations of motion, Cyclic coordinates, Rauthian procedure and equations, Derivation of Generating functions, examples, properties, Derivation of Hamiltonian equations from variational principle.

## LAGRANGIAN AND HAMILTONIAN FORMULATIONS

Hamilton's principle - Derivation of Lagrange's equations from Hamilton's principle Principle of Least Action and its applications, Canonical Transformation : The Hamiltonian Formalism, Canonical formalism, Hamiltonian equations of motion, Cyclic coordinates, Rauthian procedure and equations, Derivation of Generating functions, examples, properties, Derivation of Hamiltonian equations from variational principle.

### 1.1 HAMILTON'S PRINCIPLE:

The motion of the system from time $t_{1}$ to time $t_{2}$ is such that the line integral

$$
I=\int_{t_{1}}^{t_{2}} L d t
$$

Where $\mathrm{L}=\mathrm{T}-\mathrm{V}$, is an extremum for the path of motion

$$
\begin{equation*}
\delta \mathrm{I}=\delta \int_{\mathrm{t}_{1}}^{\mathrm{t}_{2}} \mathrm{Ldt}=0 \tag{or}
\end{equation*}
$$

$\delta$ is the variation symbol.

## Deduction of Lagrange's equations:

Consider a conservative system of particles. The integral can be written as

$$
\int_{t_{1}}^{t_{2}}\left[T\left(q_{j}, \dot{q}_{j}\right)-V\left(q_{j}\right)\right] \mathrm{dt} .
$$

According to Hamilton's variational principle, we have

$$
\begin{aligned}
& \delta \int_{t_{1}}^{t_{2}}\left[T\left(q_{j} \dot{q}_{j}\right)-V\left(q_{j}\right)\right] \mathrm{dt}=0 \\
& \int_{t_{1}}^{t_{2}} \sum_{j}\left[\left(\frac{\partial T}{\partial q_{j}} \delta q_{j}+\frac{\partial T}{\partial \dot{q}_{j}} \delta \dot{q}_{j}\right)-\frac{\partial V}{\partial q_{j}} \delta q_{j}\right] \mathrm{dt}=0 \\
& \int_{t_{1}}^{t_{2}} \sum_{j}\left(\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}\right) \delta q_{j} d t+\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial T}{\partial \dot{q}_{j}} \delta \dot{q}_{j} d t=0
\end{aligned}
$$

$$
\int_{t_{1}}^{t_{2}} \sum_{j}\left(\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}\right) \delta q_{j} d t+\int_{t_{1}}^{t_{2}} \sum \frac{\partial T}{\partial \dot{q}_{j}} \frac{d}{d t}\left(\delta q_{j}\right) d t=0
$$

Integrating by parts the second term, we get
$\int_{t_{1}}^{t_{2}} \sum_{j}\left(\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}\right) \delta q_{j} d t+\left.\sum_{j} \frac{\partial T}{\partial \dot{q}_{j}} \delta q_{j}\right|_{t_{1}} ^{t_{2}}-\int_{t_{1}}^{t_{2}} \frac{d}{d t}\left(\frac{\partial T}{\partial \dot{q}_{j}}\right) \delta q_{j} d t=0$
There is no coordinate variation at end points and hence
$\left.\delta q_{j}\right|_{t_{1}} ^{t_{2}}=0$.
Now equation reduces to
$\int_{t_{1}}^{t_{2}} \sum_{j}\left(\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}\right) \delta q_{j} d t-\int_{t_{1}}^{t_{2}} \sum_{j} \frac{d}{d t}\left(\frac{\partial T}{\partial \dot{q}_{j}}\right) \delta q_{j} d t=0$
$\int_{t_{1}}^{t_{2}} \sum\left[\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}-\frac{d}{d t}\left(\frac{\partial T}{\partial \dot{q}_{j}}\right)\right] \delta q_{j} d t=0$
each $\delta q_{j}$ are independent of each other, the coefficient of every $\delta q_{j}$ should be equated to zero. And we get
$\left[\frac{\partial T}{\partial q_{j}}-\frac{\partial V}{\partial q_{j}}-\frac{d}{d t}\left(\frac{\partial T}{\partial \dot{q}_{j}}\right)\right]=0$
$\left[\frac{d}{d t}\left(\frac{\partial T}{\partial \dot{q}_{j}}\right)-\frac{\partial}{\partial q_{j}}(T-V)\right]=0$
V is not a function of $\dot{q}_{j}$ and therefore

$$
\frac{d}{d t}\left[\frac{\partial(T-V)}{\partial \dot{q}_{j}}\right]-\frac{\partial}{\partial q_{j}}(T-V)=0
$$

$\mathrm{T}-\mathrm{V}=\mathrm{L}=$ Lagrangian for a conservation system
$\mathrm{L}=$ Scalar function of $q_{j}, \dot{q}_{j}$ and $t$

$$
\left[\frac{\mathrm{d}}{\mathrm{dt}}\left(\frac{\partial \mathrm{~L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}}\right)-\frac{\partial \mathrm{L}}{\partial \mathrm{q}_{\mathrm{j}}}\right]=0 \quad \mathrm{~J}=1,2, \ldots \ldots . \mathrm{n} .
$$

This set of equations is called Lagrange's equations of motion and each is a second order differential equation in terms of the time as independent variable.

### 1.2 DERIVATION OF LAGRANGE'S EQUATIONS FROM HAMILTON'S PRINCIPLE:

The Lagrangian $L$ is a function of generalized co-ordinates $q_{j}$ 's and generalized velocities $\dot{q}_{\mathrm{j}}$ 's and time t .

$$
\text { That is } L=L\left[q_{j}(t), \dot{q}_{j}(t), t\right]
$$

According to Hamilton's variational principle, motion of a conservative system from finite time $t_{1}$ to time $t_{2}$ is such that the line integral

$$
\mathrm{I}=\int_{t_{1}}^{t_{2}} L\left[q_{j}(t), \dot{q}_{j}(t), t\right] d t
$$

is zero. That is

$$
\delta I=\delta \int_{t_{1}}^{t_{2}} L\left[q_{j}(t), \dot{q}_{j}(t), t\right] d t=0
$$

If the Lagrangian does not depend on time $t$ explicitly, then the variation $\delta \mathrm{L}$ can be written as

$$
\delta L=\sum_{j=1}^{n} \frac{\partial L}{\partial q_{j}} \delta q_{j}+\frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}
$$

Integrating both sides from $t=t_{1}$ to $t=t_{2}$

$$
\int_{t_{1}}^{t_{2}} \delta L d t=\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial q_{j}} \delta q_{j} d t+\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j} d t=0
$$

But from Hamilton's principle

$$
\int_{t_{1}}^{t_{2}} \delta L d t=0
$$

Therefore

$$
\begin{aligned}
& \int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial q_{j}} \delta q_{j} d t+\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j} d t=0 \\
& \delta \dot{q}_{j}=\frac{d}{d t}\left(\delta q_{j}\right)
\end{aligned}
$$

Integrating by parts the second term, we get

$$
\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j} d t=\sum_{j}\left[\frac{\partial L}{\partial q_{j}} \delta q_{j}\right]_{t_{1}}^{t_{2}}-\int_{t_{1}}^{t_{2}} \sum_{j} \frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right) \delta q_{j} d t
$$

There is no coordinate variation at end points and hence

$$
\sum_{j}\left[\frac{\partial L}{\partial q_{j}} \delta q_{j}\right]_{t_{1}}^{t_{2}}=0
$$

Now equation reduces to

$$
\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial q_{j}} \delta q_{j} d t-\int_{t_{1}}^{t_{2}} \sum_{j} \frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right) \delta q_{j} d t=0
$$

(or)

$$
\int_{t_{1}}^{t_{2}} \sum_{j} \frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right) \delta q_{j} d t-\int_{t_{1}}^{t_{2}} \sum_{j} \frac{\partial L}{\partial q_{j}} \delta q_{j} d t=0
$$

$$
\int_{t_{1}}^{t_{2}} \sum_{j}\left[\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right)-\frac{\partial L}{\partial q_{j}}\right] \delta q_{j} d t=0
$$

For holonomic system the generalized co-ordinates $\delta q_{j}$ are independent of each other. Therefore the coefficients of each $\delta q_{j}$ must vanish. And we get

$$
\left[\frac{\mathrm{d}}{\mathrm{dt}}\left(\frac{\partial \mathrm{~L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}}\right)-\frac{\partial \mathrm{L}}{\partial \mathrm{q}_{\mathrm{j}}}\right]=0 \quad \mathrm{~J}=1,2, \ldots . . . \mathrm{n} .
$$

This set of equations is called Lagrange's equations of motion and each is a second order differential equation in terms of the time as independent variable.

### 1.3 PRINCIPLE OF LEAST ACTION:

The time integral of twice the K.E is called the action. The principle of least action states that

$$
\Delta \int_{t_{1}}^{t_{2}} 2 T d t=0
$$

But in systems for which H remains constant

$$
\begin{gathered}
2 T=\sum_{j} p_{j} \dot{q}_{j} \\
\therefore \Delta \int_{t_{1}}^{2} \sum_{j} p_{j} \dot{q}_{j} d t=0
\end{gathered}
$$

$\Delta$ represents variation of the path which allows time
 as well the position coordinates to vary.

In $\Delta$ variation

1. time as well as the position coordinates are allowed to vary.
2. time $t$ varies even at the end points.
3. the position coordinates are held fixed at the end points. ie $\Delta q_{j}=0$

Let APB be the actual path and AP'B be the varied path. The end points A and B after time $\Delta t$ take the positions $\mathrm{A}^{\prime}$ and $\mathrm{B}^{\prime}$ such that A and B are fixed while time is not fixed. A point P on the actual path gives $\mathrm{P}^{\prime}$ on the varied path.

$$
\mathrm{q}_{\mathrm{j}} \rightarrow \mathrm{q}_{\mathrm{j}}^{\prime}=\mathrm{q}_{\mathrm{j}}+\Delta \mathrm{q}_{\mathrm{j}}
$$

If $\alpha$ is the variational parameter, then in $\delta$ process $t$ is independent of $\alpha$. But in $\Delta$ process $t$ is a function of $\alpha$ even at the end points. ie $t=t(\alpha)$.
$q_{j}$ depends on $t$ and $\alpha$

$$
\Delta \mathrm{q}_{\mathrm{j}}=\frac{d q_{j}}{d \alpha} d \alpha
$$

$$
\begin{aligned}
& =\left[\frac{\partial q_{j}}{\partial \alpha}+\frac{\partial q_{j}}{\partial t} \frac{\partial t}{\partial \alpha}\right] d \alpha \\
& =\frac{\partial q_{j}}{\partial \alpha} d \alpha+\dot{q}_{j} \frac{\partial t}{\partial \alpha} d \alpha \\
& =\delta q_{j}+\dot{q}_{j} \Delta t
\end{aligned}
$$

Since $\delta q_{j}=\frac{\partial q_{j}}{\partial \alpha} d \alpha \quad$ and $\quad \dot{q}_{j} \frac{\partial t}{\partial \alpha} d \alpha=\dot{q}_{j} \Delta t$
Any function $f=f\left(q_{j}, \dot{q}_{j}, t\right)$

$$
\begin{align*}
\Delta \mathrm{f} & =\sum_{j}\left[\frac{\partial f}{\partial q_{j}} \Delta q_{j}+\frac{\partial f}{\partial \dot{q}_{j}} \Delta \dot{q}_{j}+\frac{\partial f}{\partial t} \Delta t\right] \\
& =\sum_{j} \frac{\partial f}{\partial q_{j}}\left(\delta q_{j}+\dot{q}_{j} \Delta t\right)+\sum \frac{\partial f}{\partial \dot{q}_{j}}\left(\delta \dot{q}_{j}+\ddot{q}_{j} \Delta t\right)+\frac{\partial f}{\partial t} \Delta t \\
& =\delta f+\frac{\partial f}{\partial t} \Delta t \\
\Delta & =\delta+\Delta t \frac{\partial}{\partial t} \tag{1}
\end{align*}
$$

Here $\Delta$ operation and time differentiation cannot be interchanged.

## Proof:

$$
\begin{align*}
\mathrm{A} & =\int_{t_{1}}^{t_{2}} \sum_{j} p_{j} \dot{q}_{j} d t \\
& =\int_{t_{1}}^{t_{2}}(L+H) d t \\
& =\int_{t_{1}}^{t_{2}} L d t+H\left(t_{2}-t_{1}\right) \quad \text { [since H is conserved ] }  \tag{2}\\
\Delta \mathrm{A} & =\Delta \int_{t_{1}}^{t_{2}} L d t+H \Delta\left(t_{2}-t_{1}\right) \\
& =\Delta \int_{t_{1}}^{t_{2}} L d t+\left.H \Delta t\right|_{t_{1}} ^{t_{2}} \tag{3}
\end{align*}
$$

To Solve $\Delta \int_{t_{1}}^{t_{2}} L d t$ :

$$
\text { Let } \int_{t_{1}}^{t_{2}} L d t=\mathrm{I} \quad \text { so that } \dot{\mathrm{I}}=\mathrm{L}
$$

$$
\text { Now } \Delta \mathrm{I}=\delta \mathrm{I}+\dot{I} \Delta t
$$

ie

$$
\begin{equation*}
\Delta \int_{t_{1}}^{t_{2}} L d t=\delta \int_{t_{1}}^{t_{2}} L d t+\left.L \Delta t\right|_{t_{1}} ^{t_{2}} \tag{4}
\end{equation*}
$$

Substituting equation (4) in equation (3) we get

$$
\begin{equation*}
\Delta A=\delta \int_{t_{1}}^{t_{2}} L d t+\left.L \Delta t\right|_{t_{1}} ^{t_{2}}+\left.H \Delta t\right|_{t_{1}} ^{t_{2}} \tag{5}
\end{equation*}
$$

$\delta \int_{t_{1}}^{t_{2}}$ Ldt cannot be zero.

$$
\begin{array}{rl}
\delta \int_{t_{1}}^{t_{2}} L & d t
\end{array}=\int_{t_{1}}^{t_{2}} \sum_{j}\left(\frac{\partial L}{\partial q_{j}} \delta q_{j}+\frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}\right) d t \quad \begin{aligned}
& t_{t_{1}} \\
&=\int_{j}\left[\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right) \delta q_{j}+\frac{\partial L}{\partial \dot{q}_{j}} \frac{d}{d t}\left(\delta q_{j}\right)\right] d t
\end{aligned}
$$

[Since from Lagrange's equation of motion $\frac{\partial L}{\partial q_{j}}=\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right)$ ]

$$
\delta \int_{t_{1}}^{t_{2}} L d t=\int_{t_{1}}^{t_{2}} \sum_{j}\left[\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}} \delta q_{j}\right)\right] d t
$$

Putting $\delta q_{j}=\Delta q_{j}-\dot{q}_{j} \Delta t$

$$
\begin{aligned}
\delta \int_{\mathrm{t}_{1}}^{\mathrm{t}_{2}} \mathrm{~L} d \mathrm{t} & =\int_{\mathrm{t}_{1}}^{\mathrm{t}_{2}} \sum_{\mathrm{j}}\left[\frac{\mathrm{~d}}{\mathrm{dt}}\left(\frac{\partial \mathrm{~L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}} \Delta \mathrm{q}_{\mathrm{j}}-\frac{\partial \mathrm{L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}} \dot{\mathrm{q}}_{\mathrm{j}} \Delta \mathrm{t}\right)\right] \mathrm{dt} \\
& =\sum_{j}\left(\frac{\partial L}{\partial \dot{q}_{j}} \Delta q_{j}-\frac{\partial L}{\partial \dot{q}_{j}} \dot{q}_{j} \Delta t\right)_{t_{1}}^{t_{2}}
\end{aligned}
$$

At end points $\Delta q_{j}=0$. Therefore

$$
\begin{aligned}
\delta \int_{t_{1}}^{t_{2}} L d t & =-\left.\sum_{j} \frac{\partial L}{\partial \dot{q}_{j}} \dot{q}_{j} \Delta t\right|_{t_{1}} ^{t_{2}} \\
& =-\left.\sum_{j} p_{j} \dot{q}_{j} \Delta t\right|_{t_{1}} ^{t_{2}}
\end{aligned}
$$

Now equation (5) becomes

$$
\begin{aligned}
\Delta A & =-\left.\sum_{j} p_{j} \dot{q}_{j} \Delta t\right|_{t_{1}} ^{t_{2}}+\left.L \Delta t\right|_{t_{1}} ^{t_{2}}+\left.H \Delta t\right|_{t_{1}} ^{t_{2}} \\
& =\left.\left(H+L-\sum_{j} p_{j,} \dot{q}_{j}\right) \Delta t\right|_{t_{1}} ^{t_{2}}
\end{aligned}
$$

$$
=0
$$

Since

$$
\mathrm{H}=\sum_{j} p_{j}, \dot{q}_{j}-L
$$

Thus

$$
\Delta A=\Delta \int_{t_{1}}^{t_{2}} \sum p_{j,} \dot{q}_{j} d t=0
$$

Which proves the principle of least action.
Here $\int_{t_{1}}^{t_{2}} \sum p, \dot{q}_{j}=$ Hamiltion's characteristic function
(i) Principle of least action in terms of arc length of the particle trajectory.

Let a system contain only one particle of mass $m$
Kinetic energy $T=\frac{1}{2} m\left(\frac{d s}{d t}\right)^{2}$
$\mathrm{ds} \rightarrow$ element of arc traversed in time dt

$$
\mathrm{dt}=\left(\frac{m}{2 T}\right)^{\frac{1}{2}} d s
$$

The principle of least action

$$
\begin{array}{ll}
\Delta \int_{t_{1}}^{t_{2}} 2 T d t=\Delta \int_{t_{1}}^{t_{2}} 2 T\left(\frac{m}{2 T}\right)^{\frac{1}{2}} d s=0 & \\
\operatorname{ie} \Delta \int_{t_{1}}^{t_{2}}(2 m T)^{\frac{1}{2}} d s=0 & \text { Since } \mathrm{T}+\mathrm{V}=\mathrm{E} \\
\Delta \int_{t_{1}}^{t_{2}}[2 m(E-V)]^{\frac{1}{2}} d s=0 & \text { Since } \mathrm{E}=\mathrm{H} \\
\Delta \int_{t_{1}}^{t_{2}}[2 m(H-V)]^{\frac{1}{2}} d s=0 & \text { Since } \mathrm{m}=\mathrm{Constant}
\end{array}
$$

The above equation represents the principle of least action in term of arc length of the particle trajectory.

## (ii) Jacobi's form of the principle of least action:

The K.E of the system

$$
\begin{aligned}
T & =\frac{1}{2} \sum_{j, k} a_{j k} \dot{q}_{j} \dot{q}_{k} \\
2 T & =\sum_{j, k} a_{j k} \dot{q}_{j} \dot{q}_{k}
\end{aligned}
$$

$$
\begin{align*}
& =\sum_{j, k} a_{j k} \frac{d q_{j} d q_{k}}{d t^{2}} \\
& =\left(\frac{d \rho}{d t}\right)^{2} \tag{7}
\end{align*}
$$

Where $(d \rho)^{2}=\sum_{j, k} a_{j k} d_{q j} d q_{k}, a$ differential
From equation (7) $\mathrm{T}=\frac{1}{2}\left(\frac{\mathrm{dp}}{\mathrm{dt}}\right)^{2}$

$$
\mathrm{dt}=\frac{d \rho}{(2 T)^{\frac{1}{2}}}
$$

The principle of least action

$$
\begin{gather*}
\Delta \int_{t_{1}}^{t_{2}} 2 T d t=0 \\
\Delta \int_{t_{1}}^{t_{2}} 2 T \frac{d \rho}{(2 T)^{\frac{1}{2}}}=0 \\
\Delta \int_{t_{1}}^{t_{2}}(2 T)^{\frac{1}{2}} d \rho=0 \\
\Delta \int_{t_{1}}^{t_{2}}[2(E-V)]^{\frac{1}{2}} d \rho=0 \\
\Delta \int_{t_{1}}^{t_{2}}[2(H-V)]^{\frac{1}{2}} d \rho=0 \\
\Delta \int_{t_{1}}^{t_{2}}(H-V)^{\frac{1}{2}} d \rho=0 \tag{8}
\end{gather*}
$$

This equation gives the Jacobi's form of principle of least action.

## (iii) Fermat's principle:

It states that the time taken by a light ray to travel between two points is extremum. According to principle of least action

$$
\begin{aligned}
& \Delta \int_{t_{1}}^{t_{2}} 2 \mathrm{~T} \mathrm{dt}=0 \\
& \Delta \int_{t_{1}}^{t_{2}} T d t=0
\end{aligned}
$$

If T is conserved, then

$$
\begin{aligned}
\Delta \int_{\mathrm{t}_{1}}^{\mathrm{t}_{2}} \mathrm{dt} & =0 \\
\Delta\left(\mathrm{t}_{2}-\mathrm{t}_{1}\right) & =0 \\
\left(\mathrm{t}_{2}-\mathrm{t}_{1}\right) & =\text { extremum. }
\end{aligned}
$$

ie, the time taken by the light ray to travel between two points is extremum.

### 1.4 CANONICAL TRANSFORMATION:

Transformation is one to change one set of position and momentum coordinates into another set of position and momentum coordinates.

We assume $\mathrm{p}_{\mathrm{j}}$ and $\mathrm{q}_{\mathrm{j}}$ are the old momentum and position coordinates and $\mathrm{P}_{\mathrm{j}}$ and $\mathrm{Q}_{\mathrm{j}}$ are new one related by

$$
\begin{align*}
& P_{j}=P_{j}\left(p_{j}, q_{j}, t\right) \\
& Q_{j}=Q_{j}\left(p_{j}, q_{j}, t\right) \tag{1}
\end{align*}
$$

Then if there exists a new Hamiltonian $\overline{\mathrm{H}}$ in the new coordinates such that

$$
\begin{equation*}
\dot{P}_{j}=\frac{\partial \bar{H}}{\partial Q_{j}} \text { and } \dot{Q}_{j}=\frac{\partial \bar{H}}{\partial P_{j}} \tag{2}
\end{equation*}
$$

These equations are known as canonical (or) contact transformations.
$\mathrm{Q}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}$ are canonical coordinates.
By definition we have $\mathrm{H}=\sum \mathrm{p}_{\mathrm{j}} \mathrm{q}_{\mathrm{j}}-\mathrm{L}$
and $\quad \bar{H}=\sum p_{j} \dot{Q}_{j}-K$
Here the position and momenta coordinates are independent.
Canonical transformations are the transformations of phase space. They are characterized by the property that they leave the form of Hamilton's equations of motion. example : Cartesian to polar coordinate is an example of co-ordinate transformation.

The transformation of one set of position coordinates to new set of coordinates is called point transformation. They are the transformations of configuration space.

### 1.5 HAMILTONIAN FORMALISM:

Lagrangian equations of motion are invariant in form with respect to the set of any generalized coordinates. In the new set $\mathrm{Q}_{\mathrm{j}}$, Lagrange's equations will be

$$
\frac{\mathrm{d}}{\mathrm{dt}}\left(\frac{\partial \mathrm{~L}}{\partial \dot{\mathrm{Q}}_{\mathrm{j}}}\right)-\frac{\partial \mathrm{L}}{\partial \mathrm{Q}_{\mathrm{j}}}=0
$$

ie, Lagrange's equations are covariant with respect to point transformations. If we define $\mathrm{P}_{\mathrm{j}}$ as

$$
P_{j}=\frac{\partial L}{\partial \dot{Q}_{j}}\left(Q_{j}, \dot{Q}_{j}\right)
$$

The Hamilton's canonical equation will also be covariant. ie,

$$
\begin{aligned}
\dot{Q}_{j} & =\frac{\partial H}{\partial P_{j}}\left(Q_{j}, P_{j}\right) \\
\dot{P}_{j} & =-\frac{\partial H}{\partial Q_{j}}\left(Q_{j}, P_{j}\right)
\end{aligned}
$$

Therefore, this transformation is extended to Hamiltonian formulation. In Hamiltonian formulation, we admit the existence of one more independent variable called momentum. Consequently the simultaneous transformation of the independent coordinates and momenta $q_{j}, p_{j}$ to a new set $\mathrm{Q}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}$ can be represented in the form

$$
\begin{align*}
Q_{j} & =Q_{j}(q, p, t)  \tag{1}\\
P_{j} & =P_{j}(q, p, t)
\end{align*}
$$

For $\mathrm{Q}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}$ to be canonical, they should be able to be expressed in Hamiltonian form of equations of motion.
ie

$$
\dot{Q}_{j}=\frac{\partial K}{\partial P_{j}} \quad \dot{P}_{j}=-\frac{\partial K}{\partial Q_{j}}
$$

Where K is a function of $(\mathrm{Q}, \mathrm{P}, \mathrm{t})$ and is a substitute for H of old set in new set of coordinates. If $\mathrm{Q}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}$ are to be canonical coordinates, they must satisfy the modified Hamilton's principle of the form

$$
\begin{equation*}
\delta \int_{t_{1}}^{t}\left[\sum P_{j} \dot{Q}_{j}-k(Q, P, t)\right] d t=0 \tag{2}
\end{equation*}
$$

The old coordinates $\mathrm{p}_{\mathrm{j}}, \mathrm{q}_{\mathrm{j}}$ are already canonical.

## Therefore

$$
\begin{equation*}
\delta \int_{\mathrm{t}_{1}}^{\mathrm{t}_{2}}\left[\sum \mathrm{p}_{\mathrm{j}} \dot{\mathrm{q}}_{\mathrm{j}}-\mathrm{H}(\mathrm{q}, \mathrm{p}, \mathrm{t})\right] \mathrm{dt}=0 \tag{3}
\end{equation*}
$$

The simultaneous validity of equations (2) and (3) does not mean that the integrands of the two integrals are equal. We can therefore write

$$
\begin{equation*}
\delta \int_{t_{1}}^{t_{2}}\left[\left(\sum p_{j} \dot{q}_{j}-H\right)-\left(\sum P_{j} \dot{Q}_{j}-K\right)\right] d t=0 \tag{4}
\end{equation*}
$$

Equation (4) will not be affected if we add to or subtract from it a total time derivative of a function $\mathrm{F}=\mathrm{F}(\mathrm{q}, \mathrm{p}, \mathrm{t})$.Now we can write equation (4) as

$$
\delta \int_{t_{1}}^{t_{2}}\left\{\left(\sum p_{j} \dot{q}_{j}-k\right)-\left(\sum P_{j} \dot{Q}_{j}-K\right)-\frac{d F}{d t}\right\} d t=0
$$

is follows that

$$
\begin{equation*}
\left(\sum p_{j} \dot{q}_{j}-H\right)-\left(\sum P_{j} \dot{Q}_{j}-K\right)=\frac{d F}{d t} \tag{5}
\end{equation*}
$$

### 1.6 CANONICAL FORMALISM

## DERIVATION OF GENERATING FUNCTIONS:

The first term in equation (5) is regarded as a function of $q_{j}, p_{j}$ and $t$ and the second term as a function of $Q_{j}, P_{j}$ and $t$. $F$ is in general as a function of $(4 n+1)$ variables $q_{j}$, $p_{j}, Q_{j}, P_{j}$ and $t$. The two sets of variables are connected by the 2 n transformation equations and besides $t$, only 2 n are independent. Now F is a function of both old and new set of coordinates and four forms of $F$ are possible. $F_{1}(q, Q, t), F_{2}(q, P, t) F_{3}(p, Q, t)$ and $F_{4}(p, P, t)$ and F is termed as the generating function.

## (A) FIRST FORM $\mathbf{F}_{1}$ ( $\mathbf{( q , ~ Q , t )}$

We can write equation (5) as

$$
\begin{align*}
\sum p_{j} \dot{q}_{j}-H & =\sum P_{j} \dot{Q}_{j}-K+\frac{d F_{1}}{d t}(q, Q, t)  \tag{6}\\
\mathrm{F}_{1} & =\mathrm{F}_{1}(\mathrm{q}, \mathrm{Q}, \mathrm{t}) \\
\frac{d F_{1}}{d t} & =\sum_{j} \frac{\partial F_{1}}{\partial q_{j}} \dot{q}_{j}+\sum_{j} \frac{\partial F_{1}}{\partial Q_{j}} \dot{Q}_{j}+\frac{\partial F_{1}}{\partial t}
\end{align*}
$$

Now equation (6) becomes

$$
\begin{align*}
& \sum p_{j} \dot{q}_{j}-H=\sum P_{j} \dot{Q}_{j}-K+\sum \frac{\partial F_{1}}{\partial q_{j}} \dot{q}_{j}+\sum \frac{\partial F_{1}}{\partial Q_{j}} \dot{Q}_{j}+\frac{\partial F_{1}}{\partial t} \\
& \sum\left(\frac{\partial F_{1}}{\partial q_{j}}-p_{j}\right) \dot{q}_{j}+\sum\left(P_{j}+\frac{\partial F_{1}}{\partial Q_{j}}\right) \dot{Q}_{j}-K+H+\frac{\partial F_{1}}{\partial t}=0 \tag{7}
\end{align*}
$$

Since $\mathrm{q}_{\mathrm{j}}$ and $\mathrm{Q}_{\mathrm{j}}$ are to be treated as independent variables, equation (7) can hold only if $\dot{\mathrm{q}}_{\mathrm{j}}$ and $\dot{\mathrm{Q}}_{\mathrm{j}}$ separately vanish.
ie

$$
\begin{align*}
p_{j} & =\frac{\partial F_{1}}{\partial q_{j}}(q, Q, t)  \tag{8}\\
P_{j} & =-\frac{\partial F_{1}}{\partial Q_{j}}(q, Q, t)  \tag{9}\\
\text { and } \quad \mathrm{K} & =\mathrm{H}+\frac{\partial \mathrm{F}_{1}}{\partial \mathrm{t}}(\mathrm{q}, \mathrm{Q}, \mathrm{t}) \tag{10}
\end{align*}
$$

Solving equation (8), we get

$$
\mathrm{Q}_{\mathrm{j}}=\mathrm{Q}_{\mathrm{j}}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{p}_{\mathrm{j}}, \mathrm{t}\right)
$$

Which when substituted in (9) gives $P_{j}=P_{j}\left(q_{j}, p_{j}, t\right)$

## (B) SECOND FORM F 2 ( $\mathbf{( q , P , t )}$

$\mathrm{F}_{2}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}, \mathrm{t}\right)=\mathrm{F}_{1}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{Q}_{\mathrm{j}}, \mathrm{t}\right)+\sum \mathrm{P}_{\mathrm{j}} \mathrm{Q}_{\mathrm{j}}$
$F_{1}\left(q_{j}, Q_{j}, t\right)=F_{2}\left(q_{j}, P_{j}, t\right)-\sum P_{j} Q_{j}$
putting equation (13) in equation (6), we get

$$
\begin{align*}
& \sum p_{j} \dot{q}_{j}-H=\sum P_{j} \dot{Q}_{j}-K+\frac{d}{d t}\left[F_{2}\left(q_{j}, P_{j}, t\right)-\sum P_{j} Q_{j}\right] \\
&=\sum P_{j} \dot{Q}_{j}-K+\sum \frac{\partial F_{2}}{\partial q_{j}} \dot{q}_{j}+\sum \frac{\partial F_{2}}{\partial P_{j}} \dot{P}_{j}+\frac{\partial F_{2}}{\partial t}-\sum \dot{P}_{j} Q_{j}-\sum P_{j} \dot{Q}_{j} \\
&=-\sum \dot{P}_{j} Q_{j}-K+\frac{\partial F_{2}}{\partial t}+\sum \frac{\partial F_{2}}{\partial q_{j}} \dot{q}_{j}+\sum \frac{\partial F_{2}}{\partial P_{j}} \dot{P}_{j} \\
& \sum\left(\frac{\partial F_{2}}{\partial q_{j}}-p_{j}\right) \dot{q}_{j}+\sum\left(\frac{\partial F_{2}}{\partial P_{j}}-Q_{j}\right) \dot{P}_{j}+H+\frac{\partial F_{2}}{\partial t}-K=0 \tag{12}
\end{align*}
$$

Since $q_{j}$ and $P_{j}$ are independent variable, equation (12) can be satisfied only when

$$
\begin{align*}
p_{j} & =\frac{\partial F_{2}}{\partial q_{j}}\left(q_{j}, P_{j}, t\right)  \tag{13}\\
Q_{j} & =\frac{\partial F_{2}}{\partial P_{j}}\left(q_{j}, P_{j}, t\right)  \tag{14}\\
\text { and } K & =H+\frac{\partial F_{2}}{\partial t}\left(q_{j}, P_{j}, t\right) \tag{15}
\end{align*}
$$

Equation (13) can be solved to give $\mathrm{P}_{\mathrm{j}}=\mathrm{P}_{\mathrm{j}}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{p}_{\mathrm{j}}, \mathrm{t}\right)$
which when substituted in (14) gives $\mathrm{Q}_{\mathrm{j}}=\mathrm{Q}_{\mathrm{j}}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{p}_{\mathrm{j}}, \mathrm{t}\right)$

## (C) THIRD FORM $\mathrm{F}_{3}(\mathbf{p}, \mathbf{Q}, \mathrm{t})$

$F_{3}$ can be obtained from $F_{1}$ by replacing $q_{j}$ by $p_{j}$

$$
\begin{array}{ll}
F_{3}\left(p_{j}, Q_{j}, t\right) & =F_{1}\left(q_{j}, Q_{j}, t\right)-\sum p_{j} q_{j} \\
F_{1}\left(q_{j}, Q_{j}, t\right) & =F_{3}\left(p_{j}, Q_{j}, t\right)+\sum p_{j} q_{j} \tag{16}
\end{array}
$$

putting equation (16) in equation (6), we get

$$
\begin{aligned}
\sum p_{j} \dot{q}_{j}-H & =\sum P_{j} \dot{Q}_{j}-K+\frac{d}{d t}\left[F_{3}\left(p_{j}, Q_{j}, t\right)+\sum p_{j} q_{j}\right] \\
& =\sum P_{j} \dot{Q}_{j}-K+\sum \frac{\partial F_{3}}{\partial p_{j}} \dot{p}_{j}+\sum \frac{\partial F_{3}}{\partial Q_{j}} \dot{Q}_{j}+\frac{\partial F_{3}}{\partial t}+\sum \dot{p}_{j} q_{j}+\sum p_{j} \dot{q}_{j} \\
-H & =\sum p_{j} \dot{Q}_{j}-K+\frac{\partial F_{3}}{\partial t}+\sum\left(\frac{\partial F_{3}}{\partial p_{j}}+q_{j}\right) \dot{p}_{j}+\sum\left(\frac{\partial F_{3}}{\partial Q_{j}}+P_{j}\right) \dot{Q}_{j}
\end{aligned}
$$

$$
\begin{equation*}
\Sigma\left(\frac{\partial F_{3}}{\partial p_{j}}+q_{j}\right) \dot{p}_{j}+\Sigma\left(\frac{\partial F_{3}}{\partial Q_{j}}+P_{j}\right) \dot{Q}_{j}+H+\frac{\partial F_{3}}{\partial t}-K=0 \tag{17}
\end{equation*}
$$

Since $p_{j}, Q_{j}$ are independent variables, equation (17) can be satisfied only when

$$
\begin{align*}
& q_{j}=-\frac{\partial F_{3}}{\partial p_{j}}\left(p_{j}, Q_{j}, t\right)  \tag{18}\\
& P_{j}=-\frac{\partial F_{3}}{\partial Q_{j}}\left(p_{j}, Q_{j}, t\right)  \tag{19}\\
& k=H+\frac{\partial F_{3}}{\partial t}\left(p_{j}, Q_{j}, t\right) \tag{20}
\end{align*}
$$

equation (18) gives $\quad \mathrm{Q}_{\mathrm{j}}=\mathrm{Q}_{\mathrm{j}}(\mathrm{q}, \mathrm{p}, \mathrm{t})$
and equation (19) gives $\mathrm{P}_{\mathrm{j}}=\mathrm{P}_{\mathrm{j}}(\mathrm{q}, \mathrm{p}, \mathrm{t})$

## (D) FOURTH FORM $\mathrm{F}_{4}(\mathbf{p}, \mathbf{P}, \mathrm{t})$

$F_{4}$ can be obtained from $F_{3}$ by replacing $Q_{j}$, by $P_{j}$

$$
\begin{align*}
\mathrm{F}_{4}\left(\mathrm{p}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}, \mathrm{t}\right) & =\mathrm{F}_{3}\left(\mathrm{p}_{\mathrm{j}}, \mathrm{Q}_{\mathrm{j}}, \mathrm{t}\right)+\sum \mathrm{P}_{\mathrm{j}} \mathrm{Q}_{\mathrm{j}} \\
& =\mathrm{F}_{1}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{Q}_{\mathrm{j}}, \mathrm{t}\right)-\sum \mathrm{p}_{\mathrm{j}} \mathrm{q}_{\mathrm{j}}+\sum \mathrm{P}_{\mathrm{j}} \mathrm{Q}_{\mathrm{j}} \\
\mathrm{~F}_{1}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{Q}_{\mathrm{j}, \mathrm{t})}\right. & =\mathrm{F}_{4}\left(\mathrm{p}_{\mathrm{j}}, \mathrm{P}_{\mathrm{j}}, \mathrm{t}\right)+\sum \mathrm{p}_{\mathrm{j}} \mathrm{q}_{\mathrm{j}}-\sum \mathrm{P}_{\mathrm{j}} \mathrm{Q}_{\mathrm{j}} \tag{21}
\end{align*}
$$

putting equation (23) in equation (6) we get

$$
\begin{align*}
& \sum p_{j} \dot{q}_{j}-H=\sum P_{j} \dot{Q}_{j}-K+\frac{d}{d t}\left[F_{4}\left(p_{j}, P_{j}, t\right)+\sum p_{j} q_{j}-\sum P_{j} Q_{j}\right] \\
& \quad=\sum P_{j} \dot{Q}_{j}-K+\sum \frac{\partial F_{4}}{\partial p_{j}} \dot{p}_{j}+\sum \frac{\partial F_{4}}{\partial P_{j}} \dot{P}_{j}+\frac{\partial F_{4}}{\partial t}+\sum \dot{p}_{j} q_{j}+\sum p_{j} \dot{q}_{j}-\sum \dot{P}_{j} Q_{j}-\sum P_{j} \dot{Q}_{j} \\
& -H=-K+\sum\left(\frac{\partial F_{4}}{\partial p_{j}}+q_{j}\right) \dot{p}_{j}+\sum\left(\frac{\partial F_{4}}{\partial P_{j}}-Q_{j}\right) \dot{P}_{j}+\frac{\partial F_{4}}{\partial t} \tag{22}
\end{align*}
$$

Since $p_{j}$ and $P_{j}$ are independent variables, equation (22) can be satisfied only when

$$
\begin{align*}
q_{j} & =-\frac{\partial F_{4}}{\partial p_{j}}\left(p_{j}, P_{j}, t\right) \\
Q_{j} & \left.=\frac{\partial F_{4}}{\partial P_{j}}\left(p_{j}, P_{j}, t\right)\right)  \tag{24}\\
K & =H+\frac{\partial F_{4}}{\partial t}\left(p_{j}, P_{j}, t\right) \tag{25}
\end{align*}
$$

Equation (23) gives $\mathrm{Q}_{\mathrm{j}}=\mathrm{Q}_{\mathrm{j}}(\mathrm{q}, \mathrm{p}, \mathrm{t})$
and equation (24) gives $\mathrm{P}_{\mathrm{j}}=\mathrm{P}_{\mathrm{j}}(\mathrm{q}, \mathrm{p}, \mathrm{t})$

## (i) Condition for a transformation to be canonical:

If the expression $\quad \Sigma\left(\mathrm{P}_{\mathrm{j}} \mathrm{dQ}_{\mathrm{j}}-\mathrm{p}_{\mathrm{j}} \mathrm{dq}_{\mathrm{j}}\right)$
(or) $\quad \Sigma\left(\mathrm{p}_{\mathrm{j}} \mathrm{dq}_{\mathrm{j}}-\mathrm{P}_{\mathrm{j}} \mathrm{dQ}_{\mathrm{j}}\right)$
be an exact differential then the transformation from $\left(q_{j}, p_{j}\right)$ set to $\left(Q_{j}, P_{j}\right)$ set is canonical.

Proof:
We know that for a transformation to be canonical, equation

$$
\begin{equation*}
\sum\left(p_{j} \dot{q}_{j}-H\right)-\left(\sum P_{j} \dot{Q}_{j}-K\right)=\frac{d F}{d t} \tag{1}
\end{equation*}
$$

must be satisfied.
Suppose generating function F does not include time explicitly then

$$
K=H+\frac{\partial F}{\partial t}=H
$$

Now equation (1) becomes

$$
\sum p_{j} \dot{q}_{j}-\sum P_{j} \dot{Q}_{j}=\frac{\partial F}{d t}
$$

(or)

$$
\Sigma\left(p_{j} d q_{j}-P_{j} d Q_{j}\right)=d F
$$

Where dF is the exact differential of F .

## Exercises:

1. Show that the transformation

$$
\begin{aligned}
& Q=\sqrt{2 q} e^{\alpha} \cos p \\
& P=\sqrt{2 q} e^{-\alpha} \sin p
\end{aligned}
$$

is a canonical transformation.

## Solution:

$$
\begin{aligned}
Q & =\sqrt{2 q} e^{\alpha} \cos p \\
d Q & =(2 q)^{-1 / 2} e^{\alpha} \cos p d q-(2 q)^{1 / 2} e^{\alpha} \sin p d p \\
P d Q-p d q & =(2 q)^{1 / 2} e^{-\alpha} \sin p(2 q)^{-1 / 2} e^{\alpha} \cos p d q-(2 q)^{1 / 2} e^{-\alpha} \sin p(2 q)^{1 / 2} e^{\alpha} \sin p d p-p d q \\
P d Q-p d q & =\sin p \cos p d q-2 q \sin ^{2} p d p-p d q
\end{aligned}
$$

$$
\begin{aligned}
P d Q-p d q & =(\sin p \cos p-p) d q-2 q \sin ^{2} p d p \\
& =\left(\frac{1}{2} \sin 2 p-p\right) d q-2 q \sin ^{2} p d p \\
& =\frac{\partial}{\partial q}\left(\frac{1}{2} q \sin 2 p-p q\right) d q+\frac{\partial}{\partial p}\left(\frac{1}{2} q \sin 2 p-p q\right) d p \\
& =\frac{\partial F}{\partial q} d q+\frac{\partial F}{\partial p} d p \\
& =\mathrm{dF}
\end{aligned}
$$

Which shows that the RHS is an exact differential of the function

$$
F=\frac{1}{2} q \sin 2 p-p q
$$

and hence the transformation is canonical.
2. Show that the transformation

$$
\begin{array}{rlrl}
q & =\sqrt{2 p} \sin Q & p & =\sqrt{2 p} \cos Q \\
\text { (or) } \quad P & =\frac{1}{2}\left(p^{2}+q^{2}\right) & Q & =\tan ^{-1} \frac{q}{p}
\end{array} \quad \text { is canconical }
$$

## Solution:

$$
\begin{aligned}
d q & =(2 p)^{1 / 2} \cos Q d Q+(2 p)^{-1 / 2} \sin Q d P \\
p d q & =(2 p)^{1 / 2} \cos Q(2 p)^{1 / 2} \cos Q d Q+(2 p)^{1 / 2} \cos Q(2 p)^{-1 / 2} \sin Q d P \\
\mathrm{pdq} & =2 \mathrm{P} \cos ^{2} \mathrm{Q} \mathrm{dQ}+\sin \mathrm{Q} \cos \mathrm{Q} \mathrm{dP} \\
\mathrm{pdq}-\mathrm{PdQ} & =2 \mathrm{P} \cos ^{2} \mathrm{Q} \mathrm{dQ}+\sin \mathrm{Q} \cos \mathrm{Q} \mathrm{dP}-\mathrm{PdQ} \\
& =\left(2 \mathrm{P} \cos ^{2} \mathrm{Q}-\mathrm{P}\right) \mathrm{dQ}+\frac{1}{2} \sin 2 \mathrm{Q} \mathrm{dP} \\
= & \frac{\partial}{\partial Q}\left(\frac{1}{2} P \sin 2 Q\right) d Q+\frac{\partial}{\partial P}\left(\frac{1}{2} P \sin 2 Q\right) d P \\
= & \frac{\partial F}{\partial Q} d Q+\frac{\partial F}{\partial P} d P \\
& =\mathrm{dF} \text { where } F=\frac{1}{2} P \sin 2 Q
\end{aligned}
$$

3. Show that the transformation

$$
\begin{aligned}
\mathrm{P} & =\mathrm{q} \cot \mathrm{p} \\
\mathrm{Q} & =\log \left(\frac{\sin p}{q}\right) \text { is canonical. show that the generating function is } \\
F= & e^{-Q}\left(1-q^{2} e^{2 Q}\right)^{1 / 2}+q \sin ^{-1}\left(q e^{Q}\right)
\end{aligned}
$$

## Solution:

$$
\begin{aligned}
d Q & =\frac{\partial Q}{\partial q} \partial q+\frac{\partial Q}{\partial p} d p \\
& =\frac{\partial}{\partial q}\left[\log \left(\frac{\sin p}{q}\right)\right] d q+\frac{\partial}{\partial p}\left[\log \left(\frac{\sin p}{q}\right)\right] d p \\
& =\frac{1}{\left(\frac{\sin p}{q}\right)}\left(-\frac{\sin p}{q^{2}}\right) d q+\frac{1}{\left(\frac{\sin p}{q}\right)}\left(\frac{\cos p}{q}\right) d p \\
=- & \frac{d q}{q}+\cot p d p \\
p d q-P d Q & =p d q-q \cot p\left(-\frac{d q}{q}+\cot p d p\right) \\
& =(p+\cot p) d q-q \cot ^{2} p d p \\
& =\frac{\partial}{\partial q}[q p+q \cot p] d q+\frac{\partial}{\partial p}[q p+q \cot p] d p \\
& =\frac{\partial F}{\partial q} d q+\frac{\partial F}{\partial p} d p \\
& =d F=\operatorname{exact} \text { differential }
\end{aligned}
$$

$$
F=q p+q \cot p
$$

and hence the transformation is canonical.
Let us put $Q=\log \left(\frac{\sin p}{q}\right)$

$$
\begin{gathered}
\sin p=q e^{Q} \Rightarrow p=\sin ^{-1}\left(q e^{Q}\right) \\
\cos \mathrm{p}=\left(1-q^{2} e^{2 Q}\right)^{1 / 2} \\
\cot \mathrm{p}=\frac{\left(1-q^{2} e^{2 Q}\right)^{1 / 2}}{q e^{Q}}
\end{gathered}
$$

Now the generating function $\mathrm{F}=q \sin ^{-1}\left(q e^{Q}\right)+e^{-Q}\left(1-q^{2} e^{1}\right)^{1 / 2}$

### 1.7 HAMILTONIAN:

The quantity $\left(\sum p_{j} \dot{q}_{j}-L\right)$ is a constant of motion with the condition that L does not involve time explicitly. This constant was designated by H.

$$
\text { ie } H=\sum p_{j} \dot{q}_{j}-L\left(q_{j}, \dot{q}_{j}\right)
$$

H as Hamiltonian $\mathrm{H}=\mathrm{H}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{p}_{\mathrm{j}}\right)$

$$
=\sum p_{j} \dot{q}_{j}-L\left(q_{j}, \dot{q}_{j}\right)
$$

If H does not involve time, it is said to be a constant of motion.
(i) Hamilton's canonical equations of motion:

Hamiltonian is in general as a function of the position coordinates $q_{j}$, the momenta $p_{j}$ and the time t .

$$
\begin{align*}
\mathrm{H} & =\mathrm{H}\left(\mathrm{q}_{\mathrm{j}}, \mathrm{p}_{\mathrm{j}}, \mathrm{t}\right) \\
d H & =\sum \frac{\partial H}{\partial q_{j}} d q_{j}+\sum \frac{\partial H}{\partial p_{j}} d p_{j}+\frac{\partial H}{\partial t} d t  \tag{1}\\
\mathrm{H} & =\sum p_{j} \dot{q}_{j}-L \tag{2}
\end{align*}
$$

So that $\delta H=\sum \dot{q}_{j} d p_{j}+\sum p_{j} d \dot{q}_{j}-d L$
But Lagrangian $\mathrm{L}=\mathrm{L}\left(\mathrm{q}_{\mathrm{j}}, \dot{\mathrm{q}}_{\mathrm{j}}, \mathrm{t}\right)$

$$
\begin{equation*}
d L=\sum \frac{\partial L}{\partial q_{j}} d q_{j}+\sum \frac{\partial L}{\partial \dot{q}_{j}} d \dot{q}_{j}+\frac{\partial L}{\partial t} d t \tag{3}
\end{equation*}
$$

Substituting equation (3) in equation (2) we get

$$
\begin{align*}
d H & =\sum \dot{q}_{j} d p_{j}+\sum p_{j} d \dot{q}_{j}-\sum \frac{\partial L}{\partial q_{j}} d q_{j}-\sum \frac{\partial L}{\partial \dot{q}_{j}} d \dot{q}_{j}-\frac{\partial L}{\partial t} d t  \tag{4}\\
\frac{\partial L}{\partial \dot{q}_{j}} & =p_{j} \text { and } \frac{\partial L}{\partial q_{j}}=\dot{p}_{j}
\end{align*}
$$

Now equation (4) becomes

$$
\begin{align*}
& d H=\sum \dot{q}_{j} d p_{j}+\sum p_{j} d \dot{q}_{j}-\sum \dot{p}_{j} d q_{j}-\sum p_{j} d \dot{q}_{j}-\frac{\partial L}{\partial t} d t \\
& d H=\sum \dot{q}_{j} d p_{j}-\sum \dot{p}_{j} d q_{j}-\frac{\partial L}{\partial t} d t \tag{5}
\end{align*}
$$

Comparing coefficients in equation (5) and equation (1), we arrive

$$
\left.\begin{array}{rl}
\dot{\mathrm{q}}_{\mathrm{j}} & =\frac{\partial \mathrm{H}}{\partial \phi_{\mathrm{j}}}  \tag{6}\\
\dot{p}_{j} & =-\frac{\partial H}{\partial q_{j}} \\
-\frac{\partial \mathrm{L}}{\partial \mathrm{t}} & =\frac{\partial \mathrm{H}}{\partial \mathrm{t}}
\end{array}\right]-
$$

Equations (6) are known as Hamilton's canonical equations of motion and of a set of 2 n first order equations of motion.

## (ii) Physical Significance of $\mathbf{H}$

Hamiltonian H also possesses the dimensions of energy but in all circumstances $\mathrm{H} \neq \mathrm{E}$
$\mathrm{E}=\mathrm{H}$ equality has some restrictions. That are

1. The system be conservative one. ie. Potential energy is coordinate dependent and not velocity dependent.
2. Coordinate transformation equations be independent of time so that $\sum p_{j} \dot{q}_{j}=2 T$

Let us write $\mathrm{H}=\mathrm{H}\left(\mathrm{p}_{1}, \mathrm{p}_{2}, \ldots \ldots \mathrm{p}_{\mathrm{j}}, \mathrm{q}_{1}, \mathrm{q}_{2}, \ldots \ldots \ldots \mathrm{q}_{\mathrm{j}}, \mathrm{t}\right)$

$$
\frac{d H}{d t}=\sum \frac{\partial H}{\partial q_{j}} \dot{q}_{j}+\sum \frac{\partial H}{\partial p_{j}} \dot{p}_{j}+\frac{\partial H}{\partial t}
$$

From Hamilton's equations of motion

$$
\begin{align*}
& \frac{\partial H}{\partial q_{j}}=-\dot{p}_{j} \quad \frac{\partial H}{\partial p_{j}}=\dot{q}_{j} \\
& \text { Therefore } \begin{aligned}
\frac{d H}{d t} & =-\sum \dot{p}_{j} \dot{q}_{j}+\sum \dot{q}_{j} \dot{p}_{j}+\frac{\partial H}{\partial t} \\
& =\frac{\partial \mathrm{H}}{\partial \mathrm{t}} \\
& =-\frac{\partial \mathrm{L}}{\partial \mathrm{t}} \\
\therefore \frac{\partial H}{\partial t} & =-\frac{\partial L}{\partial t}
\end{aligned}
\end{align*}
$$

If L is not an explicit function of time, $\frac{\partial \mathrm{L}}{\partial \mathrm{t}}=0$

$$
\begin{gather*}
\therefore \frac{\partial H}{\partial t}=0 \quad \quad i e \frac{d H}{d t}=0 \\
\mathrm{H}=\text { constant } \tag{3}
\end{gather*}
$$

Thus if $L$ is not an explicit function of time, H is constant of motion.
For conservative systems, the Potential energy does not depend upon generalized velocity, ie

$$
\begin{equation*}
\frac{\partial V}{\partial \dot{q}_{j}}=0 \tag{4}
\end{equation*}
$$

We know $H=\sum p_{j} \dot{q}_{j}-L$

$$
=\Sigma \frac{\partial \mathrm{L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}} \dot{\mathrm{q}}_{\mathrm{j}}-\mathrm{L}
$$

$$
\begin{array}{rlr} 
& =\sum \dot{\mathrm{q}}_{\mathrm{j}}\left\{\frac{\partial}{\partial \dot{\mathbf{q}}_{\mathrm{j}}}(\mathrm{~T}-\mathrm{V})\right\}-\mathrm{L} & \text { Since } \mathrm{L}=\mathrm{T}-\mathrm{V} \\
& =\sum \dot{q}_{j}\left\{\frac{\partial T}{\partial \dot{q}_{j}}-\frac{\partial V}{\partial \dot{q}_{j}}\right\}-L & \text { since } \frac{\partial V}{\partial \dot{q}_{j}}=0 \\
& =\sum \dot{\mathrm{q}}_{\mathrm{j}}\left\{\frac{\partial \mathrm{~T}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}}\right\}-\mathrm{L} \quad \\
\mathrm{H} & =\sum \dot{q}_{j} \frac{\partial}{\partial \dot{q}_{j}}\left(\frac{1}{2} m \dot{q}_{j}^{2}\right)-L & \\
& =\sum \mathrm{m}_{\mathrm{j}}^{2}-\mathrm{L} \\
& =2 \mathrm{~T}-\mathrm{L}=2 \mathrm{~T}-(\mathrm{T}-\mathrm{V}) \\
& =\mathrm{T}+\mathrm{V}=\mathrm{K} \cdot \mathrm{E}+\mathrm{P} \cdot \mathrm{E}=\text { Total energy. }
\end{array}
$$

$\Rightarrow \mathrm{H}$ represents the total energy of the system for conservative system.

### 1.8 CYCLIC (OR) IGNORABLE COORDINATE:

We know that the Lagrangian $L$ is a function of generalized coordinate $q j$, generalized velocity $\dot{q}_{\mathrm{j}}$ and time t . If the Lagrangian of a system does not contain a particular coordinate $\mathrm{q}_{\mathrm{k}}$, then $\frac{\partial L}{\partial q_{k}}=0$. such a coordinate is referred to as an ignorable or cyclic coordinate.
(i) Generalised momentum: [conjugate (or) canonical momentum]

Consider a system of mass points acted upon by forces derived from potentials dependent on position only.

Now Lagrange's equations of motion are

$$
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right)-\frac{\partial L}{\partial q_{j}}=0
$$

Suppose $\mathrm{q}_{\mathrm{j}}$ is cyclic.ie it does not occur in Lagrangian L , then for this coordinate Lagrange's equation reduces to

$$
\begin{aligned}
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right) & =0 \\
\frac{\partial L}{\partial \dot{q}_{j}} & =\text { constant }
\end{aligned}
$$

Generalized momentum $=$ constant.

$$
\frac{\partial L}{\partial \dot{x}_{i}}=\frac{\partial T}{\partial \dot{x}_{i}}-\frac{\partial V}{\partial x_{i}}=\frac{\partial T}{\partial \dot{x}_{i}}
$$

$$
\begin{aligned}
& =\frac{\partial}{\partial \dot{x}_{i}} \Sigma \frac{1}{2} m_{1}\left(\dot{x}_{i}^{2}+\dot{y}_{i}^{2}+\dot{z}_{i}^{2}\right) \\
& =m_{i} \dot{x}_{i}=p_{i x} \\
& =x \text { component of the linear momentum associated with the } i^{\text {th }} \text { particle } .
\end{aligned}
$$

Generalising the concept, a momentum associated with the coordinate $q_{j}$ shall be

$$
p_{j}=\frac{\partial T}{\partial \dot{q}_{j}}=\frac{\partial L}{\partial \dot{q}_{j}}=\text { generalized momentum. }
$$

Thus $p_{j}=$ constant
The generalized momentum conjugate to a cyclic coordinate is conserved.
If we put $p_{j}$ in Lagrange's equation we get $\dot{p}_{j}=\frac{\partial L}{\partial q_{j}}$

### 1.9 ROUTHIAN PROCEDURE AND EQUATIONS :

In Kepler's problem

$$
\mathrm{L}=\frac{1}{2} \mathrm{~m}\left(\dot{\mathrm{r}}^{2}+\mathrm{r}^{2} \dot{\theta}^{2}\right)+\frac{\mathrm{k}}{\mathrm{r}}
$$

$\theta$ does not occur in L and is therefore an ignorable coordinate so that corresponding momentum

$$
p_{\theta}=\frac{\partial L}{\partial \dot{\theta}}=m r^{2} \dot{\theta}=l=a \text { constant }
$$

It appears from the expression L that we can solve Kepler problem without considering $\theta$ which is ignorable. But this is not so in Lagrangian formation because $\dot{\theta}$ which requires how $\theta$ varies with t . Thus we consider $\theta$. However Routhian procedure which eliminates this consideration. We want to find a function R called Routhian function such that it does not contain generalized velocities corresponding to ignorable coordinates.

$$
\mathrm{L}=\mathrm{L}\left(\mathrm{q}_{1}, \mathrm{q}_{2}, \ldots . . \mathrm{q}_{\mathrm{n}}, \dot{\mathrm{q}}_{1}, \dot{\mathrm{q}}_{2} \ldots . \dot{\mathrm{q}}_{\mathrm{n}}, \mathrm{t}\right)
$$

If coordinates $\mathrm{q}_{1} \ldots . . . \mathrm{q}_{\mathrm{k}}$ are ignorable then

$$
\begin{gather*}
\mathrm{L}=\mathrm{L}\left(\mathrm{q}_{\mathrm{k}+1} \ldots \ldots \mathrm{q}_{\mathrm{n}}, \dot{\mathrm{q}}_{1} \ldots . . \dot{\mathrm{q}}_{\mathrm{n}}, \mathrm{t}\right) \\
\delta L=\sum_{j=k+1}^{n} \frac{\partial L}{\partial q_{j}} \delta q_{j}+\sum_{j=1}^{n} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}+\frac{\partial L}{\partial t} \delta t \\
\text { (or) }\left[\delta L-\sum_{j=1}^{k} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}\right]=\sum_{j=k+1}^{n} \frac{\partial L}{\partial q_{j}} \delta q_{j}+\sum_{j=k+1}^{n} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}+\frac{\partial L}{\partial t} \delta t \tag{1}
\end{gather*}
$$

Routhian function R in which velocities $\dot{\mathrm{q}}_{1} \ldots \ldots . \dot{\mathrm{q}}_{\mathrm{k}}$ corresponding to ignorable coordinates $\mathrm{q}_{1} \ldots \ldots . \mathrm{q}_{\mathrm{k}}$ are eliminated, can be written as

$$
R=R\left(q_{k+1} \cdots q_{n}, \ldots \dot{q}_{k+1} \ldots \dot{q}_{n}, t\right)
$$

so that

$$
\begin{equation*}
\delta R=\sum_{J=k+1}^{n} \frac{\partial R}{\partial q_{j}} \delta q_{j}+\sum_{J=k+1}^{n} \frac{\partial R}{\partial \dot{q}_{j}} \delta q_{j}+\frac{\partial R}{\partial t} \delta t \tag{2}
\end{equation*}
$$

We can also define the Routhian function as

$$
\begin{align*}
\mathrm{R} & =\mathrm{L}-\sum_{\mathrm{J}=1}^{\mathrm{k}} \dot{\mathrm{q}}_{\mathrm{j}} \mathrm{p}_{\mathrm{j}} \\
\delta R & =\delta L-\sum_{J=1}^{k} \dot{q}_{j} \delta p_{j}-\sum_{J=1}^{k} \delta \dot{q}_{j} p_{j} \\
& =\delta L-\sum_{J=1}^{k} p_{j} \delta \dot{q}_{j}-\sum_{J=1}^{k} \dot{q}_{j} \delta p_{j} \\
& =\left[\delta L-\sum_{J=1}^{k} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}\right]-\sum_{J=1}^{k} \dot{q}_{j} \delta p_{j} \\
& =\sum_{J=k+1}^{n} \frac{\partial L}{\partial q_{j}} \delta q_{j}+\sum_{J=k+1}^{n} \frac{\partial L}{\partial \dot{q}_{j}} \delta \dot{q}_{j}+\frac{\partial L}{\partial t} \delta t-\sum_{J=1}^{k} \dot{q}_{j} \delta p_{j} \tag{3}
\end{align*}
$$

Comparing equations (2) and (3), we get

$$
\left.\begin{array}{l}
\frac{\partial \mathrm{L}}{\partial \mathrm{q}_{\mathrm{j}}}=\frac{\partial \mathrm{R}}{\partial \mathrm{q}_{\mathrm{j}}}  \tag{4}\\
\frac{\partial \mathrm{~L}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}}=\frac{\partial \mathrm{R}}{\partial \dot{\mathrm{q}}_{\mathrm{j}}}
\end{array}\right] \quad \mathrm{J}=\mathrm{k}+1 \ldots \mathrm{n}
$$

putting equation (4) in Lagrange's equations

$$
\sum_{J=1}^{n}\left[\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{j}}\right)-\frac{\partial L}{\partial q_{j}}\right]=0
$$

we get

$$
\begin{equation*}
\sum_{J=K+1}^{n}\left[\frac{d}{d t}\left(\frac{\partial R}{\partial \dot{q}_{j}}\right)-\frac{\partial R}{\partial q_{j}}\right]=0 \tag{5}
\end{equation*}
$$

in which Routhian function has replaced Lagranian function. These are only ( $\mathrm{n}-\mathrm{k}$ ) second order equations in the non-ignorable variables. Thus we can eliminate the ignorable coordinates through Routhian procedure.
(i) Kepler's problem:

$$
\begin{aligned}
& \text { we know that } \quad p_{\theta}=m r^{2} \dot{\theta} \\
& \text { so that } \\
& \mathrm{R}=L-p_{\theta} \dot{\theta} \\
& =L-m r^{2} \dot{\theta}^{2}
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{1}{2} m\left(\dot{r}^{2}+r^{2} \dot{\theta}^{2}\right)+\frac{k}{r}-m r^{2} \dot{\theta}^{2} \\
& =\frac{1}{2} \mathrm{~m}\left(\dot{\mathrm{r}}^{2}-\mathrm{r}^{2} \dot{\theta}^{2}\right)+\frac{\mathrm{k}}{\mathrm{r}} \\
\frac{\partial \mathrm{R}}{\partial \dot{\mathrm{r}}} & =m \dot{\mathrm{r}} \\
\frac{\partial R}{\partial r} & =m r \dot{\theta}^{2}-\frac{k}{r^{2}}
\end{aligned}
$$

Now we get the equation of motion as

$$
\begin{aligned}
\frac{d}{d t}(m \dot{r})-m r \dot{\theta}^{2}+\frac{k}{r^{2}} & =0 \\
m \ddot{r}-m r \dot{\theta}^{2}+\frac{k}{r^{2}} & =0 \\
m \ddot{r} & =m \dot{\theta}^{2}-\frac{\mathrm{k}}{\mathrm{r}^{2}} \\
& =\frac{\mathrm{mv}^{2} \theta}{\mathrm{r}}+\mathrm{f}(\mathrm{r})
\end{aligned}
$$

[from equation (5)]

Which is the equation of motion of a particle under central force.

### 1.10 DERIVATION OF HAMILTON'S CANONICAL EQUATIONS FROM VARIATIONAL PRINCIPLE:

Hamilton's principle is stated as

$$
\begin{aligned}
& \delta I=\delta \int_{t_{1}}^{t_{2}} L d t=0 \\
& H=\sum p_{j} \dot{q}_{j}-L \\
& L=\sum p_{j} \dot{q}_{j}-H
\end{aligned}
$$

$$
\begin{equation*}
\text { and hence } \delta I=\delta \int_{t_{1}}^{t_{2}}\left[\sum p_{j} \dot{q}_{j}-H\left(q_{j}, p_{j}, t\right)\right] d t=0 \tag{1}
\end{equation*}
$$

Eqn. (1) is termed as modified Hamilton's principle.
The $\delta$ variation can be expressed as $\delta \rightarrow \mathrm{d} \alpha \frac{\partial}{\partial \alpha}$

$$
\begin{aligned}
& \delta I=d \alpha \frac{\partial I}{\partial \alpha} \\
&=d \alpha \frac{\partial}{\partial \alpha} \int_{t_{1}}^{t_{2}}\left[\Sigma p_{j} \dot{q}_{j}-H\left(q_{j}, p_{j}, t\right)\right] d t=0
\end{aligned}
$$

end point's times are same for every path. Limits are independent of $\alpha$ and hence $\frac{\partial}{\partial \alpha}$ can be taken inside the integral.
$\delta \mathbf{I}=\mathrm{d} \alpha \int_{t_{1}}^{t_{2}} \Sigma\left[\frac{\partial p_{j}}{\partial \alpha} \dot{q}_{j}+p_{j} \frac{\partial \dot{q}_{j}}{\partial \alpha}-\frac{\partial H}{\partial q_{j}} \frac{\partial q_{j}}{\partial \alpha}-\frac{\partial H}{\partial p_{j}} \frac{\partial p_{j}}{\partial \alpha}-\frac{\partial H}{\partial t} \frac{\partial t}{\partial \alpha}\right] d t=0$
But $\frac{\partial \mathrm{t}}{\partial \alpha}=0$ since time of travel along every path is same. Also

$$
\begin{aligned}
\int_{t_{1}}^{t_{2}} p_{j} \frac{\partial \dot{q}_{j}}{\partial \alpha} & d t
\end{aligned}=\int_{t_{1}}^{t_{2}} p_{j} \frac{d}{d t}\left(\frac{\partial q_{j}}{\partial \alpha}\right) d t t+\left.p_{j} \frac{\partial q_{j}}{\partial \alpha}\right|_{t_{1}} ^{t_{2}}-\int_{t_{1}}^{t_{2}} \dot{p}_{j} \frac{\partial q_{j}}{\partial \alpha} d t .
$$

$$
\frac{\partial \mathrm{q}_{\mathrm{j}}}{\partial \alpha} \text { vanishes at limits } \mathrm{t}_{1} \text { and } \mathrm{t}_{2},
$$

Now equation (2) becomes

$$
\delta \mathbf{I}=\mathrm{d} \alpha \int_{t_{1}}^{t_{2}} \Sigma\left[\frac{\partial p_{j}}{\partial \alpha} \dot{q}_{j}-\dot{p}_{j} \frac{\partial q_{j}}{\partial \alpha}-\frac{\partial H}{\partial q_{j}} \frac{\partial q_{j}}{\partial \alpha}-\frac{\partial H}{\partial p_{j}} \frac{\partial p_{j}}{\partial \alpha}\right] d t=0
$$

Putting $\frac{\partial q_{j}}{\partial \alpha} d \alpha=\delta q_{j}$

$$
\frac{\partial p_{j}}{\partial \alpha} d \alpha=\delta p_{j}
$$

We get $\quad \delta I=\int_{t_{1}}^{t_{2}} \Sigma\left[\delta p_{j} \dot{q}_{j}-\dot{p}_{j} \delta q_{j}-\frac{\partial H}{\partial q_{j}} \delta q_{j}-\frac{\partial H}{\partial p_{j}} \delta p_{j}\right] d t=0$

$$
=\int_{t_{1}}^{t_{2}} \Sigma\left\{\delta p_{j}\left[\dot{q}_{j}-\frac{\partial H}{\partial p_{j}}\right]-\delta q_{j}\left[\dot{p}_{j}+\frac{\partial H}{\partial q_{j}}\right]\right\} d t=0
$$

Since $p_{j}$ and $\mathrm{q}_{\mathrm{j}}$ are independent variables, the above equation can be satisfied only if

$$
\begin{aligned}
& q_{j}-\frac{\partial H}{\partial p_{j}}=0 \Rightarrow \dot{q}_{j}=\frac{\partial H}{\partial p_{j}} \\
& \dot{p}_{j}+\frac{\partial H}{\partial q_{j}}=0 \Rightarrow \dot{p}_{j}=-\frac{\partial H}{\partial q_{j}}
\end{aligned}
$$

which are the desired canonical equations of motion.

### 1.11 APPLICATIONS OF HAMILTON'S EQUATIONS OF MOTION:

## 1. Simple pendulum :

The kinetic energy of the bob $\mathrm{T}=\frac{1}{2} \mathrm{~m} l^{2} \dot{\theta}^{2}$
and the potential energy $\quad \mathrm{r}=\mathrm{mg} l(1-\cos \theta)$
Lagrangian $\quad \mathrm{L}=\mathrm{T}-\mathrm{V}$

$$
\begin{align*}
& =\frac{1}{2} m l^{2} \dot{\theta}^{2}-\mathrm{mg} l(1-\cos \theta)  \tag{1}\\
\mathrm{p}_{\theta} & =\frac{\partial \mathrm{L}}{\partial \dot{\theta}}=\mathrm{m} l^{2} \dot{\theta}^{2}  \tag{2}\\
\text { Hamiltonian } \mathrm{H} & =\Sigma p_{j} \dot{q}_{j}-L \\
& =\mathrm{p}_{\theta} \dot{\theta}-\mathrm{L} \\
& =\mathrm{m} l^{2} \dot{\theta}^{2}-\left[\frac{1}{2} \mathrm{~m} l^{2} \dot{\theta}^{2}-\mathrm{mg} l(1-\cos \theta)\right] \\
& =\frac{1}{2} m l^{2} \theta^{2}+m g l(1-\cos \theta)  \tag{3}\\
& =\mathrm{T}+\mathrm{V}
\end{align*}
$$

Then the system is conservative.
Putting equation (2) into equation (3), we get

$$
H=\frac{1}{2} m l^{2}\left(\frac{p_{\theta}}{m l^{2}}\right)^{2}+m g l(1-\cos \theta)
$$

giving

$$
\left.\begin{array}{l}
\frac{\partial H}{\partial p_{\theta}}=\frac{p_{\theta}}{m l^{2}}  \tag{4}\\
\frac{\partial H}{\partial \theta}=m g l \sin \theta
\end{array}\right]
$$

Thus Hamilton's equations of motion for this system will be

$$
\begin{align*}
& \dot{\theta}=\frac{\partial H}{\partial \theta}=\frac{p_{\theta}}{m l^{2}}  \tag{5}\\
& \dot{p}_{\theta}=\frac{-\partial H}{\partial \theta}=-m g l \sin \theta \tag{6}
\end{align*}
$$

From equation (5), we have

$$
\dot{p}_{\theta}=m l^{2} \ddot{\theta}
$$

and hence equation (6) becomes

$$
\begin{gathered}
\mathrm{m} l^{2} \ddot{\theta}=-\mathrm{mg} l \sin \theta \\
\ddot{\theta}=-\mathrm{g} \sin \theta \\
\ddot{\theta}+\mathrm{g} \sin \theta=0 \\
l \ddot{\theta}+\mathrm{g} \theta=0 \\
\ddot{\theta}+\frac{\mathrm{g}}{l} \theta=0
\end{gathered}
$$

which represents the equation of motion of a simple pendulum with period $2 \pi \sqrt{l / g}$

## 2. Compound pendulum :

$$
\begin{aligned}
& \mathrm{T}=\frac{1}{2} \mathrm{I} \dot{\theta}^{2} \\
& \mathrm{~V}=-\mathrm{mg} / \cos \theta
\end{aligned}
$$

Now the Lagrangian $\mathrm{L}=\frac{1}{2} I \dot{\theta}^{2}+m g l \cos \theta$

$$
\text { Then } \begin{align*}
p_{\theta} & =\frac{\partial L}{\partial \dot{\theta}} \\
& =\mathrm{I} \dot{\theta}  \tag{1}\\
\text { Hamiltonian } \quad \mathrm{H} & =\Sigma p_{j} \dot{q}_{j}-L \\
& =p_{\theta} \dot{\theta}-L \\
& =I \dot{\theta}^{2}-\frac{1}{2} I \dot{\theta}^{2}-m g l \cos \theta \\
& =\frac{1}{2} I \dot{\theta}^{2}-m g l \cos \theta \\
& =\frac{1}{2} \mathrm{I}\left(\frac{\mathrm{p}_{\theta}}{\mathrm{I}}\right)^{2}-\mathrm{mgl} \cos \theta \\
& =\frac{p_{\theta}{ }^{2}}{2 I}-m g l \cos \theta  \tag{2}\\
& =\mathrm{T}+\mathrm{V}
\end{align*}
$$

Then the system is conservative.
The Hamilton's equations of motion for $\theta$ and $p_{\theta}$ are

$$
\left.\begin{array}{l}
\dot{\theta}=\frac{\partial H}{\partial P_{\theta}}  \tag{3}\\
\dot{p}_{\theta}=\frac{-\partial H}{\partial \theta}
\end{array}\right]
$$

From equation (2) we find

$$
\begin{align*}
& \frac{\partial \mathrm{H}}{\partial \mathrm{p}_{\theta}}=\frac{\mathrm{p}_{\theta}}{\mathrm{I}} \\
& \frac{\partial \mathrm{H}}{\partial \theta}=\mathrm{mgl} \sin \theta \tag{4}
\end{align*}
$$

Now equation (3) becomes $\dot{\theta}=\frac{p_{\theta}}{I}$
and

$$
\begin{equation*}
\dot{\mathrm{p}}_{\theta}=-\mathrm{mg} l \sin \theta \tag{5}
\end{equation*}
$$

From equation (4) $\quad \dot{\mathrm{p}}_{\theta}=\mathrm{I} \ddot{\theta}$
Now equation (5) becomes

$$
\begin{aligned}
& I \ddot{\theta}=-m g l \sin \theta \\
& \ddot{\theta}+\frac{m g l}{I} \sin \theta=\theta \\
& \Rightarrow \ddot{\theta}+\omega^{2} \theta=\theta
\end{aligned}
$$

which is the equation of motion of compound pendulum with $\omega=\sqrt{\frac{m g l}{I}}$

## 3. Linear Harmonic Oscillator :

The system is conservative and constraint is independent of time. Hamiltonian will represent the total energy of the system. The Lagrangian

$$
\begin{aligned}
L & =T-V \\
& =\frac{1}{2} m \dot{x}^{2}-\frac{1}{2} k x^{2} \\
\frac{\partial L}{\partial \dot{x}} & =\frac{\partial T}{\partial \dot{x}}=p=m \dot{x} \\
\dot{x} & =\frac{p}{m}
\end{aligned}
$$

giving Hamiltonian

$$
\begin{aligned}
H & =T+V \\
& =\frac{1}{2} m\left(\frac{p}{m}\right)^{2}+\frac{1}{2} k x^{2} \\
& =\frac{p^{2}}{2 m}=+\frac{1}{2} k x^{2}
\end{aligned}
$$

Equations of motion are

$$
\begin{aligned}
& \dot{p}=\frac{-\partial H}{\partial x}=-k x \\
& \dot{x}=\frac{\partial H}{\partial p}=\frac{p}{m} \\
& \ddot{x}=\frac{\dot{p}}{m}=\frac{-k x}{m} \\
& m \ddot{x}+k x=0
\end{aligned}
$$

This relation shows that motion is simple harmonic and is the desired equation.

## 4. Particle in a central field of force :

The system is conservative and hence the Hamiltonian represents the total energy.

$$
\begin{aligned}
& T=\frac{1}{2} m\left(\dot{r}^{2}+r^{2} \dot{\theta}^{2}\right) \\
& V=V(r)
\end{aligned}
$$

Lagrangian $\mathrm{L}=\mathrm{T}-\mathrm{V}$

$$
\begin{aligned}
& =\frac{1}{2} m\left(\dot{r}^{2}+r^{2} \dot{\theta}^{2}\right)-V(r) \\
p_{r} & =\frac{\partial L}{\partial \dot{r}}=m \dot{r} \Rightarrow \dot{\mathrm{r}}=\frac{\mathrm{p}_{\mathrm{r}}}{\mathrm{~m}} \\
p_{\theta} & =\frac{\partial L}{\partial \dot{\theta}}=m r^{2} \dot{\theta} \Rightarrow \dot{\theta}=\frac{\mathrm{p}_{\theta}}{\mathrm{mr}^{2}}
\end{aligned}
$$

Hamiltonian $\mathrm{H}=\mathrm{T}+\mathrm{V}$

$$
\left.\begin{array}{rl} 
& =\frac{1}{2} m\left[\dot{r}^{2}+r^{2} \dot{\theta}^{2}\right]+V(r) \\
& =\frac{p_{r}{ }^{2}}{2 m}+\frac{p_{\theta}{ }^{2}}{2 m r^{2}}+V(r) \\
\dot{p}_{r} & =-\frac{\partial H}{\partial r}=\frac{p_{\theta}{ }^{2}}{m r^{3}}-\frac{\partial V}{\partial r}  \tag{1}\\
\dot{\mathrm{p}}_{\theta} & =-\frac{\partial \mathrm{H}}{\partial \theta}=0
\end{array}\right]
$$

and

$$
\left.\begin{array}{l}
\dot{\mathrm{r}}=\frac{\partial \mathrm{H}}{\partial \mathrm{p}_{\mathrm{r}}}=\frac{\mathrm{p}_{\mathrm{r}}}{\mathrm{~m}} \\
\dot{\theta}=\frac{\partial \mathrm{H}}{\partial \mathrm{p}_{\theta}}=\frac{\mathrm{p}_{\theta}}{\mathrm{mr}^{2}} \tag{2}
\end{array} \quad\right\}
$$

Which are the desired equations of motion.
From equation (2) we can write

$$
\begin{align*}
& \ddot{r}=\frac{\dot{p}_{r}}{m}=\frac{p_{\theta}{ }^{2}}{m^{2} r^{3}}-\frac{1}{m} \frac{\partial V}{\partial r} \\
& m \ddot{r}=\frac{p_{\theta}{ }^{2}}{m r^{3}}-\frac{\partial V}{\partial r} \tag{3}
\end{align*}
$$

We put

$$
\begin{aligned}
-\frac{\partial V}{\partial r} & =F(r)=\text { radial force and } \\
\frac{p_{\theta}{ }^{2}}{m r^{3}} & =\frac{\left[m r^{2} \dot{\theta}\right]^{2}}{m r^{3}}=m r \dot{\theta}^{2} \quad[\text { Fromequation }(2)] \\
& =\frac{m[\dot{r} \theta]^{2}}{r} \\
& =\frac{m \mathrm{v}_{\theta}{ }^{2}}{r}=\text { centrifuga l force }
\end{aligned}
$$

From equation (3)

$$
m \ddot{r}=\frac{m \mathrm{v}_{\theta}{ }^{2}}{r}+F(r)
$$

gives an equation of motion involving the actual force $\mathrm{F}(\mathrm{r})$ and a centrifugal force $\frac{m \mathrm{v}_{\theta}{ }^{2}}{r}$.

## 5. Hamiltonian for a charged particle in an electromagnetic field :

Lagrangian $L=T-q\left(\varphi-\frac{1}{c} \overrightarrow{\mathrm{v}} \cdot \vec{A}\right)$

$$
\begin{aligned}
& =\Sigma \frac{1}{2} \mathrm{mv}_{\mathrm{j}}^{2}-\mathrm{q}\left(\varphi-\Sigma \frac{\mathrm{v}_{\mathrm{j}} \mathrm{~A}_{\mathrm{j}}}{\mathrm{c}}\right) \\
p_{j} & =\frac{\partial L}{\partial \dot{q}_{j}}=\frac{\partial L}{\partial \mathrm{v}_{j}} \\
& =m \mathrm{v}_{j}+\frac{q}{c} A_{j}
\end{aligned}
$$

Hamiltonian $\mathrm{H}=\Sigma \dot{\mathrm{q}}_{\mathrm{j}} \mathrm{p}_{\mathrm{j}}-\mathrm{L}$

$$
\begin{aligned}
& =\Sigma \mathrm{v}_{j}\left(m \mathrm{v}_{j}+\frac{q}{c} A_{j}\right)-L \\
& =\Sigma m \mathrm{v}_{j}^{2}+\Sigma \frac{q}{c} \mathrm{v}_{j} A_{j}-L \\
& =m \mathrm{v}^{2}+\frac{q}{c}(\overrightarrow{\mathrm{v}} \cdot \vec{A})-L \\
& =2 T+\frac{q}{c}(\overrightarrow{\mathrm{v}} \cdot \vec{A})-\left[T-q\left(\varphi-\frac{1}{c} \overrightarrow{\mathrm{v}} \cdot \vec{A}\right)\right] \\
& =T+q \varphi \\
& =\frac{1}{2} m \mathrm{v}^{2}+q \varphi
\end{aligned}
$$

such that H can be interpreted as the sum of kinetic and electrostatic potential energies of the particle.

## 6. Particle moving hear the surface of earth :

Let z axis be along upward vertical direction, then kinetic energy is

$$
\mathrm{T}=\frac{1}{2} \mathrm{~m}\left(\dot{x}^{2}+\dot{y}^{2}+\dot{z}^{2}\right)
$$

The applied force on the body is its weight acting in negative z direction.ie

$$
\begin{aligned}
& F=F_{z}=-m g=-\frac{\partial V}{\partial z} \\
& \therefore V=m g z
\end{aligned}
$$

Lagrangian

$$
\begin{aligned}
& L=T-V \\
& =\frac{1}{2} m\left(\dot{x}^{2}+\dot{y}^{2}+\dot{z}^{2}\right)-m g z \\
& \frac{\partial \mathrm{~L}}{\partial \dot{x}}=\frac{\partial \mathrm{T}}{\partial \dot{x}}=\mathrm{p}_{x}=\mathrm{m} \dot{x} \\
& \text { giving } \quad \dot{x}=\frac{\mathrm{p}_{x}}{\mathrm{~m}} \text {. } \\
& \text { Similarly } \quad \dot{\mathrm{y}}=\frac{\mathrm{p}_{\mathrm{y}}}{\mathrm{~m}} \quad \text { and } \quad \dot{\mathrm{z}}=\frac{\mathrm{p}_{\mathrm{z}}}{\mathrm{~m}}
\end{aligned}
$$

Hamiltonian for such a system is conserved. ie

$$
\begin{aligned}
H & =T+V \\
& =\frac{1}{2} m\left(\dot{x}^{2}+\dot{y}^{2}+\dot{z}^{2}\right)+m g z
\end{aligned}
$$

$$
=\frac{1}{2 \mathrm{~m}}\left(\mathrm{p}_{x}^{2}+\mathrm{p}_{\mathrm{y}}^{2}+\mathrm{p}_{\mathrm{z}}^{2}\right)+\mathrm{mgz}
$$

giving equations of motion

$$
\left.\begin{array}{l}
\dot{\mathrm{p}}_{x}=-\frac{\partial \mathrm{H}}{\partial x}=0 \\
\dot{\mathrm{p}}_{\mathrm{y}}=-\frac{\partial \mathrm{H}}{\partial \mathrm{y}}=0 \\
\dot{\mathrm{p}}_{\mathrm{z}}=-\frac{\partial \mathrm{H}}{\partial \mathrm{z}}=-\mathrm{mg} \\
\dot{\mathrm{x}}=\frac{\partial \mathrm{H}}{\partial \mathrm{p}_{x}}=\frac{\mathrm{p}_{x}}{\mathrm{~m}}  \tag{2}\\
\dot{\mathrm{y}}=\frac{\partial \mathrm{H}}{\partial \mathrm{p}_{\mathrm{y}}}=\frac{\mathrm{p}_{\mathrm{y}}}{\mathrm{~m}} \\
\dot{\mathrm{z}}=\frac{\partial \mathrm{H}}{\partial \mathrm{p}_{\mathrm{z}}}=\frac{\mathrm{p}_{\mathrm{z}}}{\mathrm{~m}}
\end{array}\right]
$$

From equation (2) we get

$$
\begin{aligned}
& \ddot{x}=\frac{\dot{\mathrm{p}}_{x}}{\mathrm{~m}}=0 \\
& \ddot{\mathrm{y}}=\frac{\dot{\mathrm{p}}_{\mathrm{y}}}{\mathrm{~m}}=0 \\
& \ddot{\mathrm{z}}=\frac{\dot{\mathrm{p}}_{\mathrm{z}}}{\mathrm{~m}}=-\mathrm{g}
\end{aligned}
$$


which shows that the acceleration along $z$ direction is the acceleration due to gravity and is true.

## UNIT 2

## POISSON BRACKET AND THEORY OF SMALL OSCILLATIONS

Poisson bracket, Special cases of Poisson bracket, Poisson theorem, Poisson bracket and canonical transformation, Jacobi identity and its derivation, Lagrange bracket and its properties, the relationship between Poisson and Lagrange brackets and its derivation, the angular momenta and Poisson bracket, Liouville's theorem and its applications; Theory of small oscillations:

Formulation of the problem, Eigenvalue equation and the principle axis transformation, frequencies of free vibration and normal coordinates, free vibrations of a linear triatomic molecule

### 2.1 POISSON BRACKET : DEFINITION

Let $F$ be any dynamical variable of a system.
Suppose $F$ is function of conjugate variables $q_{j}, p_{j}$ and $t$, then

$$
\begin{aligned}
\frac{d F}{d t} & =\frac{d F}{d t}\left(q_{j}, p_{j}, t\right)=\sum_{j} \frac{\partial F}{\partial q_{j}} \dot{q}_{j}+\frac{\partial F}{\partial p_{j}} \dot{p}_{j}+\frac{\partial F}{\partial t} \\
& =\sum_{j}\left(\frac{\partial F}{\partial q_{j}} \frac{\partial H}{\partial p_{j}}-\frac{\partial F}{\partial p_{j}} \frac{\partial H}{\partial q_{j}}\right)+\frac{\partial F}{\partial t}
\end{aligned}
$$

on using Hamiltonts canonical equations of motion.
The first bracketted term is called Poisson Bracket of F with H .
In general if X and Y are two dynamical variables then

$$
\begin{equation*}
[X, Y]_{q, p}=\sum_{j}\left(\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}-\frac{\partial X}{\partial p_{j}} \frac{\partial Y}{\partial q_{j}}\right) \tag{1}
\end{equation*}
$$

### 2.2 SPECIAL CASES OF POISSON BRACKET

(a) $\quad[X, Y]=-[Y, X]$
(b) $\quad[X, X]=0$
(c) $[X, Y+Z]=[X, Y]+[X, Z]$
(d) $[X, Y Z]=Y[X, Z]+[X, Y] Z$

Also

$$
\begin{align*}
(e) \quad\left[q_{i}, q_{j}\right]_{q, p} & =0=\left[p_{i}, p_{j}\right]_{q, p} \\
(f) \quad\left[q_{i}, p_{j}\right]_{q, p} & =\delta_{i j}=0 \text { if } i \neq j  \tag{3}\\
& =1 \text { if } i=j
\end{align*}
$$

Equation (3) are known as fundamental Poisson brackets.
Take the property

$$
\text { (c) }[X, Y+Z]=[X, Y]+[X, Z]
$$

## Proof :

$$
\begin{aligned}
{[X, Y+Z] } & =\sum_{j}\left(\frac{\partial X}{\partial q_{j}} \frac{\partial(Y+Z)}{\partial p_{j}}-\frac{\partial X}{\partial p_{j}} \frac{\partial(Y+Z)}{\partial q_{j}}\right) \\
& =\sum_{j}\left(\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial X}{\partial q_{j}} \frac{\partial Z}{\partial p_{j}}\right)-\sum_{j}\left(\frac{\partial X}{\partial p_{j}} \frac{\partial Y}{\partial q_{j}}+\frac{\partial X}{\partial p_{j}} \frac{\partial Z}{\partial q_{j}}\right) \\
& =\sum_{j}\left(\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}-\frac{\partial X}{\partial p_{j}} \frac{\partial Y}{\partial q_{j}}\right)+\sum_{j}\left(\frac{\partial X}{\partial q_{j}} \frac{\partial Z}{\partial p_{j}}-\frac{\partial X}{\partial p_{j}} \frac{\partial Z}{\partial q_{j}}\right) \\
& =[X, Y]+[X, Z]
\end{aligned}
$$

Similarly

$$
\begin{gathered}
{\left[q_{i}, q_{j}\right]_{q, p}=\sum_{k}\left(\frac{\partial q_{i}}{\partial q_{k}} \frac{\partial q_{j}}{\partial p_{k}}-\frac{\partial q_{i}}{\partial p_{k}} \frac{\partial q_{j}}{\partial q_{k}}\right)} \\
\frac{\partial q_{j}}{\partial p_{k}}=\frac{\partial q_{i}}{\partial p_{k}}=0
\end{gathered}
$$

and hence

$$
\begin{aligned}
& {\left[q_{i}, q_{j}\right]_{q, p}=0=\left[p_{i}, p_{j}\right]_{q, p} } \\
& {\left[q_{i}, p_{j}\right]_{q, p} }=\sum_{k}\left(\frac{\partial q_{i}}{\partial q_{k}} \frac{\partial p_{j}}{\partial p_{k}}-\frac{\partial q_{i}}{\partial p_{k}} \frac{\partial p_{j}}{\partial q_{k}}\right) \\
&=\sum_{k} \frac{\partial q_{i}}{\partial q_{k}} \frac{\partial p_{j}}{\partial p_{k}}
\end{aligned}
$$

since

$$
\frac{\partial q_{i}}{\partial p_{k}} \text { and } \frac{\partial p_{j}}{\partial q_{k}}=0
$$

Also

$$
\frac{\partial q_{i}}{\partial q_{k}} \text { and } \frac{\partial p_{j}}{\partial p_{k}}=0
$$

sothat

$$
\begin{aligned}
{\left[q_{i}, p_{j}\right]_{q, p} } & =\sum \delta_{i k} \delta_{j k} \\
& =\delta_{i j} \\
& =0 \quad i f i \neq j \\
& =1 \quad i f i=j
\end{aligned}
$$

## Excercises

1.If $[\phi, \psi]$ be the Poisson bracket of $\phi$ and $\psi$ prove that

$$
\begin{aligned}
\text { (a) } \frac{\partial}{\partial t}[\phi, \psi] & =\left[\frac{\partial \phi}{\partial t}, \psi\right]+\left[\phi, \frac{\partial \psi}{\partial t}\right] \\
\text { (b) } \frac{d}{d t}[\phi, \psi] & =\left[\frac{d \phi}{d t}, \psi\right]+\left[\phi, \frac{d \psi}{d t}\right]
\end{aligned}
$$

We have

$$
\begin{gathered}
{[\phi, \psi]=\sum_{i}\left(\frac{\partial \phi}{\partial q_{i}} \frac{\partial \psi}{\partial p_{i}}-\frac{\partial \psi}{\partial q_{i}} \frac{\partial \phi}{\partial p_{i}}\right)} \\
\frac{\partial}{\partial t}[\phi, \psi]=\sum_{i} \frac{\partial}{\partial t}\left\{\frac{\partial \phi}{\partial q_{i}} \frac{\partial \psi}{\partial p_{i}}-\frac{\partial \psi}{\partial q_{i}} \frac{\partial \phi}{\partial p_{i}}\right\} \\
=\sum_{i} \frac{\partial}{\partial q_{i}}\left(\frac{\partial \phi}{\partial t}\right) \frac{\partial \psi}{\partial p_{i}}+\sum_{i} \frac{\partial \phi}{\partial q_{i}} \frac{\partial}{\partial p_{i}}\left(\frac{\partial \psi}{\partial t}\right) \\
-\sum_{i} \frac{\partial}{\partial q_{i}}\left(\frac{\partial \psi}{\partial t}\right) \frac{\partial \phi}{\partial p_{i}}-\sum_{i} \frac{\partial \psi}{\partial q_{i}} \frac{\partial}{\partial p_{i}}\left(\frac{\partial \phi}{\partial t}\right) \\
=\sum_{i}\left\{\frac{\partial}{\partial q_{i}}\left(\frac{\partial \phi}{\partial t}\right) \frac{\partial \psi}{\partial p_{i}}-\frac{\partial \psi}{\partial q_{i}} \frac{\partial}{\partial p_{i}}\left(\frac{\partial \phi}{\partial t}\right)\right\} \\
+\sum_{i}\left\{\frac{\partial \phi}{\partial q_{i}} \frac{\partial}{\partial p_{i}}\left(\frac{\partial \psi}{\partial t}\right)-\frac{\partial}{\partial q_{i}}\left(\frac{\partial \psi}{\partial t}\right) \frac{\partial \phi}{\partial p_{i}}\right\} \\
=\left[\frac{d \phi}{d t}, \psi\right]+\left[\phi, \frac{d \psi}{d t}\right]
\end{gathered}
$$

2.If $\left\{p_{l}, q_{i}\right\},\left\{q_{l}, q_{i}\right\}$ are the Lagrange's brackets and $\left[p_{l}, p_{j}\right],\left[q_{l}, p_{j}\right]$ are the Poisson brackets, then prove that

$$
\sum_{i=1}^{n}\left\{p_{l}, q_{i}\right\}\left[p_{l} p_{j}\right]+\sum_{i=1}^{n}\left\{q_{l}, q_{i}\right\}\left[q_{l}, p_{j}\right]=0
$$

We have

$$
\begin{aligned}
\left\{p_{l}, q_{i}\right\} & =-\left\{q_{i}, p_{l}\right\} \\
& =-\delta_{i l}
\end{aligned}
$$

and

$$
\begin{aligned}
& \left\{q_{l}, q_{i}\right\}=0 \\
& {\left[p_{l}, p_{j}\right]=0} \\
& {\left[q_{l}, p_{j}\right]=\delta_{l j}}
\end{aligned}
$$

Substituting these values we get

$$
\begin{aligned}
\sum_{i=1}^{n}\left\{p_{l}, q_{i}\right\}\left[p_{l}, p_{j}\right]+\left\{q_{l}, q_{i}\right\}\left[q_{l}, p_{j}\right] & =-\delta_{i l} \times 0+0 \times \delta_{l j} \\
& =0
\end{aligned}
$$

3.If $\left\{q_{l}, q_{i}\right\},\left\{p_{l}, q_{i}\right\}$ are the Lagrange's brackets and $\left[q_{l}, q_{j}\right],\left[p_{l}, q_{j}\right]$ are the Poisson brackets, then prove that

$$
\sum_{i=1}^{n}\left\{q_{l}, q_{i}\right\}\left[q_{l}, q_{j}\right]+\sum_{i=1}^{n}\left\{p_{l}, q_{i}\right\}\left[p_{l}, q_{j}\right]=\delta_{i j}
$$

We know

$$
\begin{aligned}
& \left\{q_{l}, q_{i}\right\}=0 \\
& {\left[q_{l}, q_{j}\right]=0}
\end{aligned}
$$

Also

$$
\begin{aligned}
\left\{p_{l}, q_{i}\right\} & =-\left\{q_{i}, p_{l}\right\} \\
& =-\delta_{i l} \\
{\left[p_{l}, q_{j}\right] } & =-\left[q_{j}, p_{l}\right] \\
& =-\delta_{j l}
\end{aligned}
$$

$$
\begin{aligned}
\sum_{i=1}^{n}\left\{q_{l}, q_{i}\right\}\left[q_{l}, q_{j}\right]+\sum_{i=1}^{n}\left\{p_{l}, q_{i}\right\}\left[p_{l}, q_{j}\right] & =0 \times 0+\left[-\delta_{i l} \times-\delta_{j l}\right] \\
& =\delta_{i j}
\end{aligned}
$$

Hence proved.

### 2.3 POISSON'S THEOREM

For a dynamical variable $F(q, p, t)$

$$
\frac{d F}{d t}=[F, H]+\frac{\partial F}{\partial t}
$$

If F is a constant of motion so that $d F / d t=0$, then by Poisson's theorem

$$
[F, H]+\frac{\partial F}{\partial t}=0
$$

Furthermore if F does not contain time explicitly, that is $\partial F / \partial t=0$ then

$$
[F, H]=0
$$

This is the required condition for F to be a constant of motion.

### 2.4 POISSON BRACKET AND CANONICAL TRANSFORMATION :

Poisson brackets are invariant under a canonical transformation.That is

$$
[X, Y]_{q, p}=[X, Y]_{Q, P}
$$

Proof :

$$
\begin{aligned}
{[X, Y]_{Q, P} } & =\sum_{i}\left(\frac{\partial X}{\partial Q_{i}} \frac{\partial Y}{\partial P_{i}}-\frac{\partial X}{\partial P_{i}} \frac{\partial Y}{\partial Q_{i}}\right) \\
& =\sum_{i, j}\left\{\frac{\partial X}{\partial Q_{i}}\left(\frac{\partial Y}{\partial q_{j}} \frac{\partial q_{j}}{\partial P_{i}}+\frac{\partial Y}{\partial p_{j}} \frac{\partial p_{j}}{\partial P_{i}}\right)-\frac{\partial X}{\partial P_{i}}\left(\frac{\partial Y}{\partial q_{j}} \frac{\partial q_{j}}{\partial Q_{i}}+\frac{\partial Y}{\partial p_{j}} \frac{\partial p_{j}}{\partial Q_{i}}\right)\right\} \\
& =\sum_{j} \frac{\partial Y}{\partial q_{j}} \sum_{i}\left(\frac{\partial X}{\partial Q_{i}} \frac{\partial q_{j}}{\partial P_{i}}-\frac{\partial X}{\partial P_{i}} \frac{\partial q_{j}}{\partial Q_{i}}\right)+\sum_{j} \frac{\partial Y}{\partial p_{j}} \sum_{i}\left(\frac{\partial X}{\partial Q_{i}} \frac{\partial p_{j}}{\partial P_{i}}-\frac{\partial X}{\partial P_{i}} \frac{\partial p_{j}}{\partial Q_{i}}\right) \\
& =\sum_{j}\left\{\frac{\partial Y}{\partial q_{j}}\left[X, q_{j}\right]_{Q, P}+\frac{\partial Y}{\partial p_{j}}\left[X, p_{j}\right]_{Q, P}\right\}
\end{aligned}
$$

Further

$$
\begin{align*}
{\left[X, q_{j}\right]_{Q, P} } & =-\left[q_{j}, X\right]_{Q, P} \\
& =-\sum_{m}\left(\frac{\partial q_{j}}{\partial Q_{m}} \frac{\partial X}{\partial P_{m}}-\frac{\partial q_{j}}{\partial P_{m}} \frac{\partial X}{\partial Q_{m}}\right) \\
& =-\sum_{m, k}\left\{\frac{\partial q_{j}}{\partial Q_{m}}\left(\frac{\partial X}{\partial q_{k}} \frac{\partial q_{k}}{\partial P_{m}}+\frac{\partial X}{\partial p_{k}} \frac{\partial p_{k}}{\partial P_{m}}\right)-\frac{\partial q_{j}}{\partial P_{m}}\left(\frac{\partial X}{\partial q_{k}} \frac{\partial q_{k}}{\partial Q_{m}}+\frac{\partial X}{\partial p_{k}} \frac{\partial p_{k}}{\partial Q_{m}}\right)\right\} \\
& =-\sum_{k} \frac{\partial X}{\partial q_{k}} \sum_{m}\left(\frac{\partial q_{j}}{\partial Q_{m}} \frac{\partial q_{k}}{\partial P_{m}}-\frac{\partial q_{j}}{\partial P_{m}} \frac{\partial q_{k}}{\partial Q_{m}}\right)+\sum_{m} \frac{\partial X}{\partial p_{k}} \sum_{i}\left(\frac{\partial q_{j}}{\partial Q_{m}} \frac{\partial p_{k}}{\partial P_{m}}-\frac{\partial q_{j}}{\partial P_{m}} \frac{\partial p_{k}}{\partial Q_{m}}\right) \\
& =-\sum_{k}\left\{\frac{\partial X}{\partial q_{k}}\left[q_{j}, q_{k}\right]_{Q, P}+\frac{\partial X}{\partial p_{k}}\left[q_{j}, p_{k}\right]_{Q, P}\right\} \\
& =-\sum_{k} \frac{\partial X}{\partial p_{k}} \delta_{j k}=\frac{\partial X}{\partial p_{j}} \tag{4}
\end{align*}
$$

Similarly

$$
\begin{gathered}
{[X, Y]_{Q, P}=\sum_{j}\left(-\frac{\partial Y}{\partial q_{j}} \frac{\partial X}{\partial p_{j}}+\frac{\partial Y}{\partial p_{j}} \frac{\partial X}{\partial q_{j}}\right)} \\
=[X, Y]_{q, p}
\end{gathered}
$$

Hence Poisson brackets are invariant under canonical transformation.
A canonical transformation can be generated from functions $F_{1}\left(q_{j}, Q_{j}, t\right)$,
$F_{2}\left(q_{j}, P_{j}, t\right), F_{3}\left(p_{j}, Q_{j}, t\right)$ and $F_{4}\left(p_{j}, P_{j}, t\right)$.
In the case of generating function $F_{1}$, we have obtained

$$
p_{j}=\frac{\partial F_{1}}{\partial q_{j}}
$$

and

$$
P_{j}=-\frac{\partial F_{1}}{\partial Q_{j}}
$$

Using the above two relations we get

$$
\begin{equation*}
\frac{\partial p_{j}}{\partial Q_{i}}=\frac{\partial^{2} F_{1}}{\partial Q_{i} \partial q_{j}}=-\frac{\partial P_{i}}{\partial q_{j}} \tag{5}
\end{equation*}
$$

Similarly in the case of generating function $F_{2}$, we have obtained

$$
p_{j}=\frac{\partial F_{2}}{\partial q_{j}}
$$

and

$$
Q_{j}=\frac{\partial F_{2}}{\partial P_{j}}
$$

Using the above two relations we get

$$
\begin{equation*}
\frac{\partial p_{j}}{\partial P_{i}}=\frac{\partial^{2} F_{2}}{\partial P_{i} \partial q_{j}}=\frac{\partial Q_{i}}{\partial q_{j}} \tag{6}
\end{equation*}
$$

Similarly in the case of $F_{3}$ and $F_{4}$ we have seen that

$$
\begin{equation*}
\frac{\partial q_{j}}{\partial Q_{i}}=-\frac{\partial^{2} F_{3}}{\partial Q_{i} \partial p_{j}}=\frac{\partial P_{i}}{\partial p_{j}} \tag{7}
\end{equation*}
$$

and

$$
\begin{gather*}
\frac{\partial q_{j}}{\partial P_{i}}=\frac{\partial^{2} F_{4}}{\partial P_{i} \partial p_{j}}=-\frac{\partial Q_{i}}{\partial p_{j}}  \tag{8}\\
{\left[Q_{i}, P_{j}\right]_{q, p}=\sum_{k}\left(\frac{\partial Q_{i}}{\partial q_{k}} \frac{\partial P_{j}}{\partial p_{k}}-\frac{\partial Q_{i}}{\partial p_{k}} \frac{\partial P_{j}}{\partial q_{k}}\right)}
\end{gather*}
$$

Using eqns(5) and (7) we get

$$
\begin{aligned}
{\left[Q_{i}, P_{j}\right]_{q, p} } & =\sum_{k}\left(\frac{\partial Q_{i}}{\partial q_{k}} \frac{\partial q_{k}}{\partial Q_{j}}+\frac{\partial Q_{i}}{\partial p_{k}} \frac{\partial p_{k}}{\partial Q_{j}}\right) \\
& =\frac{\partial Q_{i}}{\partial Q_{j}}=\delta_{i j}=\left[Q_{i}, P_{j}\right]_{Q, P}
\end{aligned}
$$

and similarly

$$
\begin{align*}
{\left[Q_{i}, Q_{j}\right]_{q, p} } & =0=\left[Q_{i}, Q_{j}\right]_{Q, P} \\
{\left[P_{i}, P_{j}\right]_{q, p} } & =0=\left[P_{i}, P_{j}\right]_{Q, P} \tag{9}
\end{align*}
$$

Thus we have proved the affirmation for the fundamental brackets.

## Excercises

1.Using Poisson bracket show that the transformation defined by
$q=\sqrt{2 P} \sin Q$
$p=\sqrt{2 P} \cos Q$ is canonical.
$\mathrm{q}, \mathrm{p}$ can be rewritten as

$$
\begin{aligned}
\tan Q & =\frac{q}{p} \\
P & =\frac{1}{2}\left(q^{2}+p^{2}\right)
\end{aligned}
$$

If the transfomation is canonical, it must satisfy the conditions
$[Q, Q]=[P, P]=0$
and

$$
\begin{equation*}
[Q, P]=1 \tag{1}
\end{equation*}
$$

Already we know
$[Q, Q]=[P, P]=0$
Hence we can show that
$[Q, P]=1$ From eqn.(1)

$$
\begin{array}{rlc}
\sec ^{2} Q \frac{\partial Q}{\partial q} & =\frac{1}{p} & \sec ^{2} Q \frac{\partial Q}{\partial p}=\frac{-q}{p^{2}} \\
\frac{\partial P}{\partial q} & =q & \frac{\partial P}{\partial p}=p
\end{array}
$$

Then

$$
\begin{aligned}
{[Q, P] } & =\left(\frac{\partial Q}{\partial q} \frac{\partial P}{\partial p}-\frac{\partial Q}{\partial p} \frac{\partial P}{\partial q}\right) \\
& =\left\{\left(\frac{1}{p} \cos ^{2} Q\right) p+\left(\frac{q}{p^{2}} \cos ^{2} Q\right) q\right\} \\
& =\cos ^{2} Q\left(1+\frac{q^{2}}{\mathrm{ffl} p^{2}}\right) \\
& =\cos ^{2} Q\left(1+\tan ^{2} Q\right) \\
& =\cos ^{2} Q \times \sec ^{2} Q=1
\end{aligned}
$$

Hence the transformation is canonical.
2.Using Poisson bracket show that the transformation defined by

$$
\begin{gathered}
Q=e^{-q}\left(1-p^{2} e^{2 q}\right)^{1 / 2} \\
P=\tan ^{-1} \frac{e^{-q}\left(1-p^{2} e^{2 q}\right)^{1 / 2}}{p}
\end{gathered}
$$

is canonical.
Q and P can be rewritten as

$$
\begin{aligned}
Q & =e^{-q}\left(1-p^{2} e^{2 q}\right)^{1 / 2} \\
& =\left(e^{-2 q}-p^{2}\right)^{1 / 2}
\end{aligned}
$$

and

$$
P=\tan ^{-1} \frac{Q}{p}
$$

Now

$$
\begin{gathered}
\tan P=\frac{Q}{p} \\
1+\tan ^{2} P=1+\frac{Q^{2}}{p^{2}} \\
1+\tan ^{2} P=\frac{Q^{2}+p^{2}}{p^{2}} \\
\sec ^{2} P=\frac{Q^{2}+p^{2}}{p^{2}} \\
\begin{aligned}
\sec P=\frac{\sqrt{Q^{2}+p^{2}}}{p} \\
\cos P=\frac{p}{\sqrt{Q^{2}+p^{2}}} \\
=\frac{p}{\sqrt{e^{-2 q}-p^{2}+p^{2}}} \\
=\frac{p}{\sqrt{e^{-2 q}}} \\
=\frac{p}{e^{-q}} \\
=p e^{q} \\
P=\cos ^{-1}\left(p e^{q}\right)
\end{aligned}
\end{gathered}
$$

So now the transformation is

$$
\begin{aligned}
Q & =\left(e^{-2 q}-p^{2}\right)^{1 / 2} \\
P & =\cos ^{-1}\left(p e^{q}\right)
\end{aligned}
$$

Then

$$
\begin{aligned}
& \frac{\partial Q}{\partial q}=\frac{1}{2} \frac{\left(-e^{-2 q}\right)(-2)}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}=\frac{-e^{-2 q}}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}} \\
& \frac{\partial Q}{\partial p}=\frac{1}{2} \frac{(-2 p)}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}=\frac{-p}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}} \\
& \frac{\partial P}{\partial q}=\frac{-p e^{q}}{\left(1-p^{2} e^{2 q}\right)^{1 / 2}}=\frac{-p}{e^{-q}\left(1-p^{2} e^{2 q}\right)^{1 / 2}}=\frac{-p}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}} \\
& \frac{\partial P}{\partial p}=\frac{-e^{q}}{\left(1-p^{2} e^{2 q}\right)^{1 / 2}}=\frac{-1}{e^{-q}\left(1-p^{2} e^{2 q}\right)^{1 / 2}}=\frac{-1}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}
\end{aligned}
$$

Therefore

$$
\begin{array}{r}
{[Q, P]=\left(\frac{\partial Q}{\partial q} \frac{\partial P}{\partial p}-\frac{\partial Q}{\partial p} \frac{\partial P}{\partial q}\right)} \\
=\left\{\frac{-e^{-2 q}}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}\right\}\left\{\frac{-1}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}\right\} \\
-\left\{\frac{-p}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}\right\}\left\{\frac{-p}{\left(e^{-2 q}-p^{2}\right)^{1 / 2}}\right\} \\
=\frac{e^{-2 q}}{\left(e^{-2 q}-p^{2}\right)}-\frac{p^{2}}{\left(e^{-2 q}-p^{2}\right)} \\
=\frac{\left(e^{-2 q}-p^{2}\right)}{\left(e^{-2 q}-p^{2}\right)}=1
\end{array}
$$

Furthermore $[Q . Q]=0$ and $[P, P]=0$
Hence the transformation is canonical.

### 2.5 EQUATIONS OF MOTION IN POISSON'S BRACKET FORM :

The total time derivative of a dynamical variable $F\left(q_{j}, p_{j}, t\right)$ can be expressed as

$$
\dot{F}=[F, H]+\frac{\partial F}{\partial t}
$$

If F does not involve time t explicitly then

$$
\begin{equation*}
\dot{F}=[F, H] \tag{1}
\end{equation*}
$$

If the Poisson bracket of F with H vanishes then $F=$ constant of motion. This requirement does not however require that H should be a constant of motion. Suppose such dynamical variables are $q_{j}$ and $p_{j}$, then

$$
\dot{q}_{j}=\left[q_{j}, H\right]
$$

and

$$
\begin{equation*}
\dot{p_{j}}=\left[p_{j}, H\right] \tag{2}
\end{equation*}
$$

The above equations are identical with Hamilton's canonical equations of motion

$$
\left[q_{j}, H\right]=\sum_{i}\left[\frac{\partial q_{j}}{\partial H} \frac{\partial H}{\partial p_{i}}-\frac{\partial q_{j}}{\partial p_{i}} \frac{\partial H}{\partial q_{i}}\right]
$$

Since

$$
\frac{\partial q_{j}}{\partial p_{i}}=0
$$

we get

$$
\begin{aligned}
{\left[q_{j}, H\right] } & =\frac{\partial H}{\partial p_{i}} \delta_{i j} \\
& =\frac{\partial H}{\partial p_{j}}(\text { for } i=j)
\end{aligned}
$$

Therefore

$$
\dot{q}_{j}=\frac{\partial H}{\partial p_{j}}=\left[q_{j}, H\right]
$$

Similarly

$$
p_{j}=-\frac{\partial H}{\partial q_{j}}=\left[p_{j}, H\right]
$$

Equations (2) can thus be known as equations of motion inpoisson bracket form. If Poisson bracket $\left[p_{j}, H\right]$ vanishes, then

$$
\begin{aligned}
& \dot{p_{j}}=0 \\
& p_{j}=\text { constant }
\end{aligned}
$$

That is the linear momentum is conserved and hence the corresponding co-ordinate is cyclic. Thus all functions whose Poisson bracket with Hamiltonian vanish will be constants of motion and conversely Poisson brackets of all constants of motion with H must vanish.

### 2.6 JACOBI'S IDENTITY AND ITS DERIVATION :

$$
[X,[Y, Z]]+[Y,[Z, X]]+[Z,[X, Y]]=0
$$

We have

$$
\begin{array}{r}
{[X,[Y, Z]]=\frac{\partial[X, Y]}{\partial q_{j}} \frac{\partial Z}{\partial p_{j}}-\frac{\partial Z}{\partial q_{j}} \frac{\partial[X, Y]}{\partial p_{j}}} \\
=\frac{\partial}{\partial q_{j}}\left\{\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}-\frac{\partial Y}{\partial q_{j}} \frac{\partial X}{\partial p_{j}}\right\} \frac{\partial Z}{\partial p_{j}}-\frac{\partial Z}{\partial q_{j}} \frac{\partial}{\partial p_{j}}\left\{\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}-\frac{\partial Y}{\partial q_{j}} \frac{\partial X}{\partial p_{j}}\right\} \\
=\left\{\frac{\partial^{2} X}{\partial q_{j^{2}}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial X}{\partial q_{j}} \frac{\partial^{2} Y}{\partial q_{j} \partial p_{j}}-\frac{\partial^{2} Y}{\partial q_{j^{2}}} \frac{\partial X}{\partial p_{j}}-\frac{\partial Y}{\partial q_{j}} \frac{\partial^{2} X}{\partial q_{j}} \frac{\partial Z}{\partial p_{j}}\right\} \\
-\frac{\partial Z}{\partial q_{j}}\left\{\frac{\partial^{2} X}{\partial p_{j} \partial q_{j}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial Y}{\partial p_{j}^{2}} \frac{\partial X}{\partial q_{j}}-\frac{\partial^{2} Y}{\partial p_{j} \partial q_{j}} \frac{\partial X}{\partial p_{j}}-\frac{\partial^{2} X}{\partial p_{j}^{2}} \frac{\partial Y}{\partial q_{j}}\right\} \\
=\frac{\partial^{2} X}{\partial q_{j^{2}}} \frac{\partial Y}{\partial p_{j}} \frac{\partial Z}{\partial p_{j}}+\frac{\partial^{2} X}{\partial p_{j}^{2}} \frac{\partial X}{\partial q_{j}} \frac{\partial Z}{\partial q_{j}}-\left\{\frac{\partial^{2} Y}{\partial q_{j}{ }^{2}} \frac{\partial X}{\partial p_{j}} \frac{\partial Z}{\partial p_{j}}+\frac{\partial^{2} Y}{\partial p_{j^{2}}} \frac{\partial X}{\partial q_{j}} \frac{\partial Z}{\partial q_{j}}\right\} \\
-\frac{\partial^{2} X}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial Y}{\partial p_{j}} \frac{\partial Z}{\partial q_{j}}+\frac{\partial Y}{\partial q_{j}} \frac{\partial Z}{\partial q_{j}}\right\}+\frac{\partial^{2} Y}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial X}{\partial q_{j}} \frac{\partial Z}{\partial p_{j}}+\frac{\partial X}{\partial p_{j}} \frac{\partial Z}{f f \partial q_{j}}\right\}
\end{array}
$$

Similarly

$$
\begin{aligned}
{[[Z, X], Y]=} & \frac{\partial^{2} Z}{\partial q_{j^{2}}} \frac{\partial X}{\partial p_{j}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial^{2} Z}{\partial p_{j}^{2}} \frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial q_{j}}-\left\{\frac{\partial^{2} X}{\partial q_{j^{2}}} \frac{\partial Z}{\partial p_{j}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial^{2} X}{\partial p_{j^{2}}} \frac{\partial Z}{\partial q_{j}} \frac{\partial Y}{\partial q_{j}}\right\} \\
& -\frac{\partial^{2} Z}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial X}{\partial p_{j}} \frac{\partial Y}{\partial q_{j}}+\frac{\partial X}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}\right\}+\frac{\partial^{2} X}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial Z}{\partial q_{j}} \frac{\partial Y}{\partial p_{j}}+\frac{\partial Z}{\partial p_{j}} \frac{\partial Y}{\text { ff } \partial q_{j}}\right\} \\
{[[Y, Z], X]=} & \frac{\partial^{2} Y}{\partial q_{j}{ }^{2}} \frac{\partial Z}{\partial p_{j}} \frac{\partial X}{\partial p_{j}}+\frac{\partial^{2} Y}{\partial p_{j}^{2}} \frac{\partial Z}{\partial q_{j}} \frac{\partial X}{\partial q_{j}}-\left\{\frac{\partial^{2} Z}{\partial q_{j} 2} \frac{\partial Y}{\partial p_{j}} \frac{\partial X}{\partial p_{j}}+\frac{\partial^{2} Z}{\partial p_{j^{2}}} \frac{\partial Y}{\partial q_{j}} \frac{\partial X}{\partial q_{j}}\right\} \\
& -\frac{\partial^{2} Y}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial Z}{\partial p_{j}} \frac{\partial X}{\partial q_{j}}+\frac{\partial Z}{\partial q_{j}} \frac{\partial X}{\partial p_{j}}\right\}+\frac{\partial^{2} Z}{\partial p_{j} \partial q_{j}}\left\{\frac{\partial Y}{\partial q_{j}} \frac{\partial X}{\partial p_{j}}+\frac{\partial Y}{\partial p_{j}} \frac{\partial X}{\text { flo } q_{j}}\right\}
\end{aligned}
$$

Adding all we get

$$
[X,[Y, Z]]+[Y,[Z, X]]+[Z,[X, Y]]=0
$$

### 2.7 LAGRANGE'S BRACKETS AND ITS PROPERTIES:

Lagrange's bracket $u, v$ with respect to $\left(q_{j}, p_{j}\right)$ is defined as

$$
\begin{equation*}
\{u, v\}_{q, p}=\sum_{j}\left(\frac{\partial q_{j}}{\partial u} \frac{\partial p_{j}}{\partial v}-\frac{\partial p_{j}}{\partial u} \frac{\partial q_{j}}{\partial v}\right) \tag{1}
\end{equation*}
$$

(a) Lagrange bracket is invariant under canonical transformation :

Poincare's theorem states that the integral

$$
\begin{equation*}
J_{1}=\iint_{S} \sum_{j} d q_{j} d p_{j} \tag{2}
\end{equation*}
$$

taken over an arbitrary two dimensional surface $S$ of the $2 n$ dimensional ( $q, p$ ) phase space is invariant under canonical transformation.

Position of a point on any two dimensional surface is expressed as

$$
\begin{align*}
q_{j} & =q_{j}(u, v) \\
p_{j} & =p_{j}(u, v) \tag{3}
\end{align*}
$$

Transforming the integral (2) in terms of ( $u, v$ ), we write

$$
\begin{equation*}
d q_{j} d p_{j}=\frac{\partial\left(q_{j}, p_{j}\right)}{\partial(u, v)} d u d v \tag{4}
\end{equation*}
$$

with

$$
\frac{\partial\left(q_{j}, p_{j}\right)}{\partial(u, v)}=\left|\begin{array}{ll}
\frac{\partial q_{j}}{\partial u} & \frac{\partial p_{j}}{\partial u}  \tag{5}\\
\frac{\partial q_{j}}{\partial v} & \frac{\partial p_{j}}{\partial v}
\end{array}\right|
$$

as the Jacobian.
Further

$$
\begin{equation*}
\iint_{S} \sum_{j} d q_{j} d p_{j}=\iint_{S} \sum_{j} d Q_{j} d P_{j} \tag{6}
\end{equation*}
$$

where $\left(Q_{j}, P_{j}\right)$ is another set of canonical co-ordinates to which the $\operatorname{set}\left(q_{j}, p_{j}\right)$ has been transformed.
Now relation (6) becomes

$$
\iint_{S} \sum_{j} \frac{\partial\left(q_{j}, p_{j}\right)}{\partial(u, v)} d u d v=\iint_{S} \sum_{j} \frac{\partial\left(Q_{j}, P_{j}\right)}{\partial(u, v)} d u d v
$$

$S$ is arbitrary and area dudv is arbitrary. Therefore expressions on boyh the sides will be equal only when

$$
\begin{aligned}
\sum_{j} \frac{\partial\left(q_{j}, p_{j}\right)}{\partial(u, v)} & =\sum_{j} \frac{\partial\left(Q_{j}, P_{j}\right)}{\partial(u, v)} \\
\sum_{j}\left|\begin{array}{ll}
\frac{\partial q_{j}}{\partial u} & \frac{\partial p_{j}}{\partial u} \\
\frac{\partial q_{j}}{\partial v} & \frac{\partial p_{j}}{\partial v}
\end{array}\right| & =\sum_{j}\left|\begin{array}{ll}
\frac{\partial Q_{j}}{\partial u} & \frac{\partial P_{j}}{\partial u} \\
\frac{\partial Q_{j}}{\partial v} & \frac{\partial P_{j}}{\partial v}
\end{array}\right|
\end{aligned}
$$

or

$$
\begin{gather*}
\sum_{j}\left(\frac{\partial q_{j}}{\partial u} \frac{\partial p_{j}}{\partial v}-\frac{\partial p_{j}}{\partial u} \frac{\partial q_{j}}{\partial v}\right)=\sum_{j}\left(\frac{\partial Q_{j}}{\partial u} \frac{\partial P_{j}}{\partial v}-\frac{\partial P_{j}}{\partial u} \frac{\partial Q_{j}}{\partial v}\right) \\
\{u, v\}_{q, p}=\{u, v\}_{Q, P} \tag{7}
\end{gather*}
$$

Thus Lagrange's bracket is invariant under canonical transformation.
(b) Lagrange brackets do not obey the commutative law :

$$
\begin{align*}
\{u, v\} & =\sum_{j}\left(\frac{\partial q_{j}}{\partial u} \frac{\partial p_{j}}{\partial v}-\frac{\partial p_{j}}{\partial u} \frac{\partial q_{j}}{\partial v}\right) \\
& =-\sum_{j}\left(\frac{\partial p_{j}}{\partial u} \frac{\partial q_{j}}{\partial v}-\frac{\partial q_{j}}{\partial u} \frac{\partial p_{j}}{\partial v}\right) \\
& =-\sum_{j}\left(\frac{\partial q_{j}}{\partial v} \frac{\partial p_{j}}{\partial u}-\frac{\partial p_{j}}{\partial v} \frac{\partial q_{j}}{\partial u}\right) \\
& =\{v, u\} \tag{8}
\end{align*}
$$

(c) Proof: $\left\{q_{i}, q_{j}\right\}=0\left\{p_{i}, p_{j}\right\}=0 \quad\left\{q_{i}, q_{j}\right\}=\delta_{i j}$ :

$$
\begin{gather*}
\left\{q_{i}, q_{j}\right\}=0 \\
\left\{p_{i}, p_{j}\right\}=0 \\
\left\{q_{i}, q_{j}\right\}=\delta_{i j} \\
\left\{q_{i}, q_{j}\right\}=\sum_{k}\left(\frac{\partial q_{k}}{\partial q_{i}} \frac{\partial p_{k}}{\partial q_{j}}-\frac{\partial q_{k}}{\partial q_{j}} \frac{\partial p_{k}}{\partial q_{i}}\right) \tag{9}
\end{gather*}
$$

q's and p's are independent and hence

$$
\frac{\partial p_{k}}{\partial q_{j}}=0 \quad \text { and } \quad \frac{\partial p_{k}}{\partial q_{i}}=0
$$

Then

$$
\left\{q_{i}, q_{j}\right\}=0
$$

Similarly we can prove

$$
\begin{equation*}
\left\{p_{i}, p_{j}\right\}=0 \tag{10}
\end{equation*}
$$

Now

$$
\left\{q_{i}, p_{j}\right\}=\sum_{k}\left(\frac{\partial q_{k}}{\partial q_{i}} \frac{\partial p_{k}}{\partial p_{j}}-\frac{\partial q_{k}}{\partial p_{j}} \frac{\partial q_{k}}{\partial q_{i}}\right)
$$

q's and p's are independent and hence

$$
\frac{\partial q_{k}}{\partial p_{j}}=0
$$

Then

$$
\begin{equation*}
\left\{q_{i}, p_{j}\right\}=\sum_{k} \frac{\partial q_{k}}{\partial q_{i}} \frac{\partial p_{k}}{\partial p_{j}} \tag{11}
\end{equation*}
$$

We have

$$
\frac{\partial q_{k}}{\partial q_{i}}=\delta_{k i} \quad \text { and } \quad \frac{\partial p_{k}}{\partial p_{j}}=\delta_{k j}
$$

Hence

$$
\begin{align*}
\left\{q_{i}, p_{j}\right\}= & \sum_{k} \delta_{k i} \delta_{k j} \\
= & \delta_{i j} \tag{12}
\end{align*}
$$

### 2.8 RELATIONSHIP BETWEEN LAGRANGE AND POISSON BRACKET

We can show that

$$
\sum_{i=1}^{2 n}\left\{u_{l}, u_{i}\right\}\left[u_{l}, u_{j}\right]=\delta_{i j}
$$

Here $\left\{u_{l}, u_{i}\right\}$ is Lagrange bracket and $\left[u_{l}, u_{j}\right]$ is Poisson bracket. Now

$$
\begin{align*}
\sum_{l=1}^{2 n}\left\{u_{l}, u_{i}\right\}\left[u_{l}, u_{j}\right]= & \sum_{l=1}^{2 n}\left\{\sum_{k=1}^{n}\left(\frac{\partial q_{k}}{\partial u_{l}} \frac{\partial p_{k}}{\partial u_{i}}-\frac{\partial p_{k}}{\partial u_{l}} \frac{\partial q_{k}}{\partial u_{i}}\right)\right\} \\
& \left\{\sum_{m=1}^{n}\left(\frac{\partial u_{l}}{\partial q_{m}} \frac{\partial u_{j}}{\partial p_{m}}-\frac{\partial u_{l}}{\partial p_{m}} \frac{\partial u_{j}}{\partial q_{m}}\right)\right\} \tag{1}
\end{align*}
$$

The first four terms on R.H.S on multiplication is

$$
\begin{aligned}
\sum_{k, m=1^{n}} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{m}} \cdot \sum_{l=1}^{2 n} \frac{\partial q_{k}}{\partial u_{l}} \frac{\partial u_{l}}{\partial q_{m}} & =\sum_{k, m} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{m}} \cdot \frac{\partial q_{k}}{\partial q_{m}} \\
& =\sum_{k, m} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{m}} \cdot \delta_{k m}
\end{aligned}
$$

But

$$
\delta_{k m}=\frac{\partial p_{m}}{\partial p_{k}}
$$

The first four terms on R.H.S on multiplication is

$$
\sum_{k, m=1^{n}} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{m}} \cdot \sum_{l=1}^{2 n} \frac{\partial q_{k}}{\partial u_{l}} \frac{\partial u_{l}}{\partial q_{m}}=\sum_{k, m} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{m}} \cdot \frac{\partial p_{m}}{\partial p_{k}}
$$

$$
\begin{equation*}
=\sum_{k, m} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{k}} \tag{2}
\end{equation*}
$$

The last four terms will be

$$
\begin{align*}
\sum_{k, m=1^{n}} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{m}} \cdot \sum_{l=1}^{2 n} \frac{\partial p_{k}}{\partial u_{l}} \frac{\partial u_{l}}{\partial p_{m}} & =\sum_{k, m} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{m}} \cdot \frac{\partial p_{k}}{\partial p_{m}} \\
& =\sum_{k, m} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{m}} \cdot \delta_{k m} \\
& =\sum_{k, m} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{m}} \cdot \frac{\partial q_{m}}{\partial q_{k}} \\
& =\sum_{k, m} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{k}} \tag{3}
\end{align*}
$$

The second term is

$$
-\sum_{k, m=1^{n}} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{m}} \cdot \sum_{l=1}^{2 n} \frac{\partial q_{k}}{\partial u_{l}} \frac{\partial u_{l}}{\partial p_{m}}=0
$$

since

$$
\sum_{l=1}^{2 n} \frac{\partial q_{k}}{\partial u_{l}} \frac{\partial u_{l}}{\partial p_{m}}=\frac{\partial q_{k}}{\partial p_{m}}=0
$$

Similarly the third term will be zero.
Hence R.H.S of equation (1) is

$$
\begin{gather*}
\sum_{k} \frac{\partial p_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial p_{k}}+\sum_{k} \frac{\partial q_{k}}{\partial u_{i}} \frac{\partial u_{j}}{\partial q_{k}}=\sum_{k}\left(\frac{\partial u_{j}}{\partial p_{k}} \frac{\partial p_{k}}{\partial u_{i}}+\frac{\partial u_{j}}{\partial q_{k}} \frac{\partial q_{k}}{\partial u_{i}}\right) \\
=\frac{\partial u_{j}}{\partial u_{i}}\left(q_{k}, p_{k}\right) \\
=\frac{\partial u_{j}}{\partial u_{i}}=\delta_{i j} \tag{4}
\end{gather*}
$$

Therefore

$$
\sum_{i=1}^{2 n}\left\{u_{l}, u_{i}\right\}\left[u_{l}, u_{j}\right]=\delta_{i j}
$$

Which gives the relation between Lagrange and Poisson brackets.

### 2.9 THE ANGULAR MOMENTUM AND POISSON BRACKETS :

The angular momentum $\mathbf{l}$ can be expressed in terms of linear momentum $\mathbf{p}$ and radius vector $\mathbf{r}$ as

$$
\begin{gather*}
\mathbf{l}=\mathbf{r} \times \mathbf{p} \\
=(\mathbf{i} x+\mathbf{j} y+\mathbf{k} z) \times\left(\mathbf{i} p_{x}+\mathbf{j} p_{y}+\mathbf{k} p_{z}\right) \\
=\mathbf{i}\left(y p_{z}-z p_{y}\right)+\mathbf{j}\left(z p_{x}-x p_{z}\right)+\mathbf{k}\left(x p_{y}-y p_{x}\right) \tag{1}
\end{gather*}
$$

giving

$$
\begin{array}{lll}
l_{x}=y p_{z}-z p_{y} ; & l_{y}=z p_{x}-x p_{z} ; & l_{z}=x p_{y}-y p_{x} \\
\frac{\partial l_{x}}{\partial p_{x}}=0 & \frac{\partial l_{y}}{\partial p_{x}}=z & \frac{\partial l_{z}}{\partial p_{x}}=-y \\
\frac{\partial l_{x}}{\partial p_{y}}=-z & \frac{\partial l_{y}}{\partial p_{y}}=0 & \frac{\partial l_{z}}{\partial p_{y}}=x \\
\frac{\partial l_{x}}{\partial p_{z}}=y & \frac{\partial l_{y}}{\partial p_{z}}=-x & \frac{\partial l_{z}}{\partial p_{z}}=0 \tag{2}
\end{array}
$$

We know that

$$
\begin{aligned}
{\left[F, p_{j}\right] } & =\sum_{k}\left(\frac{\partial F}{\partial q_{k}} \frac{\partial p_{j}}{\partial p_{k}}-\frac{\partial F}{\partial p_{k}} \frac{\partial p_{j}}{\partial q_{k}}\right) \\
& =\frac{\partial F}{\partial q_{j}} \quad(\text { for } \quad j=k)
\end{aligned}
$$

so that

$$
\begin{array}{lll}
{\left[l_{x}, p_{x}\right]=\frac{\partial l_{x}}{\partial x}=0} & {\left[l_{y}, p_{x}\right]=\frac{\partial l_{y}}{\partial x}=-p_{z}} & {\left[l_{z}, p_{x}\right]=\frac{\partial l_{z}}{\partial x}=p_{y}} \\
{\left[l_{x}, p_{y}\right]=\frac{\partial l_{x}}{\partial y}=p_{z}} & {\left[l_{y}, p_{y}\right]=\frac{\partial l_{y}}{\partial y}=0} & {\left[l_{z}, p_{y}\right]=\frac{\partial l_{z}}{\partial y}=-p_{x}} \\
{\left[l_{x}, p_{z}\right]=\frac{\partial l_{x}}{\partial z}=-p_{y}} & {\left[l_{y}, p_{z}\right]=\frac{\partial l_{y}}{\partial z}=p_{x}} & {\left[l_{z}, p_{z}\right]=\frac{\partial l_{z}}{\partial z}=0} \tag{3}
\end{array}
$$

Equations (2) and (3) give Poisson brackets of angular and linear momentum components.
We know that

$$
\left[p_{j}, p_{x}\right]=0
$$

Therefore

$$
\begin{equation*}
\left[p_{x}, p_{y}\right]=\left[p_{y}, p_{z}\right]=\left[p_{z}, p_{x}\right]=0 \tag{4}
\end{equation*}
$$

Now we find out the Poisson bracket of components of 1

$$
\begin{gathered}
{\left[l_{x}, l_{y}\right]=\sum_{k}\left(\frac{\partial l_{x}}{\partial q_{k}} \frac{\partial l_{y}}{\partial p_{k}}-\frac{\partial l_{x}}{\partial p_{k}} \frac{\partial l_{y}}{\partial q_{k}}\right)} \\
=\left(\frac{\partial l_{x}}{\partial x} \frac{\partial l_{y}}{\partial p_{x}}-\frac{\partial l_{x}}{\partial p_{x}} \frac{\partial l_{y}}{\partial x}\right)+\left(\frac{\partial l_{x}}{\partial y} \frac{\partial l_{y}}{\partial p_{y}}-\frac{\partial l_{x}}{\partial p_{y}} \frac{\partial l_{y}}{\partial y}\right)+\left(\frac{\partial l_{x}}{\partial z} \frac{\partial l_{y}}{\partial p_{z}}-\frac{\partial l_{x}}{\partial p_{z}} \frac{\partial l_{y}}{\partial z}\right)
\end{gathered}
$$

Using equations (2) and (3), we get

$$
\begin{gathered}
{\left[l_{x}, l_{y}\right]=0-0+0-0+\left(-p_{y}\right)(-x)-(y)\left(p_{x}\right)} \\
=\left(x p_{x}-y p_{x}\right)=l_{z}
\end{gathered}
$$

Similarly we can prove

$$
\left[l_{y}, l_{z}\right]=l_{x}
$$

and

$$
\left[l_{z}, l_{x}\right]=l_{y}
$$

### 2.10 LIOUVILLE'S THEOREM :

The theorem consists of two parts
(1) The first part states the conservation of density in phase space

$$
\text { i.e } \frac{d \rho}{d t}=0
$$

2) The second part states the conservation of extension in phase space

$$
\text { i.e } \frac{d}{d t}(\delta \Gamma)=0
$$

## (1) First Part :

Consider any fixed element of volume of phase space located between $q_{1}$ and $q_{1}+\delta q_{1}, \ldots q_{f}$ and $q_{f}+\delta q_{f}, p_{1}$ and $p_{1}+\delta p_{1}, \ldots p_{f}$ and $p_{f}+\delta p_{f}$.
If $\rho$ is the density of phase points, the number of phase points in this volume element at any instant t is
$\delta N=\rho . \delta \Gamma=\rho\left(\delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f}\right)$


The number of phase points located in the volume ( $\left.\delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f}\right)$ changes as the coordinates and momenta vary. The change in the number of phase points within this volume of phase space in time dt is

$$
\frac{d(\delta N)}{d t}=\frac{d(\rho . \delta \Gamma)}{d t}=\frac{d \rho}{d t} d t\left(\delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f}\right)
$$

This change is due to the number of phase points entering and leaving this volume in time dt.

Consider two faces of hypervolume normal to the q -axis with coordinates $q_{1}$ and $q_{1}+\delta q_{1}$. Number of phase points entering the first phase in time dt is

$$
\begin{equation*}
\rho \dot{q}_{1} d t \delta q_{2} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{1}
\end{equation*}
$$

$\rho$ and $\dot{q}_{1}$ are the density and velocity component at $\left(q_{1} \ldots q_{f} ; p_{1} \ldots p_{f}\right)$
Number of phase points entering the second phase in time dt is

$$
\begin{equation*}
\left(\rho+\frac{\partial \rho}{\partial q_{1}} \delta q_{1}\right)\left(\dot{q}_{1}+\frac{\partial \dot{q}_{1}}{\partial q_{1}} \delta q_{1}\right) d t \delta q_{2} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{2}
\end{equation*}
$$

Neglecting higher order terms we have

$$
\begin{equation*}
\left[\rho \dot{q}_{1}+\left(\rho \frac{\partial \dot{q}_{1}}{\partial q_{1}}+\dot{q}_{1} \frac{\partial \rho}{\delta q_{1}}\right) \delta q_{1}\right] d t \delta q_{2} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{3}
\end{equation*}
$$

Eqn(1)-Eqn(3) gives

$$
\begin{equation*}
-\left(\rho \frac{\partial \dot{q}_{1}}{\partial q_{1}}+\dot{q}_{1} \frac{\partial \rho}{\delta q_{1}}\right) d t \delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{4}
\end{equation*}
$$

Similarly for $p_{1}$ co-ordinate

$$
\begin{equation*}
-\left(\rho \frac{\partial \dot{p_{1}}}{\partial p_{1}}+\dot{p_{1}} \frac{\partial \rho}{\delta p_{1}}\right) d t \delta p_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{5}
\end{equation*}
$$

The net increase in the number of phase points in time dt is in this volume of phase space is obtained by summing the net number of phase points entering the volume through all the faces labelled by $q_{1} \ldots q_{f}$ and $p_{1} \ldots p_{f}$. Hence

$$
\begin{equation*}
\frac{d}{d t}(\delta N)=-\sum_{j=1}^{f}\left\{\rho\left(\frac{\partial \dot{q}_{j}}{\partial q_{j}}+\frac{\partial \dot{p}_{j}}{\partial p_{j}}\right)+\left(\frac{\partial \rho}{\partial q_{j}} \dot{q}_{j}+\frac{\partial \rho}{\partial p_{j}} \dot{p}_{j}\right)\right\} d t \delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \tag{6}
\end{equation*}
$$

Already we have seen that

$$
\frac{d}{d t}(\delta N)=\frac{\partial \rho}{\partial t} d t \delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f}
$$

and hence

$$
\begin{gather*}
\frac{\partial \rho}{\partial t} d t \delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \\
=-\sum_{j=1}^{f}\left\{\rho\left(\frac{\partial \dot{q}_{j}}{\partial q_{j}}+\frac{\partial \dot{p}_{j}}{\partial p_{j}}\right)+\left(\frac{\partial \rho}{\partial q_{j}} \dot{q}_{j}+\frac{\partial \rho}{\partial p_{j}} \dot{p}_{j}\right)\right\} d t \delta q_{1} \ldots \delta q_{f} \delta p_{1} \ldots \delta p_{f} \\
\frac{\partial \rho}{\partial t}=-\sum_{j=1}^{f}\left\{\rho\left(\frac{\partial \dot{q}_{j}}{\partial q_{j}}+\frac{\partial \dot{p}_{j}}{\partial p_{j}}\right)+\left(\frac{\partial \rho}{\partial q_{j}} \dot{q}_{j}+\frac{\partial \rho}{\partial p_{j}} \dot{p}_{j}\right)\right\} \tag{7}
\end{gather*}
$$

The equations of motion in canonical form are

$$
\dot{q}_{j}=\frac{\partial H}{\partial p_{j}} \quad \text { and } \quad \dot{p}_{j}=-\frac{\partial H}{\partial q_{j}}
$$

Now

$$
\begin{aligned}
\frac{\partial \dot{q}_{j}}{\partial q_{j}} & =\frac{\partial^{2} H}{\partial q_{j} \partial p_{j}} \\
\frac{\partial \dot{p}_{j}}{\partial p_{j}} & =-\frac{\partial^{2} H}{\partial p_{j} \partial q_{j}}
\end{aligned}
$$

The order of differentian is immaterial and hence

$$
\begin{equation*}
\sum_{j=1}^{f}\left(\frac{\partial \dot{q}_{j}}{\partial q_{j}}+\frac{\partial \dot{p}_{j}}{\partial p_{j}}\right)=0 \tag{8}
\end{equation*}
$$

Now Eqn(7) becomes

$$
\begin{align*}
& \left(\frac{\partial \rho}{\partial t}\right)_{q, p}=-\sum_{j=1}^{f}\left(\frac{\partial \rho}{\partial q_{j}} \dot{q}_{j}+\frac{\partial \rho}{\partial p_{j}} \dot{p}_{j}\right)  \tag{9}\\
& \left(\frac{\partial \rho}{\partial t}\right)_{q, p}+\sum_{j=1}^{f}\left(\frac{\partial \rho}{\partial q_{j}} \dot{q}_{j}+\frac{\partial \rho}{\partial p_{j}} \dot{p}_{j}\right)=0 \tag{10}
\end{align*}
$$

This result is known as Liouville's theorem. This equation is identical with the equation of continuity in hydrodynamics.

If $\rho$ is a function of $q, p$ and $t$ and $q, p$ are functions of $t$, then

$$
\frac{d \rho}{d t}=\frac{\partial \rho}{\partial t}+\frac{\partial \rho}{\partial q} \frac{d q}{d t}+\frac{\partial \rho}{\partial p} \frac{d p}{d t}
$$

On generalization we get

$$
\begin{equation*}
\frac{d \rho}{d t}=\frac{\partial \rho}{\partial t}+\sum_{j}^{f} \frac{\partial \rho}{\partial q_{j}} \frac{d q_{j}}{d t}+\sum_{j}^{f} \frac{\partial \rho}{\partial p_{j}} \frac{d p_{j}}{d t} \tag{11}
\end{equation*}
$$

Comparing eqns (10) and (11) we get

$$
\frac{d \rho}{d t}=0
$$

This form is called the principle of the conservation of density in phase space.

## (2) Second Part :

Here we have to prove that

$$
\frac{d}{d t}(\delta \Gamma)=0
$$

We know

$$
\delta N=\rho \delta \Gamma
$$

Now

$$
\begin{equation*}
\frac{d}{d t}(\delta N)=\frac{d \rho}{d t} \delta \Gamma+\rho \frac{d}{d t}(\delta \Gamma) \tag{12}
\end{equation*}
$$

The number of phase points $\delta N$ in a given region must remain fixed.

$$
\frac{d}{d t}(\delta N)=0
$$

$$
\begin{equation*}
\frac{d \rho}{d t} \delta \Gamma+\rho \frac{d}{d t}(\delta \Gamma)=0 \tag{13}
\end{equation*}
$$

Already we have proved that

$$
\frac{d \rho}{d t}=0
$$

It follows that

$$
\begin{equation*}
\rho \frac{d}{d t}(\delta \Gamma)=0 \tag{14}
\end{equation*}
$$

But $\rho \neq 0$, we get

$$
\begin{equation*}
\frac{d}{d t}(\delta \Gamma)=0 \tag{15}
\end{equation*}
$$

This equation gives the principle of conservation of extension in phase space.

## Excercises :

1.If the transformation eqations between two sets of co-ordinates are

$$
\begin{aligned}
& P=2\left(1+q^{1 / 2} \cos p\right) q^{1 / 2} \sin p \\
& Q=\log \left(1+q^{1 / 2} \cos p\right)
\end{aligned}
$$

then show that (i) the transformation is canonical and (ii)the generating function of this transformation is

$$
F_{3}=-\left(e^{Q}-1\right)^{2} \tan p
$$

## Solution :

(i) For the trasformation to be canonical $(p d q-P d Q)$ must be an exact differential.

$$
\begin{aligned}
& p d q-P d Q=p d q-2\left(1+q^{1 / 2} \cos p\right) q^{1 / 2} \sin p \cdot \frac{q^{1 / 2}(-\sin p d p)+\cos p\left(\frac{1}{2} q^{-1 / 2} d q\right)}{\left(1+q^{1 / 2} \cos p\right)} \\
& \begin{aligned}
& p d q-P d Q=p d q-2\left(1+q^{1 / 2} \cos p\right) q^{1 / 2} \sin p \cdot \frac{q(-\sin p d p)+\cos p\left(\frac{1}{2} d q\right)}{q^{1 / 2}\left(1+q^{1 / 2} \cos p\right)} \\
&=p d q+2 q \sin ^{2} p d p-\sin p \cos p d q \\
&=p d q+q(1-\cos 2 p) d p-\left(\frac{1}{2} \sin 2 p d q\right) \\
&=\left(p-\frac{1}{2} \sin 2 p\right) d q+q(1-\cos 2 p) d p
\end{aligned}
\end{aligned}
$$

$$
\begin{aligned}
= & \frac{\partial}{\partial q}\left[q\left(p-\frac{1}{2} \sin 2 p\right)\right] d q+\frac{\partial}{\partial p}\left[q\left(p-\frac{1}{2} \sin 2 p\right)\right] d p \\
& =d\left[q\left(p-\frac{1}{2} \sin 2 p\right)\right] \\
& =\text { an exact differential }
\end{aligned}
$$

(ii) We have

$$
\begin{gather*}
Q=\log \left(1+q^{1 / 2} \cos p\right) \\
e^{Q}=\left(1+q^{1 / 2} \cos p\right) \\
e^{Q}-1=q^{1 / 2} \cos p \\
q^{1 / 2}=\frac{e^{Q}-1}{\cos p} \\
q=\frac{\left(e^{Q}-1\right)^{2}}{(\cos p)^{2}} \tag{1}
\end{gather*}
$$

Now

$$
\begin{align*}
P & =2\left(1+q^{1 / 2} \cos p\right) q^{1 / 2} \sin p \\
& =2 e^{Q} \frac{\left(e^{Q}-1\right)}{\cos p} \sin p \\
& =2 e^{Q}\left(e^{Q}-1\right) \tan p \tag{2}
\end{align*}
$$

We know that

$$
\begin{aligned}
q & =-\frac{\partial F_{3}}{\partial p} \\
P & =-\frac{\partial F_{3}}{\partial Q}
\end{aligned}
$$

Now

$$
\begin{align*}
\frac{\partial F_{3}}{\partial p} & =-\frac{\left(e^{Q}-1\right)^{2}}{\cos ^{2} p}=-\left(e^{Q}-1\right)^{2} \sec ^{2} p  \tag{3}\\
\frac{\partial F_{3}}{\partial Q} & =-2 e^{Q}\left(e^{Q}-1\right) \tan p \tag{4}
\end{align*}
$$

Integrating eqn(3) we get

$$
F_{3}=-\int\left(e^{Q}-1\right)^{2} \sec ^{2} p d p+\text { constant }
$$

Taking the constant of integration to be zero we get

$$
\begin{equation*}
F_{3}=-\left(e^{Q}-1\right)^{2} \tan p \tag{5}
\end{equation*}
$$

Integrating eqn(4) we get

$$
F_{3}=2 \int e^{Q}\left(e^{Q}-1\right) \tan p d Q
$$

Again taking the constant of integration to be zero we get

$$
\begin{equation*}
F_{3}=-\left(e^{Q}-1\right)^{2} \tan p \tag{6}
\end{equation*}
$$

Since

$$
\text { Equation }(5)=\text { Equation }(6)
$$

means $F_{3}$ is the generator of the given transformation.
2.Show that the generating function for the transformation

$$
p=\frac{1}{Q}, \quad p=P Q^{2}
$$

is

$$
F=\frac{q}{Q}
$$

## Solution :

$$
p=\frac{1}{Q}, \quad p=P Q^{2}
$$

We find

$$
\begin{aligned}
p d q & =\frac{1}{Q}\left(2 P Q d Q+Q^{2} d P\right) \\
& =2 P d Q+Q d P
\end{aligned}
$$

Now

$$
\begin{aligned}
p d q-P d Q & =2 P d Q+Q d P-P d Q \\
& =P d Q+Q d P \\
& =\frac{\partial}{\partial Q}(P Q) d Q+\frac{\partial}{\partial P}(P Q) d P \\
& =\frac{\partial F}{\partial Q} d Q+\frac{\partial F}{\partial P} d P
\end{aligned}
$$

$$
\begin{aligned}
& =d F \\
& =\text { an exact differential }
\end{aligned}
$$

The generating function is

$$
F=P Q
$$

But generating function involves both sets of co-ordinates. As

$$
P=\frac{q}{Q^{2}}
$$

we have

$$
\begin{aligned}
F & =\frac{q}{Q^{2}} Q \\
& =\frac{q}{Q}
\end{aligned}
$$

Hence the result.

## THEORY OF SMALL OSCILLATIONS :

### 2.11 FORMULATION OF THE PROBLEM :EIGEN VALUE EQUATION :

Consider a system with n degrees of freedom and whose total energy is conserved.Suppose the system is in an equilibrium stste at the point having the co-ordinates $q_{01}, q_{02} \ldots q_{0 n}$. Thus the potential energy satisfies the condition

$$
\left(\frac{\partial V}{\partial q_{j}}\right)_{q=q_{0}}=0
$$

Here $q=q_{0}$ represents $q_{j}=q_{0 j}$ for all values of j . let $\eta_{j}$ denotes a small displacement in the corresponding co-ordinate $q_{j}$ from the equilibrim position. Sothat

$$
q_{j}=q_{0 j}+\eta_{j}
$$

with $\mathrm{j}=1,2, \ldots$ n
Now the potential energy becomes

$$
\begin{align*}
V\left(q_{1}, q_{2}, \ldots q_{n}\right) & =V\left(q_{01}+\eta_{1}, q_{02}+\eta_{2}, \ldots q_{0 n}+\eta_{n}\right) \\
& =V\left(q_{01}, q_{02}, \ldots q_{0 n}\right)+\sum_{j=1}^{n} \eta_{j}\left(\frac{\partial V}{\partial q_{j}}\right)_{q=q_{0}} \\
& +\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} \eta_{j} \eta_{k}\left(\frac{\partial^{2} V}{\partial q_{j} \partial q_{k}}\right)_{q=q_{0}}+\ldots \tag{1}
\end{align*}
$$

The departure from the equilibrium position is small and we truncate the series after the first non-vanishing term in $\eta_{j}$.
The first term on the R.H.S is constant, the second term is zero and we consider upto the third term.

The first term gives the shift the reference of potential energy to the equilibrium point. Thus the equation (1) becomes

$$
\begin{align*}
V\left(q_{1}, q_{2}, \ldots q_{n}\right) & =\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n}\left(\frac{\partial^{2} V}{\partial q_{j} \partial q_{k}}\right)_{q=q_{0}} \eta_{j} \eta_{k} \\
& =\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} V_{j k} \eta_{j} \eta_{k} \tag{2}
\end{align*}
$$

Where

$$
V_{j k}=\left(\frac{\partial^{2} V}{\partial q_{j} \partial q_{k}}\right)_{q=q_{0}}
$$

Here $V_{j k}=V_{k j}$. For the stable equilibrium, the potential energy should be minimum at the equilibrium position and hence $V_{j k}$ must be positive. The kinetic energy of the system is

$$
T=\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} c_{j k} \dot{q}_{j} \dot{q}_{k}=\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} c_{j k} \dot{\eta_{j}} \dot{\eta}_{k}
$$

$c_{j k}$ be the functions of the co-ordinates $q_{j}$ 's and we can expand in Taylor series form about the equilibrium position :

$$
\begin{aligned}
c_{j k}\left(q_{1}, q_{2}, \ldots q_{n}\right) & =c_{j k}\left(q_{01}+\eta_{1}, q_{02}+\eta_{2}, \ldots q_{0 n}+\eta_{n}\right) \\
& =c_{j k}\left(q_{01}, q_{02}, \ldots q_{0 n}\right)+\sum_{j=1}^{n} \eta_{j}\left(\frac{\partial c_{j k}}{\partial q_{j}}\right)_{q=q_{0}}+\ldots
\end{aligned}
$$

T has the terms of second order in $\eta$ 's and we retain only the zeroth order term. Thus we have

$$
c_{j k}\left(q_{1}, q_{2}, \ldots q_{n}\right)=c_{j k}\left(q_{01}, q_{02}, \ldots q_{0 n}\right)=T_{j k}
$$

and the kinetic energy is

$$
\begin{equation*}
T=\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} T_{j k} \dot{\eta_{j}} \dot{\eta}_{k} \tag{3}
\end{equation*}
$$

Here $T_{j k}=T_{k j}$.Using eqns (2) and (3) the Lagrangian of the system is

$$
L=\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} T_{j k} \dot{\eta_{j}} \dot{\eta_{k}}-\frac{1}{2} \sum_{j=1}^{n} \sum_{k=1}^{n} V_{j k} \eta_{j} \eta_{k}
$$

The Lagrangian equations of mtion are

$$
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\eta}_{j}}\right)-\frac{\partial L}{\partial \eta_{j}}=0
$$

where $\mathrm{j}=1,2, \ldots \mathrm{n}$. Therefore we have

$$
\begin{equation*}
\sum_{k=1}^{n}\left(T_{j k} \ddot{\eta}_{k}+V_{j k} \eta_{k}\right)=0 \tag{4}
\end{equation*}
$$

where $\mathrm{j}=1,2, \ldots \mathrm{n}$.Equation (4) can be expressed in the matrix form

$$
\left[\begin{array}{cccc}
T_{11} & T_{12} & \ldots & T_{1 n} \\
T_{12} & T_{22} & \ldots & T_{2 n} \\
\ldots & \ldots & \ldots & \ldots \\
T_{1 n} & T_{2 n} & \ldots & T_{n n}
\end{array}\right]\left[\begin{array}{c}
\ddot{\eta}_{1} \\
\ddot{\eta}_{2} \\
\ldots \\
\ddot{\eta}_{n}
\end{array}\right]+\left[\begin{array}{cccc}
V_{11} & V_{12} & \ldots & V_{1 n} \\
V_{12} & V_{22} & \ldots & V_{2 n} \\
\ldots & \ldots & \ldots & \ldots \\
V_{1 n} & V_{2 n} & \ldots & V_{n n}
\end{array}\right]\left[\begin{array}{c}
\eta_{1} \\
\eta_{2} \\
\ldots \\
\eta_{n}
\end{array}\right]=\left[\begin{array}{c}
0 \\
0 \\
\ldots \\
0
\end{array}\right]
$$

or

$$
T \ddot{\eta}+V \eta=0
$$

Here T and V represent the square matrices of order $n \times n$. Both of these matrices are real as well as symmetric.Each of the $n$ equations (4) involves all the $n$ variables and can be simplified by transforming them into another set of $n$ equations each of which involves only one variable. This is possible with the help of the normal co-ordinates and normal frequencies.Let us try the oscillatory solutions of the form

$$
\begin{equation*}
\eta_{k}=A_{k} e^{i \omega t} \tag{5}
\end{equation*}
$$

here $\omega$ is the frequency of oscillations. The real part $A_{k} \cos \omega t$ corresponds to the actual motion. Using eqn (5) in (4) we get

$$
\begin{equation*}
\sum_{k=1}^{n}\left(V_{j k}-\omega^{2} T_{j k}\right) A_{k}=0 \tag{6}
\end{equation*}
$$

where $\mathrm{j}=1,2, \ldots \mathrm{n}$. Thus we have

$$
\left[\begin{array}{cccc}
V_{11}-\omega^{2} T_{11} & V_{12}-\omega^{2} T_{12} & \ldots & V_{1 n}-\omega^{2} T_{1 n} \\
V_{21}-\omega^{2} T_{21} & V_{22}-\omega^{2} T_{22} & \ldots & V_{2 n}-\omega^{2} T_{2 n} \\
\ldots & \ldots & \ldots & \ldots \\
V_{n 1}-\omega^{2} T_{n 1} & V_{n 2}-\omega^{2} T_{22} & \ldots & V_{n n}-\omega^{2} T_{2 n}
\end{array}\right]\left[\begin{array}{c}
A_{1} \\
A_{2} \\
\ldots \\
A_{n}
\end{array}\right]=\left[\begin{array}{c}
0 \\
0 \\
\ldots \\
0
\end{array}\right]
$$

This set of equations has anon-trivial solution when

$$
\left|\begin{array}{cccc}
V_{11}-\omega^{2} T_{11} & V_{12}-\omega^{2} T_{12} & \ldots & V_{1 n}-\omega^{2} T_{1 n}  \tag{7}\\
V_{21}-\omega^{2} T_{21} & V_{22}-\omega^{2} T_{22} & \ldots & V_{2 n}-\omega^{2} T_{2 n} \\
\ldots & \ldots & \ldots & \ldots \\
V_{n 1}-\omega^{2} T_{n 1} & V_{n 2}-\omega^{2} T_{22} & \ldots & V_{n n}-\omega^{2} T_{2 n}
\end{array}\right|=0
$$

This equation is known as the secular or characteristic equation.
Equation (7) may also be wrtten as

$$
\left(V A-\omega^{2} T A\right)=0
$$

called eigen value equation. Here A is a column matrix of n components:

$$
A=\left[\begin{array}{c}
A_{1} \\
A_{2} \\
\ldots \\
A_{n}
\end{array}\right]
$$

Expansion of this determinant of order $n \times n$ gives a polynomial of degree n in $\omega^{2}$. This polynomial has roots $\omega_{1}^{2}, \omega_{2}^{2}, \ldots \omega_{n}^{2}$ which are the characteristic or eigen frequencies of the system. These frequencies are known as the normal frequencies of the system. The eigen values are real as they correspond to a real symmetric matrix. For each of these frequencies equation (6) can be solved to get the eigen function $A_{k}$
To distinguish between various modes, let us put the suffix land then the eigen function is $A_{k l}$ and the frequency eigen value is $\omega_{l}$. Then a general solution for the displacement $\eta_{k}$ consists of a linear combination of all the modes ;

$$
\eta_{k}=A_{k 1} e^{i \omega_{1} t}+A_{k 2} e^{i \omega_{2} t}+\ldots+A_{k n} e^{i \omega_{n} t}=\sum_{l=1}^{n} A_{k l} e^{i \omega_{l} t}
$$

Each mode associated with an eigen frequency is known as the principal or natural mode.Each of the normal frequencies must be real.The eigen functions corresponding to different eigen values must be orthogonal to each other. Thus we have

$$
\sum_{k=1}^{n} A_{k l} A_{k l^{\prime}}=\delta_{l l^{\prime}}
$$

### 2.12 PRINCIPAL AXES TRANSFORMATION ;

We can choose a certain system of body axes with respect to which the off-diagonal elements should disappear and only the diagonal elements remain in the expression for $\mathbf{I}$. Such axes are called principal axes of transformation. The corresponding moments of inertia are called principal moments of inertia.
if we denote this form of inertia tensor by $\mathbf{I}^{\prime}$ and $I_{1}, I_{2}, I_{3}$ stand for the principal values,

$$
\mathbf{I}^{\prime}=\left[\begin{array}{lll}
I_{1} & 0 & 0  \tag{1}\\
0 & I_{2} & 0 \\
0 & 0 & I_{3}
\end{array}\right]
$$

where we have denoted $I_{x^{\prime} x^{\prime}}=I_{1}, I_{y^{\prime} y^{\prime}}=I_{2}, I_{z^{\prime} z^{\prime}}=I_{3}$. If $\omega_{x}, \omega_{y}, \omega_{z}$ are the components of angular velocity and $L_{x}, L_{y}, L_{z}$ are the angular momentum about the principal axes, then

$$
\begin{aligned}
{\left[\begin{array}{l}
L_{x} \\
L_{y} \\
L_{z}
\end{array}\right] } & =\left[\begin{array}{lll}
I_{1} & 0 & 0 \\
0 & I_{2} & 0 \\
0 & 0 & I_{3}
\end{array}\right]\left[\begin{array}{l}
\omega_{x} \\
\omega_{y} \\
\omega_{z}
\end{array}\right] \\
& =\left[\begin{array}{l}
I_{1} \omega_{x}+0+0 \\
0+I_{2} \omega_{y}+0 \\
0+0+I_{3} \omega_{z}
\end{array}\right]
\end{aligned}
$$

or

$$
\begin{align*}
L_{x} & =I_{1} \omega_{x} \\
L_{y} & =I_{2} \omega_{y} \\
L_{z} & =I_{3} \omega_{x} \tag{2}
\end{align*}
$$

That is each of angular momentum component along a principal axis is a function of corresponding angular velocity component only related to it through the principal moment of inertia about that direction.

Thus in general if a rigid body is rotating about a principal axis, the angular momentum $\mathbf{L}$ and $\omega$ are directed along any of the principal axes and therefore

$$
\mathbf{L}=\mathbf{I} \omega
$$

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where $I$ is the scalar, the moment of inertia about this axis. The angular momentum $\mathbf{L}$ and angular velocity $\omega$ are along the principal axes and hence

$$
\mathbf{L}=L_{x} \widehat{\mathbf{i}}+L_{y} \widehat{\mathbf{j}}+L_{z} \widehat{\mathbf{k}}=I\left(\omega_{x} \widehat{\mathbf{i}}+\omega_{y} \widehat{\mathbf{j}}+\omega_{z} \widehat{\mathbf{k}}\right)
$$

where $\widehat{\mathbf{i}}, \widehat{\mathbf{j}}, \widehat{\mathbf{k}}$ are unit vectors along $X, Y, Z$ axes respectively.
Thus

$$
\begin{equation*}
L_{x}=I \omega_{x}, L_{y}=I \omega_{y}, L_{z}=I \omega_{z} \tag{3}
\end{equation*}
$$

using the symmetry property of inertia tensor we get

$$
\begin{aligned}
L_{x} & =I_{x x} \omega_{x}+I_{x y} \omega_{y}+I_{x z} \omega_{z}=I \omega_{x} \\
L_{y} & =I_{y x} \omega_{x}+I_{y y} \omega_{y}+I_{y z} \omega_{z}=I \omega_{y} \\
L_{z} & =I_{z x} \omega_{x}+I_{z y} \omega_{y}+I_{z z} \omega_{z}=I \omega_{z}
\end{aligned}
$$

or

$$
\left[\begin{array}{ccc}
I_{x x}-I & I_{x y} & I_{x z}  \tag{4}\\
I_{y x} & I_{y y}-I & I_{y z} \\
I_{z x} & I_{z y} & I_{z z}-I
\end{array}\right]\left[\begin{array}{l}
\omega_{x} \\
\omega_{y} \\
\omega_{z}
\end{array}\right]=0
$$

For these equations to have non-trivial solutions, the determinant of the coefficients must vanish. That is

$$
\left|\begin{array}{ccc}
I_{x x}-I & I_{x y} & I_{x z}  \tag{5}\\
I_{y x} & I_{y y}-I & I_{y z} \\
I_{z x} & I_{z y} & I_{z z}-I
\end{array}\right|=0
$$

This is called secular equation of inertia and its solutions the secular values or eigenvalues. We solve the determinantal equation which will be cubic in $\mathbf{I}$ and therefore will furnish three values for $\mathbf{I}$ through $I_{1}, I_{2}, I_{3}$ which are desired principal moments of inertia :

The direction of any one principal axis is determined by substituting for $I=I_{1}$ and determine the ratios for $\omega_{x}: \omega_{y}: \omega_{z}$ as

$$
\frac{\omega_{y}}{\omega_{x}}=\lambda_{1}, \frac{\omega_{z}}{\omega_{x}}=\lambda_{2}
$$

Thus

$$
\omega=\omega_{x} \widehat{\mathbf{i}}+\omega_{y} \widehat{\mathbf{j}}+\omega_{z} \widehat{\mathbf{k}}
$$

and

$$
\widehat{\omega}=\left(\widehat{\mathbf{i}}+\lambda_{1} \widehat{\mathbf{j}}+\lambda_{2} \widehat{\mathbf{k}}\right) / \sqrt{1+\lambda_{1}^{2}+\lambda_{2}^{2}}
$$

Hence we can determine the direction of $\omega$ or the direction of principal axis corresponding to $I_{1}$. Similarly we may find the direction of the corresponding pricipal axis if we substitute $I_{2}$ or $I_{13}$.

## Example:

If the symmetry axis of the body is taken as axis of rotation and the origin of body axes lies on this then the principal axes are the symmetry axis and any two perpendicular axes normal to the symmetry axis. In the case of a sphere, every axis through the centre is symmetry axis and hence any three orthogoal axes through the centre are principal axes.

### 2.13 FREQUENCIES OF FREE VIBRATIONS AND NORMAL COORDINATES:

The co-ordinates in the solution of equations where only one single frequency is involved in the solution are known as the normal co-ordinates. Thus the normal co-ordinates are defined as the generalized co-ordinates wher each of them execute oscillations with a single frequency.On transformation from the co-ordinates $u_{j}$ into the normal co-ordinates denotted by $\eta_{k}$ the lagrangian as well as equations of motion are changed.
Let the new co-ordinates $\eta_{k}$ be related to the original co-ordinates as

$$
u_{j}=\sum_{k} a_{j k} \eta_{k}
$$

In the matrix form this relation can be expressed as

$$
\begin{equation*}
u=a \eta \tag{1}
\end{equation*}
$$

Here $u$ and $\eta$ are column matrices of order $n \times 1$ and a is a square matrix of order $n \times n$. We shall express potential and kinetic energy in terms of $\eta$.The potential energy is

$$
\begin{aligned}
V & =\frac{1}{2} \sum_{j, k} V_{j k} u_{j} u_{k} \\
& =\frac{1}{2} \sum_{j, k} u_{j} V_{j k} u_{k}
\end{aligned}
$$

In the matrix form this relation can be expressed as

$$
V=\frac{1}{2} u^{T} V u
$$

Using eqn(1) we get

$$
\begin{aligned}
V & =\frac{1}{2}(a \eta)^{T} V a \eta \\
& =\frac{1}{2} \eta^{T} a^{T} V a \eta \\
& =\frac{1}{2} \eta^{T} \wedge \eta
\end{aligned}
$$

Where

$$
\begin{aligned}
A^{T} V A=\wedge & =\text { diagonal matrix } \\
& =\operatorname{diag}\left(\omega_{1}{ }^{2}, \omega_{2}{ }^{2} \ldots \omega_{n}{ }^{2}\right)
\end{aligned}
$$

Further the above eqn is quardratic in $\eta$ so that

$$
\begin{align*}
V & =\frac{1}{2} \sum_{l} \lambda_{l} \eta_{l}^{2} \\
V & =\frac{1}{2} \sum_{l} \omega_{l}^{2} \eta_{l}^{2} \tag{2}
\end{align*}
$$

The kinetic energy is given by

$$
\begin{aligned}
T= & \frac{1}{2} \sum_{j} \sum_{k} T_{j k} \dot{u}_{j} \dot{u_{k}} \\
= & \frac{1}{2} \sum_{j} \sum_{k} \dot{u}_{j} T_{j k} \dot{u_{k}} \\
& =\frac{1}{2} \dot{u}^{T} T \dot{u} \\
= & \frac{1}{2}(a \dot{\eta})^{T} T(a \dot{\eta}) \\
& =\frac{1}{2} \dot{\eta}^{T} a^{T} T a \dot{\eta} \\
& =\frac{1}{2} \dot{\eta}^{T} \dot{\eta}
\end{aligned}
$$

Where

$$
\begin{align*}
a^{T} T a & =1 \\
& =\frac{1}{2} \sum{\dot{\eta_{l}}}^{2} \tag{3}
\end{align*}
$$

The Lagrangian in new co-ordinates system will be

$$
L=\frac{1}{2} \mathrm{ffl} \sum_{i=1}^{n}{\dot{\eta_{l}}}^{2}-\frac{1}{2} \sum_{i=1}^{n} \omega_{l}^{2} \eta_{l}^{2}
$$

Giving

$$
\frac{\partial L}{\partial \dot{\eta}_{l}}=\sum_{i=1}^{n} \dot{\eta}_{l} \quad \text { and } \quad \frac{\partial L}{\partial \eta_{l}}=-\sum_{i=1}^{n} \omega_{l}^{2} \dot{\eta}_{l}
$$

Now

$$
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\eta}_{l}}\right)-\frac{\partial L}{\partial \eta_{l}}=0
$$

gives

$$
\sum_{i=1}^{n}\left(\ddot{\eta}_{l}+\omega_{l}^{2} \dot{\eta}_{l}\right)=0
$$

Therefore the equations of motion in new co-ordinates are

$$
\begin{gather*}
\ddot{\eta}_{1}+\omega_{1}^{2} \dot{\eta}_{1}=0 \\
\ddot{\eta}_{2}+\omega_{2}^{2} \dot{\eta}_{2}=0 \\
\ldots \quad \ldots \quad \quad \ldots  \tag{4}\\
\ddot{\eta}_{l}+\omega_{l}^{2} \dot{\eta}_{l}=0
\end{gather*}
$$

Thus each co-ordinate executes only one single frequency oscillation and therefore $\eta_{1}, \eta_{2}$ etc are termed as normal co-ordinates.
The solution of equation

$$
\ddot{\eta}_{l}+\omega_{l}^{2} \dot{\eta}_{l}=0
$$

is

$$
\begin{array}{ll}
\eta_{l}=A_{l} \cos \omega_{l} t+B_{l} \sin \omega_{l} t & \text { if } \omega_{l}^{2}>0 \\
\eta_{l}=A_{l} t+B_{l} t & \text { if } \omega_{l}^{2}=0 \\
\eta_{l}=A_{l} e^{\omega_{l} t}+B_{l} e^{\omega_{l} t} & \text { if } \omega_{l}^{2}<0 \tag{5}
\end{array}
$$

For $\omega_{l}{ }^{2}>0$, all co-ordinates remain finite and the equilibrium is stable.
But for $\omega_{l}{ }^{2}=0$ and $\omega_{l}{ }^{2}<0$, the co-ordinates become infinite and the equilibrium is unstable.

## Normal modes of vibration :

Since

$$
\omega=2 \pi \nu
$$

The solutions become

$$
\begin{array}{lllll}
\eta_{l}= & A_{l} \cos 2 \pi \nu_{1} t+B_{l} \sin & 2 \pi \nu_{1} t \\
\eta_{2}= & A_{l} \cos & 2 \pi \nu_{2} t+B_{l} \sin & 2 \pi \nu_{2} t \\
\ldots & \cdots & \cdots & \cdots & \cdots \tag{6}
\end{array} \quad \cdots .
$$

Here A's and B's are 2 n arbitrary constants determined by the initial conditions.
Suppose all constants except $A_{1}$ and $B_{1}$ are zero. Then only $\eta_{1}$ will vary periodically with time. This situation corresponds to a normal mode of vibration. That is the system is vibrating in a normal mode.Therefore there will be n normal modes of vibration and n normal frequencies $\nu_{1}, \nu_{2}, \nu_{3} \ldots \nu_{n}$ corresponding to each normal co-ordinate $\eta_{1}, \eta_{2}, \eta_{3} \ldots \eta_{n}$ Now eqn(6) will take the form

$$
\eta_{l}=A_{l} \cos \left(\omega_{l} t+\delta_{l}\right)
$$

Her $\delta_{l}$ is the phase factor.
Now the old co-ordinates are given by

$$
u_{j}=\sum_{k} a_{j k} A_{k} \cos \left(\omega_{k} t+\delta_{k}\right)
$$

### 2.14 FREE VIBRATIONS OF A LINEAR TRIATOMIC MOLECULE :

We consider a linear triatomic molecule of the type $Y X_{2}\left(e . g C O_{2}\right) . \mathrm{Y}$ is a central atom.There exists an elastic bond between the central atom and the end atoms with force constant k . Let the mass of each end atom be m and that of cental atom be M.Let the displacement of atoms from their equilibrium position be $q_{1}, q_{2}, q_{3}$. The kinetic energy of the system

$$
T=\frac{1}{2} m\left(\dot{q}_{1}^{2}+{\dot{q_{3}}}^{2}\right)+\frac{1}{2} M{\dot{q_{2}}}^{2}
$$



## YX2molecule

Figure 1: LINEAR TRIATOMIC MOLECULE

$$
2 T=\left[\begin{array}{lll}
\dot{q_{1}} & \dot{q_{2}} & \dot{q}_{3}
\end{array}\right]\left[\begin{array}{ccc}
m & 0 & 0 \\
0 & M & 0 \\
0 & 0 & m
\end{array}\right]\left[\begin{array}{l}
\dot{q}_{1} \\
\dot{q}_{2} \\
\dot{q}_{3}
\end{array}\right]
$$

giving

$$
T=\left(T_{i j}\right)=\left[\begin{array}{ccc}
m & 0 & 0 \\
0 & M & 0 \\
0 & 0 & m
\end{array}\right]
$$

The potential energy V of the system is

$$
\begin{gathered}
V=\frac{1}{2} k\left(q_{2}-q_{1}\right)^{2}+\frac{1}{2} k\left(q_{3}-q_{2}\right)^{2} \\
V=\frac{1}{2} k\left(q_{1}^{2}+2 q_{2}^{2}+q_{3}^{2}-2 q_{1} q_{2}-2 q_{2} q_{3}\right)
\end{gathered}
$$

or

$$
2 V=\left[\begin{array}{lll}
q_{1} & q_{2} & q_{3}
\end{array}\right]\left[\begin{array}{ccc}
k & -k & 0 \\
-k & 2 k & -k \\
0 & -k & k
\end{array}\right]\left[\begin{array}{l}
q_{1} \\
q_{2} \\
q_{3}
\end{array}\right]
$$

giving the matrix V as

$$
V=\left(V_{i j}\right)=\left[\begin{array}{ccc}
k & -k & 0 \\
-k & 2 k & -k \\
0 & -k & k
\end{array}\right]
$$

Then write secular equation

$$
\left|V-\omega^{2} T\right|=0
$$

That is

$$
\left|\begin{array}{ccc}
k-\omega^{2} m & -k & 0 \\
-k & 2 k-\omega^{2} M & -k \\
0 & -k & k-\omega^{2} m
\end{array}\right|=0
$$

After expansion we get

$$
\begin{gathered}
\left(k-\omega^{2} m\right)\left[\left(2 k-\omega^{2} M\right)\left(k-\omega^{2} m\right)-k^{2}\right]+k\left[-k\left(k-\omega^{2} m\right)\right]=0 \\
\left(k-\omega^{2} m\right)\left[\left(2 k-\omega^{2} M\right)\left(k-\omega^{2} m\right)-k^{2}\right]-k^{2}\left(k-\omega^{2} m\right)=0 \\
\left(k-\omega^{2} m\right)\left[\left(2 k-\omega^{2} M\right)\left(k-\omega^{2} m\right)-2 k^{2}\right]=0
\end{gathered}
$$

giving

$$
\begin{gathered}
\omega_{1}=0 \\
\omega_{2}=\sqrt{\frac{k}{m}} \\
\omega_{3}=\sqrt{k\left(\frac{1}{m}+\frac{2}{M}\right)}
\end{gathered}
$$

Now we want to express $\eta_{1}, \eta_{2}$ and $\eta_{3}$ in terms of the generalized co-ordinates $q_{1}, q_{2}$ and $q_{3}$ as

$$
q_{j}=\sum_{k} A_{j k} \eta_{k}
$$

giving

$$
\left[\begin{array}{l}
q_{1}  \tag{1}\\
q_{2} \\
q_{3}
\end{array}\right]=\left[\begin{array}{lll}
A_{11} & A_{12} & A_{13} \\
A_{21} & A_{22} & A_{23} \\
A_{31} & A_{32} & A_{33}
\end{array}\right]\left[\begin{array}{c}
\eta_{1} \\
\eta_{2} \\
\eta_{3}
\end{array}\right]
$$

Our problem is to find the components of eigen vectors $A_{1}, A_{2}$ and $A_{3}$. For this purpose we apply the relation

$$
\sum_{j=1}^{3}\left(V_{i j}-\omega^{2} T_{i j}\right) A_{i j}=0 \quad i=1,2,3
$$

## First case :

$\omega=\omega_{1}=0$ and calculation of the components $A_{11}, A_{21}$ and $A_{31}$ of $A_{1}$. We have

$$
\left[\begin{array}{ccc}
k & -k & 0 \\
-k & 2 k & -k \\
0 & -k & k
\end{array}\right]\left[\begin{array}{l}
A_{11} \\
A_{21} \\
A_{31}
\end{array}\right]=0
$$

giving

$$
\begin{gathered}
k A_{11}-k A_{21}=0 \\
-k A_{11}+2 k A_{21}-k A_{31}=0 \\
-k A_{21}-k A_{31}=0
\end{gathered}
$$

It gives

$$
A_{11}=A_{21}=A_{31}=\alpha
$$

## Second case :

$\omega=\omega_{2}=\sqrt{\frac{k}{m}}$ and calculation of the components $A_{12}, A_{22}$ and $A_{32}$ of $A_{2}$. We have

$$
\left[\begin{array}{ccc}
0 & -k & 0 \\
-k & 2 k-\frac{k M}{m} & -k \\
0 & -k & 0
\end{array}\right]\left[\begin{array}{c}
A_{12} \\
A_{22} \\
A_{32}
\end{array}\right]=0
$$

giving

$$
\begin{gathered}
-k A_{22}=0 \\
-k A_{12}+\left(2 k-\frac{k M}{m}\right) A_{22}-k A_{32}=0 \\
-k A_{21}-k A_{31}=0
\end{gathered}
$$

It gives

$$
A_{22}=0 \quad A_{12}=-A_{32}=\beta
$$

## Third case :

$\omega=\omega_{3}=\sqrt{k\left(\frac{1}{m}+\frac{2}{M}\right)}$ and calculation of the components $A_{13}, A_{23}$ and $A_{33}$ of $A_{3}$. Then

$$
\omega^{2}=\omega_{3}^{2}=k\left(\frac{1}{m}+\frac{2}{M}\right)=\frac{k}{m}\left(1+\frac{2 m}{M}\right)
$$

We have

$$
\left[\begin{array}{ccc}
-\frac{2 m k}{M} & -k m & 0 \\
-k & -\frac{k M}{m} & -k \\
0 & -k & -\frac{2 m k}{M}
\end{array}\right]\left[\begin{array}{l}
A_{13} \\
A_{23} \\
A_{33}
\end{array}\right]=0
$$

giving

$$
\begin{gathered}
-\frac{2 m k}{M} A_{13}-k A_{23}=0 \\
-k A_{13}-\frac{k M}{m} A_{23}-k A_{33}=0 \\
-k A_{23}-\frac{2 m k}{M} A_{33}=0
\end{gathered}
$$

It leads to

$$
\begin{gathered}
\frac{2 m k}{M} A_{13}=-k A_{23} \\
\frac{2 m}{M} A_{13}=-A_{23} \Rightarrow A_{23}=-\frac{2 m}{M} A_{13}
\end{gathered}
$$

Take

$$
A_{13}=\gamma
$$

Then

$$
A_{23}=-\frac{2 m}{M} \gamma
$$

Similarly

$$
-k A_{23}-\frac{2 m k}{M} A_{33}=0
$$

That is

$$
k A_{23}+\frac{2 m k}{M} A_{33}=0
$$

Which leads to

$$
\begin{gathered}
\frac{2 m k}{M} A_{33}=-k A_{23} \Rightarrow \frac{2 m k}{M} A_{33}=-k\left(-\frac{2 m}{M} \gamma\right) \\
A_{33}=\gamma
\end{gathered}
$$

It gives

$$
A_{13}=A_{33}=\gamma \quad A_{23}=-\frac{2 m}{M} \gamma
$$

Thus the matrix A is

$$
A=A_{i j}=\left[\begin{array}{ccc}
\alpha & \beta & \gamma \\
\alpha & 0 & -\frac{2 m \gamma}{M} \\
\alpha & -\beta & \gamma
\end{array}\right]
$$

The components can be calculated by applying

$$
A^{T} T A=I
$$

$$
\begin{gathered}
{\left[\begin{array}{ccc}
\alpha & \alpha & \alpha \\
\beta & 0 & -\beta \\
\gamma-\frac{2 m \gamma}{M} & \gamma
\end{array}\right]\left[\begin{array}{ccc}
m & 0 & 0 \\
0 & M & 0 \\
0 & 0 & m
\end{array}\right]\left[\begin{array}{ccc}
\alpha & \beta & \gamma \\
\alpha & 0 & -\frac{2 m \gamma}{M} \\
\alpha & -\beta & \gamma
\end{array}\right]=\left[\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right]} \\
{\left[\begin{array}{ccc}
\alpha & \alpha & \alpha \\
\beta & 0 & -\beta \\
\gamma-\frac{2 m \gamma}{M} & \gamma
\end{array}\right]\left[\begin{array}{ccc}
\alpha m & \beta m & \gamma m \\
\alpha M & 0 & -2 m \gamma \\
\alpha m & -\beta m & \gamma m
\end{array}\right]=\left[\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right]} \\
{\left[\begin{array}{cc}
\alpha^{2}(2 m+M) & 0
\end{array}\right]=\left[\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right]}
\end{gathered}
$$

It gives

$$
\begin{gathered}
\alpha^{2}(2 m+M)=1 \Rightarrow \alpha=\frac{1}{\sqrt{2 m+M}} \\
2 \beta^{2} m=1 \Rightarrow \beta=\frac{1}{\sqrt{2 m}} \\
2 \gamma^{2} m(1+2 m / M)=1 \Rightarrow \gamma=\frac{1}{\sqrt{2 m(1+2 m / M)}}
\end{gathered}
$$

Thus the matrix A is

$$
A=A_{i j}=\left[\begin{array}{ccc}
\frac{1}{\sqrt{2 m+M}} & \frac{1}{\sqrt{2 m}} & \frac{1}{\sqrt{2 m(1+2 m / M)}}  \tag{2}\\
\frac{1}{\sqrt{2 m+M}} & 0 & \frac{1}{\sqrt{2 m(1+2 m / M)}} \\
\frac{1}{\sqrt{2 m+M}} & \frac{1}{\sqrt{2 m}} & \frac{1}{\sqrt{2 m(1+2 m / M)}}
\end{array}\right]
$$

The normal co-ordinates can be obtained by using equation (2) in equation (1).

## Unit III - TWO - BODY CENTRAL FORCE PROBLEM AND H - J THEORY

Two body central force problem: Reduction to the equivalent one body problem, the equation of motion and first integrals, classification of orbits, the virial theorem, the differential equation for the orbit, integral power law in time in the Kelper's problem, scattering in central force field;

H-J Theory: H-J equation and their solutions, use of H-J method for the solution of harmonic oscillator problem, Hamilton's principle function, Hamilton's characteristic function and their properties, Action angle variable for completely separable systems, the Kelper's problem in action angle variables

## TWO - BODY CENTRAL FORCE PROBLEM :

### 3.1 REDUCTION TO THE EQUIVALENT ONE BODY PROBLEM:

Consider a conservative system of two mass points $\mathrm{m}_{1}$ and $\mathrm{m}_{2}$. Let their instantaneous position vectors in an inertial frame with origin O are $\vec{r}_{1}$ and $\vec{r}_{2}$ respectively.

Hence the vector distance of $\mathrm{m}_{2}$ relative to $\mathrm{m}_{1}$ is

$$
\begin{equation*}
\vec{r}=\vec{r}_{2}-\vec{r}_{1} \tag{1}
\end{equation*}
$$

The Lagrangian for the system is


$$
\begin{align*}
\mathrm{L} & =\mathrm{T}-\mathrm{V} \\
& =\frac{1}{2} \mathrm{~m}_{1} \dot{\mathrm{r}}_{\mathrm{r}}^{2}+\frac{1}{2} \mathrm{~m}_{2} \dot{\mathrm{r}}_{2}^{2}-\mathrm{V}(\mathrm{r}) \tag{2}
\end{align*}
$$

Let us choose the three components of the position vector of the centre of mass $\vec{R}$ and three components of the relative vector $\overrightarrow{\mathrm{r}}=\overrightarrow{\mathrm{r}}_{2}-\overrightarrow{\mathrm{r}}_{1}$ to describe the state of the system.

The position vector of the centre of mass is defined by

$$
\begin{align*}
\vec{R} & =\frac{m_{1} \vec{r}_{1}+m_{2} \vec{r}_{2}}{m_{1}+m_{2}}  \tag{3}\\
\overrightarrow{\mathrm{R}} & =\frac{\mathrm{m}_{1} \overrightarrow{\mathrm{r}}_{1}+\mathrm{m}_{2}\left(\overrightarrow{\mathrm{r}}+\overrightarrow{\mathrm{r}}_{1}\right)}{\mathrm{m}_{1}+\mathrm{m}_{2}} \\
& =\frac{\mathrm{m}_{1} \overrightarrow{\mathrm{r}}_{1}+\mathrm{m}_{2} \overrightarrow{\mathrm{r}}+\mathrm{m}_{2} \overrightarrow{\mathrm{r}}_{1}}{\mathrm{~m}_{1}+\mathrm{m}_{2}}
\end{align*}
$$

$$
\begin{align*}
& =\frac{\left(\mathrm{m}_{1}+\mathrm{m}_{2}\right) \overrightarrow{\mathrm{r}}_{1}+\mathrm{m}_{2} \overrightarrow{\mathrm{r}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \\
& =\overrightarrow{\mathrm{r}}_{1}+\frac{\mathrm{m}_{2} \overrightarrow{\mathrm{r}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \\
\vec{r}_{1} & =\vec{R}-\frac{m_{2} \vec{r}}{m_{1}+m_{2}} \tag{4}
\end{align*}
$$

Similarly $\overrightarrow{\mathrm{R}}=\frac{\mathrm{m}_{1}\left(\overrightarrow{\mathrm{r}}_{2}-\overrightarrow{\mathrm{r}}\right)+\mathrm{m}_{2} \overrightarrow{\mathrm{r}}_{2}}{\mathrm{~m}_{1}+\mathrm{m}_{2}}$

$$
\begin{align*}
& =\frac{\mathrm{m}_{1} \overrightarrow{\mathrm{r}}_{2}-\mathrm{m}_{1} \overrightarrow{\mathrm{r}}+\mathrm{m}_{2} \overrightarrow{\mathrm{r}}_{2}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \\
& =\frac{\left(\mathrm{m}_{1}+\mathrm{m}_{2}\right) \overrightarrow{\mathrm{r}}_{2}-\mathrm{m}_{1} \overrightarrow{\mathrm{r}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \\
& =\overrightarrow{\mathrm{r}}_{2}-\frac{\mathrm{m}_{1} \overrightarrow{\mathrm{r}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \\
& \vec{r}_{2}=\vec{R}+\frac{m_{1} \vec{r}}{m_{1}+m_{2}} \tag{5}
\end{align*}
$$

Therefore

$$
\left.\begin{array}{l}
\dot{\overrightarrow{\mathrm{r}}}_{1}=\dot{\overrightarrow{\mathrm{R}}}-\frac{\mathrm{m}_{2} \dot{\overline{\mathrm{r}}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}} \text { and }  \tag{6}\\
\dot{\overrightarrow{\mathrm{r}}}_{2}=\dot{\overrightarrow{\mathrm{R}}}+\frac{\mathrm{m}_{1} \dot{\overline{\mathrm{r}}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}}
\end{array}\right\}
$$

Hence

$$
\begin{align*}
\mathrm{L}= & \frac{1}{2} \mathrm{~m}_{1}\left[\dot{\overrightarrow{\mathrm{R}}}-\frac{\mathrm{m}_{2} \dot{\overrightarrow{\mathrm{r}}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}}\right]^{2}+\frac{1}{2} \mathrm{~m}_{2}\left[\dot{\overrightarrow{\mathrm{R}}}+\frac{\mathrm{m}_{1} \dot{\overrightarrow{\mathrm{r}}}}{\mathrm{~m}_{1}+\mathrm{m}_{2}}\right]^{2}-\mathrm{V}(\mathrm{r}) \\
= & \frac{1}{2} \mathrm{~m}_{1}\left[\dot{\overrightarrow{\mathrm{R}}}^{2}+\frac{\mathrm{m}_{2}{ }^{2} \dot{\overrightarrow{\mathrm{r}}}^{2}}{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)^{2}}-\frac{2 \dot{\overrightarrow{\mathrm{R}}} \mathrm{~m}_{2} \dot{\overrightarrow{\mathrm{r}}}}{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)}\right] \\
& +\frac{1}{2} \mathrm{~m}_{2}\left[\dot{\overrightarrow{\mathrm{R}}}^{2}+\frac{\mathrm{m}_{1}^{2} \dot{\overrightarrow{\mathrm{r}}}^{2}}{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)^{2}}+\frac{2 \dot{\overrightarrow{\mathrm{R}}} \mathrm{~m}_{1} \dot{\overrightarrow{\mathrm{r}}}}{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)}\right]-\mathrm{V}(\mathrm{r}) \\
= & \frac{1}{2}\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right) \dot{\overrightarrow{\mathrm{R}}}^{2}+\frac{1}{2} \mathrm{~m}_{1} \mathrm{~m}_{2} \frac{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)}{\left(\mathrm{m}_{1}+\mathrm{m}_{2}\right)^{2}} \dot{\overrightarrow{\mathrm{r}}}^{2}-\mathrm{V}(\mathrm{r}) \\
= & \frac{1}{2}\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right) \dot{\overrightarrow{\mathrm{R}}}^{2}+\frac{1}{2} \frac{\mathrm{~m}_{1} \mathrm{~m}_{2}}{\left(\mathrm{~m}_{1}+\mathrm{m}_{2}\right)} \dot{\overrightarrow{\mathrm{r}}}^{2}-\mathrm{V}(\mathrm{r})  \tag{7}\\
\mathrm{L}= & \frac{1}{2} \mathrm{M} \dot{\overrightarrow{\mathrm{R}}}^{2}+\frac{1}{2} \mu \dot{\overrightarrow{\mathrm{r}}}^{2}-\mathrm{V}(\mathrm{r}) \tag{8}
\end{align*}
$$

Where $M=m_{1}+m_{2} \quad$ and $\quad \mu=\frac{m_{1} m_{2}}{m_{1}+m_{2}}$
Lagrangian equations of motion in terms of the two variables $\vec{R}$ and $\overrightarrow{\mathrm{r}}$ will be

$$
\begin{align*}
& \frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\vec{R}}}\right)-\frac{\partial L}{\partial \vec{R}}=0  \tag{9}\\
& \frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\vec{r}}}\right)-\frac{\partial L}{\partial \vec{r}}=0  \tag{10}\\
& \frac{\partial \mathrm{~L}}{\partial \dot{\overrightarrow{\mathrm{R}}}}=\mathrm{M} \dot{\overrightarrow{\mathrm{R}}} \text { and } \frac{\partial \mathrm{L}}{\partial \overrightarrow{\mathrm{R}}}=0 \\
& \frac{\partial \mathrm{~L}}{\partial \dot{\overrightarrow{\mathrm{r}}}}=\mu \dot{\overrightarrow{\mathrm{r}}}-\frac{\partial \mathrm{V}}{\partial \mathrm{r}}
\end{align*}
$$

Hence equations (9) and (10) become

$$
\begin{array}{r}
\frac{d}{d t}(M \dot{\vec{R}})=0 \\
\frac{\mathrm{~d}}{\mathrm{dt}}(\dot{\mu \mathrm{r}})+\frac{\partial \mathrm{V}}{\partial \mathrm{r}}=0 \tag{12}
\end{array}
$$

Equation (11) giving $M \dot{\vec{R}}=$ constant
(or) $\quad \dot{\overrightarrow{\mathrm{R}}} \quad=$ constant
That is velocity with which the centre of mass moves is constant.
Equation (12) giving $\mu \ddot{\overrightarrow{\mathrm{r}}}=-\frac{\partial \mathrm{V}}{\partial \mathrm{r}}=f(\mathrm{r})$
representing equation of motion for the system under consideration. Consequently we can ignore the first term in equation (8) and write

$$
\begin{equation*}
\mathrm{L}=\frac{1}{2} \mu \dot{\overrightarrow{\mathrm{r}}}^{2}-\mathrm{V}(\mathrm{r}) \tag{13}
\end{equation*}
$$

which is effective in describing the motion of the components of r . But L is the same as a single particle of mass $\mu$ moving at a distance $r$ from a fixed centre of force which gives rise to the potential energy $\mathrm{V}(\mathrm{r})$. Thus two body problem can be reduced to the equivalent one body problem.

### 3.2 EQUATIONS OF MOTION AND FIRST INTEGRALS:

Let us describe the position of the particle in the plane poloar co-ordinates r and $\theta$

$$
\mathrm{T}=\frac{1}{2} \mathrm{~m}\left(\dot{\mathrm{r}}^{2}+\mathrm{r}^{2} \dot{\theta}^{2}\right)
$$

$$
\mathrm{V}=\mathrm{V}(\mathrm{r})
$$

The Lagrangian

$$
\mathrm{L}=\mathrm{T}-\mathrm{V}
$$

$$
=\frac{1}{2} \mathrm{~m}\left(\dot{\mathrm{r}}^{2}+\mathrm{r}^{2} \dot{\theta}^{2}\right)-\mathrm{V}(\mathrm{r})
$$

As $\theta$ is cyclic coordinate so that its conjugate angular momentum $\mathrm{P}_{\theta}$ given by

$$
\begin{align*}
\mathrm{P}_{\theta} & =\frac{\partial L}{\partial \dot{\theta}}=m r^{2} \dot{\theta}=l \\
\dot{P}_{\theta} & =\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\theta}}\right)=\frac{d}{d t}\left(m r^{2} \dot{\theta}\right)=0 \tag{1}
\end{align*}
$$

Integrating, $\mathrm{mr}^{2} \dot{\theta}=$ constant $=l$
$l \rightarrow$ first integral and represents the magnitude of angular momentum.

$$
\begin{align*}
\frac{d}{d t}\left(m r^{2} \dot{\theta}\right) & =0 \\
\frac{d}{d t}\left(r^{2} \dot{\theta}\right) & =0 \\
\frac{d}{d t}\left(\frac{1}{2} r^{2} \dot{\theta}\right) & =0 \\
\frac{1}{2} \mathrm{r}^{2} \dot{\theta} & =\text { constant } \tag{2}
\end{align*}
$$

ie, Areal velocity = constant
The rate at which the area swept out by the radius vector is constant which is Kepler's second law of planetory motion.

Suppose dA is the area swept out by the radius vector in time dt.
Then

$$
\begin{aligned}
d A & =\frac{1}{2} r(r d \theta) \\
& =\frac{1}{2} r^{2} d \theta \\
\frac{d A}{d t} & =\frac{1}{2} r^{2} \frac{d \theta}{d t}=\frac{1}{2} r^{2} \dot{\theta}
\end{aligned}
$$

Therefore from equation (2), we write

$$
\begin{align*}
\frac{1}{2} \mathrm{r}^{2} \dot{\theta} & =\text { constant (or) } \\
\frac{d A}{d t} & =\text { constant } \tag{3}
\end{align*}
$$

Here we have two Lagrangian equations of motion. ie,

$$
\begin{equation*}
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{r}}\right)-\frac{\partial L}{\partial r}=0 \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\theta}}\right)-\frac{\partial L}{\partial \theta}=0 \tag{5}
\end{equation*}
$$

We have

$$
\begin{aligned}
& \frac{\partial L}{\partial \dot{r}}=m \dot{r} \text { and } \frac{\partial L}{\partial r}=m \dot{r} \theta^{2}-\frac{d V}{d r} \\
& \frac{\partial \mathrm{~L}}{\partial \dot{\theta}}=\mathrm{mr}^{2} \dot{\theta} \text { and } \frac{\partial \mathrm{L}}{\partial \theta}=0
\end{aligned}
$$

Now equations (4) and (5) become

$$
\begin{equation*}
\frac{d}{d t}(m \dot{r})-\left(m r \dot{\theta}^{2}-\frac{d V}{d r}\right)=0 \tag{6}
\end{equation*}
$$

And

$$
\begin{equation*}
\frac{d}{d t}\left(m r^{2} \dot{\theta}\right)=0 \tag{7}
\end{equation*}
$$

Equations (6) and (7) are the equations of motion

## (i) Expression for $\mathbf{r}(\mathbf{t})$ and $\theta(\mathbf{t})$ :

From equation (6) we write

$$
m \ddot{r}-m r \dot{\theta}^{2}=-\frac{d V}{d r}
$$

putting

$$
\dot{\theta}=\frac{l}{m r^{2}} \text { we get }
$$

$$
\begin{aligned}
m \ddot{r}-m r\left(\frac{l}{m r^{2}}\right)^{2} & =-\frac{d V}{d r} \\
m \ddot{r}-\frac{l^{2}}{m r^{3}} & =-\frac{d \mathrm{~V}}{d r} \\
m \ddot{r} & =-\frac{d}{d r}\left[V+\frac{l^{2}}{2 m r^{2}}\right] \\
m \ddot{r} \dot{r} & =-\frac{d}{d r}\left[V+\frac{l}{2 m r^{2}}\right] \dot{r}
\end{aligned}
$$

(or) $\quad \frac{d}{d t}\left(\frac{1}{2} m \dot{r}^{2}\right)=-\frac{d}{d r}\left[\mathrm{~V}+\frac{l^{2}}{2 m r^{2}}\right] \frac{d r}{d t}$

$$
=-\frac{d}{d t}\left[V+\frac{l^{2}}{2 m r^{2}}\right]
$$

So that
(or)

$$
\frac{d}{d t}\left[\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r)\right]=0
$$

$$
\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r)=\text { constant }
$$

putting

$$
l=\mathrm{mr}^{2} \dot{\theta}, \text { then }
$$

$$
\begin{aligned}
\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r) & =\frac{1}{2} m \dot{r}^{2}+\frac{m^{2} r^{4} \dot{\theta}^{2}}{2 m r^{2}}+V(r) \\
& =\frac{1}{2} m \dot{r}^{2}+\frac{1}{2} m r^{2} \dot{\theta}^{2}+V(r) \\
& =\frac{1}{2} m\left[\dot{r}^{2}+r^{2} \dot{\theta}^{2}\right]+V(r) \\
& =\mathrm{T}+\mathrm{V}=\mathrm{E}
\end{aligned}
$$

Thus we write

$$
\begin{equation*}
\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r)=E \tag{8}
\end{equation*}
$$

E is a constant of motion. This is another first integral of motion.

$$
\begin{aligned}
\dot{r} & =\left[\frac{2}{m}\left(E-V-\frac{l^{2}}{2 m r^{2}}\right)\right]^{\frac{1}{2}}=\frac{d r}{d t} \\
d t & =\frac{d r}{\left[\frac{2}{m}\left(E-V-\frac{l^{2}}{2 m r^{2}}\right)\right]^{\frac{1}{2}}}
\end{aligned}
$$

On integration we get

$$
\begin{equation*}
t=\int_{r_{0}}^{r} \frac{d r}{\left[\frac{2}{m}\left(E-V-\frac{l^{2}}{2 m r^{2}}\right)\right]^{\frac{1}{2}}} \tag{9}
\end{equation*}
$$

where $r=r_{o}$ at $t=0$.
This equation gives $r$ as a function of time. ie $r(t)$.

$$
\text { We have } \dot{\theta} \quad=\frac{l}{m r^{2}}
$$

$$
\begin{align*}
\frac{d \theta}{d t} & =\frac{l}{m r^{2}} \\
\theta & =\frac{l}{m} \int_{o}^{t} \frac{d t}{r^{2}(t)}+\theta_{o}
\end{align*}
$$

Thus integration of equations (9) and (10) provides us $r(t)$ and $\theta(t)$. Then we can locate the position of the particle on the path at any time $t$ and the solution.

### 3.3 CLASSIFICATION OF ORBITS:

We have already derived

$$
\begin{aligned}
m \ddot{r} & =-\frac{d}{d r}\left(V+\frac{l^{2}}{2 m r^{2}}\right) \\
& =-\frac{d V}{d r}+\frac{l^{2}}{m r^{3}} \\
& =f(r)+\frac{l^{2}}{m r^{3}} \\
& =f^{\prime}=\text { effective force. } \\
f^{\prime} & =f(r)+\frac{\left(m r^{2} \dot{\theta}\right)^{2}}{m r^{3}} \\
& =f(r)+m r \dot{\theta}^{2} \\
& =f(r)+\frac{m(r \dot{\theta})^{2}}{r} \\
& =f(r)+\frac{m \mathrm{v}_{\theta}^{2}}{r} \\
& =\text { Central force }+ \text { Centrifugal force. }
\end{aligned}
$$

Thus equation takes the form

$$
m \ddot{r}=f^{\prime}
$$

It is an equation of motion for a particle subjected to actual force $f(\mathrm{r})$ and pseudo centrifugal force $\frac{l^{2}}{\mathrm{mr}^{3}}$. Also $f^{\prime}=-\frac{d V^{\prime}}{d r}$

$$
\mathrm{V}^{\prime}=\text { effective potential energy }
$$

$$
\begin{aligned}
\mathrm{V}^{\prime} & =-\int f^{\prime} d r=-\int\left[f(r)+\frac{l^{2}}{m r^{3}}\right] d r \\
& =-\int f(r) d r+\frac{l^{2}}{2 m r^{2}}
\end{aligned}
$$

$$
=V(r)+\frac{l^{2}}{2 m r^{2}}
$$

The second term is the potential energy related to the centrifugal force.

## (i) Orbits under inverse square law of force :

The effective potential energy

$$
\begin{aligned}
V^{\prime}(r) & =-\int \frac{k}{r^{2}} d r+\frac{l^{2}}{2 m r^{2}} \\
& =\frac{\mathrm{k}}{\mathrm{r}}+\frac{l^{2}}{2 \mathrm{mr}^{2}}
\end{aligned}
$$

as a function of $r$ has been plotted.

## (ii) Motion with different values of k :




Case (i) : E > 0 :
There is a minimum radial distance $r_{3}$ but no maximum. The motion is unbounded. The particle comes in from $\mathrm{r}=\infty$ to a turning point and travels out to infinity again; Thus the motion is not periodic and with a single turning point.

Case (ii) : $0>\mathrm{E}>\mathrm{V}^{\prime}{ }_{\text {min }}=\mathrm{E}_{\mathrm{m}}$ :
corresponds to energy $\mathrm{E}_{1}$
The radial motion is confined to the values $r=r_{1}=r_{\text {min }}$ and $r=r_{2}=r_{\text {max }}$ $\mathrm{r}_{1}$ and $\mathrm{r}_{2}$ are the turning points.

$$
E_{1}=\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r)
$$

$$
\begin{aligned}
& =\frac{1}{2} m \dot{r}^{2}+V^{\prime}(r) \\
E_{1}-V^{\prime}(r) & =\frac{1}{2} m \dot{r}^{2}=T
\end{aligned}
$$

Though $\dot{\mathrm{r}}=0$ at these points $\dot{\theta} \neq 0$
The particle will not be at rest at these points. The motion is confined between the areas of two circles of radii $r_{1}$ and $r_{2}$.

A possible shape for an attractive inverse square law of force is an ellipse with the focus at the centre.

When $r$ varies from $r_{1}$ to $r_{2}$ and back, the radius vector turns through an angle $\theta$ obtained by

$$
\begin{aligned}
\theta & =\int \frac{l}{\mathrm{mr}^{2}} \mathrm{dt}+\theta_{0} \\
\mathrm{dt} & =\frac{\mathrm{dr}}{\left[\frac{2}{\mathrm{~m}}\left(\mathrm{E}-\mathrm{v}-\frac{l^{2}}{2 \mathrm{mr}^{2}}\right)\right]^{\frac{1}{2}}} \\
\theta & =\int \frac{\left(\frac{l}{\mathrm{r}^{2}}\right) \mathrm{dr}}{\mathrm{~m}\left[\frac{2}{\mathrm{~m}}\left(\mathrm{E}-\mathrm{V}-\frac{l^{2}}{2 \mathrm{mr}^{2}}\right)\right]^{\frac{1}{2}}} \\
& =\int \frac{\left(\frac{l}{\mathrm{r}^{2}}\right) \mathrm{dr}}{\left[2 \mathrm{~m}(\mathrm{E}-\mathrm{V})-\frac{l^{2}}{\mathrm{r}^{2}}\right]^{\frac{1}{2}}}+\theta_{\mathrm{o}}
\end{aligned}
$$



When $\theta=\frac{2 \pi \mathrm{~m}}{\mathrm{n}}$, the path is a closed orbit. When $\theta$ is not a rational fraction of $2 \pi$, the path has the shape of a rosette. Such an orbital motion is processing motion.

Case (iii) : $E=E_{m}=V_{\min }^{\prime}: \dot{r}=0$ and $\dot{\theta}=$ finite, the particle moves in a circle.

Energy $\mathrm{E}_{\mathrm{m}}$ corresponds to the minimum value of $\mathrm{V}^{\prime}(\mathrm{r})$

$$
\frac{d V^{\prime}}{d r}=\frac{d}{d r}\left[\frac{-k}{r}+\frac{l^{2}}{2 m r^{2}}\right]
$$

$$
=\frac{\mathrm{k}}{\mathrm{r}^{2}}-\frac{l^{2}}{\mathrm{mr}^{3}}
$$

Putting $r=r_{0}$ for which $V^{\prime}(r)$ is minimum.

$$
\begin{aligned}
\frac{\mathrm{k}}{\mathrm{r}_{\mathrm{o}}^{2}}-\frac{l^{2}}{\mathrm{mr}_{\mathrm{o}}^{3}} & =\mathrm{o} \Rightarrow \frac{\mathrm{k}}{\mathrm{r}_{\mathrm{o}}{ }^{2}}=\frac{l^{2}}{\mathrm{mr}_{\mathrm{o}}^{3}} \\
\mathrm{r}_{\mathrm{o}} & =\frac{l^{2}}{\mathrm{mk}} \\
\mathrm{E}_{4} & =\left.V^{\prime}(r)\right|_{\min } \\
& =-\frac{\mathrm{k}}{\mathrm{r}_{\mathrm{o}}}+\frac{l^{2}}{2 \mathrm{mr}_{\mathrm{o}}^{2}} \\
& =-\frac{\mathrm{mk}^{2}}{l^{2}}+\frac{1}{2} \frac{\mathrm{mk}^{2}}{l^{2}}=-\frac{1}{2} \frac{\mathrm{mk}^{2}}{l^{2}}
\end{aligned}
$$

In this case two bounds coincide

$$
\mathrm{r}_{3}=\mathrm{r}_{2}=\mathrm{r}_{\mathrm{o}}
$$

Orbit is a circle of radius $\frac{1^{2}}{m k}$.
Case (iv) : $\mathrm{E}<V_{\text {min }}^{\prime}: \dot{r}$ will be imaginary and therefore no physically meaningful motion is possible.

## (iii) Stability of orbits and conditions for closure:

(a) Stability:

The condition of stability in radial motion is given by the existence of local minimum in $\mathrm{V}^{\prime}(\mathrm{r})$, the effective potential. That is we require that

$$
\frac{\partial^{2} V^{\prime}(r)}{\partial r^{2}}>0 \quad \text { at } \mathrm{r}=\mathrm{r}_{\mathrm{o}}
$$

given by

$$
\frac{\partial^{2} V^{\prime}(r)}{\partial r}=0
$$

For any central force, the potential energy function is given by,

$$
\begin{aligned}
V(r) & =-k r^{n+1}(\text { for bounded motion }) \\
V^{\prime}(r) & =-k r^{n+1}+\frac{l^{2}}{2 m r^{2}} \\
\frac{\partial V^{\prime}(r)}{\partial r} & =-k(n+1) r^{n}-\frac{l^{2}}{m r^{3}}
\end{aligned}
$$

$$
\begin{aligned}
&\left.\frac{\partial V^{\prime}(r)}{\partial r}\right|_{r=r_{0}}=-k(n+1) r_{0}^{n}-\frac{l^{2}}{m r_{0}^{3}}=0 \\
& k(n+1) r_{0}^{n}=-\frac{l^{2}}{m r_{0}^{3}} \\
& k(n+1)=-\frac{l^{2} r_{0}^{-(3+n)}}{m} \\
& \begin{aligned}
\left.\frac{\partial^{2} V^{\prime}(r)}{\partial r^{2}}\right|_{r=r_{0}} & =-k n(n+1) r_{0}^{n-1}+\frac{3 l^{2}}{m r_{0}^{4}} \\
& =n \frac{l^{2}}{m} r_{o}^{-(3+n)} r_{o}^{n-1}+\frac{3 l^{2}}{m} r_{o}^{-4} \\
& =n \frac{l^{2}}{m} r_{0}^{-4}+\frac{3 l^{2}}{m} r_{0}^{-4} \\
& =\frac{l^{2}}{m}(n+3) r_{0}^{-4}
\end{aligned}
\end{aligned}
$$

Which is positive if $n>-3$
Therefore any circular orbit with $r=r_{0}$ under any central force can satisfy the stability condition if $\mathrm{n}>-3$.
(b) Conditions for closure:
(iii) All bound orbits are closed only if for the inverse square law of force of electrostatic attraction or gravitational type and for Hooke's type linear law of force.
(iv) The condition for bound motion is that there is a bounded domain of r in which $\mathrm{V}(\mathrm{r}) \leq \mathrm{E}$. The condition for stability of circular orbits is $\mathrm{n}>-3$ where $f$ (r) $\alpha \mathrm{r}^{\mathrm{n}}$. That is for $\mathrm{n}=-1$ and $\mathrm{n}=-2$ only closed orbits exist.

### 3.4 VIRIAL THEROEM:

We consider a system of mass points with position vectors $\boldsymbol{r}_{\boldsymbol{i}}$ and applied forces $\boldsymbol{F}_{\boldsymbol{i}}$.
Fundamental equations of motion will be

$$
\begin{equation*}
\dot{p}_{i}=F_{i} \tag{1}
\end{equation*}
$$

Let us write a quantity

$$
\begin{align*}
G & =\sum \boldsymbol{p}_{i} \cdot \boldsymbol{r}_{\boldsymbol{i}} \\
\frac{d G}{d t} & =\sum \boldsymbol{p}_{i} \cdot \dot{\boldsymbol{r}}_{i}+\sum \dot{\boldsymbol{p}}_{i} \cdot \boldsymbol{r}_{i} \tag{2}
\end{align*}
$$

But

$$
\begin{aligned}
\sum \dot{\boldsymbol{r}}_{i} \cdot \boldsymbol{p}_{i} & =\sum m_{i} \dot{\boldsymbol{r}}_{\boldsymbol{i}} \cdot \boldsymbol{r}_{\boldsymbol{i}} \\
& =\sum m_{i} \mathrm{v}_{i}^{2} \\
& =2 \mathrm{~T}
\end{aligned}
$$

and

$$
\sum \dot{\boldsymbol{p}}_{i} \cdot \boldsymbol{r}_{i}=\sum \boldsymbol{F}_{i} \cdot \boldsymbol{r}_{i}
$$

So that

$$
\frac{\partial G}{\partial t}=2 T+\sum \boldsymbol{F}_{i} \cdot \boldsymbol{r}_{i}
$$

The time average over a time interval $\tau$ will be

$$
\text { (or) } \begin{align*}
\frac{1}{\tau} \int_{0}^{2} \frac{d G}{d t} d t & =\overline{2 T}+\sum \overline{\boldsymbol{F}_{i} \cdot \boldsymbol{r}_{i}} \\
\overline{2 T}++\sum \overline{\boldsymbol{F}_{i} \cdot \boldsymbol{r}_{i}} & =\frac{\overline{d G}}{d t} \\
& =\frac{1}{\tau}[G(\tau)-G(0)] \tag{3}
\end{align*}
$$

If the motion is periodic and $\tau$ is its period then $\mathrm{G}(\tau)=\mathrm{G}(0)$ and hence the RHS of equation (3) is zero. If the motion is not periods but there is an upper bound to $G$ and the co-ordinates and velocities remain finite, then $\tau$ sufficiently large, RHS again be approximated to zero. Hence

$$
\begin{align*}
\overline{2 T}+\sum \overline{\boldsymbol{F}_{i} \cdot \boldsymbol{r}_{i}} & =0 \\
\bar{T} & =-\frac{1}{2} \sum \overline{\boldsymbol{F}_{i} \cdot \boldsymbol{r}_{\boldsymbol{i}}} \tag{4}
\end{align*}
$$

Equation (4) is known as the virial theorem and RHS is called virial of claussius.
This theorem is used in kinetic theory of gases to prove Boyle's law and to obtain equation of state for imperfect gases etc.

It the forces are derivable from a potential, then the theorem becomes.

$$
\begin{aligned}
\bar{T} & =\frac{1}{2} \overline{\sum \nabla_{i} \boldsymbol{V} \boldsymbol{r}_{\boldsymbol{i}}} \\
& =-\frac{1}{2} \overline{\left[-\frac{\partial \boldsymbol{V}}{\partial \boldsymbol{r}}\right]_{i} \cdot \boldsymbol{r}} \\
& =\frac{1}{2} \frac{\overline{\partial V}}{\partial r} r
\end{aligned}
$$

If the potential energy is

$$
\bar{V}=k r^{n+1}
$$

$$
\frac{\partial \bar{V}}{\partial r}=(n+1) k r^{n}
$$

Then

$$
\bar{T}=\frac{1}{2}(n+1) k r^{n} r=\frac{1}{2}(n+1) k r^{n+1}=\frac{1}{2}(n+1) \bar{V}
$$

For inverse square law $\mathrm{n}=-2$, hence

$$
\bar{T}=-\frac{1}{2} \bar{V} \Rightarrow 2 \bar{T}+\bar{V}=0
$$

### 3.5 DIFFERENTIAL EQUATION OF THE ORBIT:

Here we wish the obtain an equation that may provide a relation between r and $\theta$.

$$
\text { i.e } r=r(\theta)
$$

Such an equation will be the equation of the orbit.
It is convenient to introduce the new variable

$$
u=\frac{1}{r}(\text { or }) r=\frac{1}{u}
$$

so that

$$
\begin{aligned}
\dot{r}=-\frac{1}{u^{2}} \frac{d u}{d t} & =-\frac{1}{u^{2}} \frac{d u}{d \theta} \frac{d \theta}{d t} \\
& =-r^{2} \frac{d u}{d \theta} \dot{\theta} \\
\dot{r} & =-\frac{l}{m} \frac{d u}{d \theta} \quad\left[\text { since } \dot{\theta}=\frac{l}{m r^{2}}\right]
\end{aligned}
$$

And

$$
\begin{aligned}
\ddot{r} & =-\frac{l}{m} \frac{d}{d t}\left(\frac{d u}{d \theta}\right) \\
& =-\frac{l}{m} \frac{d}{d \theta}\left(\frac{d u}{d \theta}\right) \frac{d \theta}{d t} \\
& =-\frac{l}{m} \frac{d^{2} u}{d \theta^{2}} \dot{\theta} \\
& =-\frac{l^{2} u^{2}}{m^{2}} \frac{d^{2} u}{d \theta^{2}}
\end{aligned}
$$

We know that the equation of motion of a particle is

$$
\begin{aligned}
m \ddot{r} & =m r \dot{\theta}^{2}-\frac{d V}{d r} \\
& =\frac{l^{2}}{m r^{3}}+f(r)
\end{aligned}
$$

$$
\begin{aligned}
m\left[-\frac{l^{2} u^{2}}{m^{2}} \frac{d^{2} u}{d \theta^{2}}\right] & =\frac{l^{2}}{m} u^{3}+f\left(\frac{1}{u}\right) \\
\frac{d^{2} u}{d \theta^{2}} & =\frac{l^{2}}{m} u^{3}\left[\frac{-m}{l^{2} u^{2}}\right]+f\left(\frac{1}{u}\right)\left[\frac{-m}{l^{2} u^{2}}\right] \\
& =-u-\frac{m}{l^{2} u^{2}} f\left(\frac{1}{u}\right)
\end{aligned}
$$

Which is the differential equation of the orbit.
In case $l=0$, equation is absurd but from

$$
\begin{aligned}
l & =\mathrm{mr}^{2} \dot{\theta} \\
\mathrm{mr}^{2} \dot{\theta} & =0 \\
\dot{\theta} & =0 \\
\theta & =\text { constant }
\end{aligned}
$$

giving a straight line through the origin.

### 3.6 INTEGRABLE POWER LAW IN TIME IN KEPLER'S PROBLEM:

The inverse square law of force is most important of all the central force laws. It results the deduction of Kepler's laws.

1. All the planets move in an elliptical orbit with sun at one of its foci.
2. The radius vector connecting the sun and the planet sweeps at equal areas is equal intervals of time. ie, areal velocity is constant.
3. The square of the period of revolution of any planet about the sun is proportional to the cube of the semi major axis.
(i) Deduction of first law:

The central force varies inversely as the square of the distance. That is

$$
f(r)=\frac{-k}{r^{2}} \quad \mathrm{k} \text { is a constant }
$$

The corresponding potential energy will be

$$
V(r)=\frac{-k}{r}
$$

Equation of the orbit is $\quad \frac{d^{2} u}{d \theta^{2}}+u=\frac{-m}{l^{2} u^{2}} f\left(\frac{1}{u}\right)$
putting $f(r)=f\left(\frac{1}{u}\right)=\frac{-k}{r^{2}}=-k u^{2}$ we get

$$
\begin{equation*}
\frac{d^{2} u}{d \theta^{2}}+u=\frac{m k}{l^{2}} \tag{1}
\end{equation*}
$$

Let us put $\mathrm{y}=\mathrm{u}-\frac{\mathrm{mk}}{l^{2}}$ so that

$$
\frac{d^{2} y}{d \theta^{2}}=\frac{d^{2} u}{d \theta^{2}}
$$

Equation of the orbit then becomes

$$
\frac{d^{2} u}{d \theta^{2}}+y=0
$$

The general solution of this equation is

$$
\begin{aligned}
& \mathrm{y}=\mathrm{u}^{\prime} \cos \left(\theta-\theta^{\prime}\right) \\
& \mathrm{u}=\frac{\mathrm{mk}}{l^{2}}+\mathrm{u}^{\prime} \cos \left(\theta-\theta^{\prime}\right) \\
& u=\frac{1}{r}=\frac{m k}{l^{2}}+u^{\prime} \cos \left(\theta-\theta^{\prime}\right)
\end{aligned}
$$

Where $u^{\prime}$ and $\theta^{\prime}$ are constants.
If we orient our co-ordinate system so that $\theta^{\prime}=0$, then

$$
\begin{aligned}
\frac{1}{r} & =\frac{m k}{1^{2}}+u^{\prime} \cos \theta \\
& =\frac{m k}{1^{2}}\left[1+\frac{u^{\prime} 1^{2}}{m k} \cos \theta\right]
\end{aligned}
$$

(or)

$$
\begin{equation*}
\mathrm{r}=\frac{\frac{l^{2}}{\mathrm{mk}}}{\left[1+\frac{\mathrm{u}^{\prime} l^{2}}{\mathrm{mk}} \cos \theta\right]} \tag{2}
\end{equation*}
$$

Thus $\theta^{\prime}$ is a turning point.
We show that equation (2) represents a conic section, coincident with Kepler's first law of planetary motion. That is the orbits are conic sections with the centre at one of the foci.

We define the conic section as a curve for which the distance from a fixed point to that from a fixed line is a constant. That is

$$
\begin{aligned}
& \frac{r}{d}=\text { constant }=\varepsilon \\
& \varepsilon=\text { eccentricity }
\end{aligned}
$$

From figure, We see that

$$
\text { Let } \begin{align*}
\mathrm{P} & =\mathrm{d}+\mathrm{r} \cos \theta \\
\mathrm{p} & =\varepsilon \mathrm{P} \Rightarrow P=\frac{p}{\varepsilon} \\
\frac{p}{\varepsilon} & =d+r \cos \theta \\
& =\frac{\mathrm{r}}{\varepsilon}+\mathrm{r} \cos \theta \\
\mathrm{p} & =\mathrm{r}+\mathrm{r} \varepsilon \cos \theta \\
& =\mathrm{r}(1+\varepsilon \cos \theta) \\
\mathrm{r} & =\frac{p}{1+\varepsilon \cos \theta}
\end{align*}
$$



Which represents a conic section.
Equation (2) is of the form of equation (3) orbit under an inverse square force is always a conic section.

Comparing equations (2) and (3), we get

$$
p=\frac{l^{2}}{m k} \text { and } \varepsilon=\frac{u^{\prime} l^{2}}{m k}
$$

Further from $\varepsilon=\frac{\mathrm{r}}{\mathrm{d}}$, we must $\varepsilon \geq 0$ or r must be positive.

## (ii) To explore the shapes of orbit:

Equation (2) is the equation of the conic and consequently it should have been possible to explore the shape of orbits using this equation. Here $\varepsilon$ involves one unknown constant $\mathrm{u}^{\prime}$. Hence we express $\varepsilon$ in terms of known constants. Then we put the value of $\varepsilon$ in one equation of the conic which yield the desired information about the shape of the conic.

Already we have $\mathrm{E}=\frac{1}{2} m \dot{r}^{2}+\frac{l^{2}}{2 m r^{2}}+V(r)$

$$
\begin{align*}
\text { Here } V(r) & =\frac{-k}{r} \\
E & =\frac{1}{2} \mathrm{mi}^{2}+\frac{l^{2}}{2 \mathrm{mr}^{2}}-\frac{\mathrm{k}}{\mathrm{r}} \tag{4}
\end{align*}
$$

Suppose we take the turning point at which $r$ is minimum say $r_{\text {min }}$. Then $\dot{\mathrm{r}}=0$. Now equation (4) becomes.

$$
\begin{equation*}
\mathrm{E}=\frac{l^{2}}{2 m r_{\min }^{2}}-\frac{k}{r_{\min }} \tag{5}
\end{equation*}
$$

From equation (3) $r_{\min } \quad=\frac{p}{1+\varepsilon}=\frac{l^{2}}{m k(1+\varepsilon)}$
Now equation (5) becomes

$$
\begin{align*}
E & =\frac{l^{2}}{2 m}\left[\frac{m k(1+\varepsilon)}{l^{2}}\right]^{2}-k\left[\frac{m k(1+\varepsilon)}{l^{2}}\right] \\
& =\frac{\mathrm{mk}^{2}}{2 l^{2}}(1+\varepsilon)^{2}-\frac{\mathrm{mk}^{2}}{l^{2}}(1+\varepsilon) \\
& =\frac{\mathrm{mk}^{2}}{2 l^{2}}(1+\varepsilon)[1+\varepsilon-2] \\
& =\frac{m k^{2}}{2 l^{2}}(1+\varepsilon)(\varepsilon-1) \\
& =\frac{\mathrm{mk}^{2}}{2 l^{2}}\left(\varepsilon^{2}-1\right) \\
\varepsilon^{2}-1 & =\frac{2 l^{2} \mathrm{E}}{\mathrm{mk}^{2}} \Rightarrow \varepsilon^{2}=1+\frac{2 \mathrm{E} l^{2}}{\mathrm{mk}^{2}} \\
\varepsilon & =\left[1+\frac{2 \mathrm{E} l^{2}}{\mathrm{mk}^{2}}\right]^{\frac{1}{2}} \tag{6}
\end{align*}
$$

giving
such that
now $\varepsilon$ is a known one. After putting the value of $\varepsilon$ and p in equation (3) we get

$$
\begin{equation*}
r=\frac{\frac{l^{2}}{m k}}{1+\left[1+\frac{2 E l^{2}}{m k^{2}}\right]^{1 / 2} \cos \theta} \tag{7}
\end{equation*}
$$

If $\mathrm{E}>0$ giving $\varepsilon>1-$ conic is hyperbola
If $\mathrm{E}=0$ giving $\varepsilon=1-$ conic is parabola
If $\mathrm{E}<0$ giving $\varepsilon<1-$ conic is ellipse
If $\mathrm{E}=\frac{-\mathrm{mk}^{2}}{2 l^{2}}$ giving $\varepsilon=0-$ conic is circle.

## (iii) Case of elliptic orbits:

## Relation between energy and semi major axis:

In the case of elliptic orbits, semi major axis is given by:-
when $\theta=0, r=r_{1}=$ perihelion

Then

$$
\mathrm{r}_{1}=\frac{p}{1+\varepsilon}
$$

$$
\mathrm{r}=\mathrm{r}_{2}=\text { aphelion }
$$

Then

$$
\mathrm{r}_{2}=\frac{p}{1+\varepsilon}
$$

$a$ is the sum of one half of perihelion $r_{1}$ and aphelion $r_{2}$

$$
\begin{aligned}
\mathrm{a} & =\frac{\mathrm{r}_{1}+\mathrm{r}_{2}}{2} \\
& =\frac{p}{2}\left[\frac{1}{1+\varepsilon}+\frac{1}{1-\varepsilon}\right] \\
& =\frac{p}{2}\left[\frac{1-\varepsilon+1+\varepsilon}{1-\varepsilon^{2}}\right] \\
& =\frac{p}{\left(1-\varepsilon^{2}\right)}
\end{aligned}
$$

But $\quad \mathrm{p}=\frac{l^{2}}{\mathrm{mk}}$
Hence $\quad \mathrm{a}=\frac{l^{2}}{m k\left(1-\varepsilon^{2}\right)}$
(or)

$$
1-\varepsilon^{2}=\frac{l^{2}}{m k a}
$$

Now

$$
\begin{aligned}
\mathrm{E} & =\frac{\mathrm{mk}^{2}}{2 l^{2}}\left(\varepsilon^{2}-1\right) \text { becomes } \\
& =\frac{m k^{2}}{2 l^{2}}\left[\frac{-l^{2}}{m k a}\right] \quad \text { [Fromequation (8)] } \\
\mathrm{E} & =\frac{-\mathrm{k}}{2 \mathrm{a}}
\end{aligned}
$$

which shows that all ellipses with the same major axis have the same energy.
(iv) Deduction of Kepler's second law:

Weknow

$$
\begin{gathered}
\dot{p}_{\theta}=\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{\theta}}\right)=\frac{d}{d t}\left(m r^{2} \dot{\theta}\right)=0 \\
\frac{d}{d t}\left(r^{2} \dot{\theta}\right)=0
\end{gathered}
$$



$$
\begin{aligned}
\frac{d}{d t}\left(\frac{1}{2} r^{2} \dot{\theta}\right) & =0 \\
\frac{1}{2} \mathrm{r}^{2} \dot{\theta} & =\text { constant }
\end{aligned}
$$

ie
Areal velocity = constant

The area swept out by radius vector per unit time $=$ constant.
If $r$ describes an angle $d \theta$ in time $d t$, the area swept out by $r$ in time $d t$ is

$$
\begin{aligned}
d A & =\frac{1}{2} r(r d \theta)=\frac{1}{2} r^{2} d \theta \\
\frac{d A}{d t} & =\frac{1}{2} r^{2} \frac{d \theta}{d t} \\
& =\frac{1}{2} r^{2} \frac{d \theta}{d t} \\
& =\frac{1}{2} r^{2} \dot{\theta}=\text { constant }
\end{aligned}
$$

which is Kepler's second law.

## (v) Deduction of third law : (period of elliptic motion $\tau$ )

$\tau$ is the ratio of the total area of the ellipse to the rate at which the area is swept out. Suppose dA is the area swept out by radius vector is time dt, then the rate will be $d A / d t$.

Hence

$$
\tau=\frac{\text { area }}{d A / d t}
$$

Area of the ellipse $=\pi \mathrm{ab}$

$$
\text { And } \quad \frac{d A}{d t}=\frac{1}{2} r^{2} \dot{\theta}=\frac{l}{2 m}
$$

$$
\begin{aligned}
& \frac{d A}{d t}=\frac{1}{2} r^{2} \dot{\theta}=\frac{l}{2 m} \\
& \therefore \tau=\frac{\pi \mathrm{ab}}{l / 2 \mathrm{~m}}=\frac{2 \pi \mathrm{mab}}{l}
\end{aligned}
$$

putting

$$
\mathrm{b}=\mathrm{a}\left(1-\varepsilon^{2}\right)^{\frac{1}{2}}
$$

Then

$$
\begin{aligned}
\tau & =\frac{2 \pi \mathrm{ma}^{2}}{l}\left(1-\varepsilon^{2}\right)^{\frac{1}{2}} \\
\tau^{2} & =\frac{4 \pi^{2} \mathrm{~m}^{2} \mathrm{a}^{4}}{l^{2}}\left(1-\varepsilon^{2}\right) \\
& =\frac{4 \pi^{2} \mathrm{~m}^{2} \mathrm{a}^{4}}{l^{2}} \frac{l^{2}}{\mathrm{mka}}
\end{aligned}
$$

$$
\begin{aligned}
&=\left(\frac{4 \pi^{2} \mathrm{~m}}{\mathrm{k}}\right) \mathrm{a}^{3} \\
& \tau^{2} \propto \mathrm{a}^{3}
\end{aligned}
$$

Which is Kepler's third law. It states that the square of period is proportional to cube of the semi-major axis.

### 3.7 SCATTERING IN CENTRAL FORCE FIELD:

(i) Rutherford scattering:

## Assumptions:

1. The heavy nucleus and the positively charged particle to be point nucleus so that their dimensions are not taken into account.
2. The nucleus of the atom is so heavy that it is at rest during collision.
3. The mass of the positively charged particle may be taken as constant because the velocity is very small compared with the velocity of light.


Let a positively charged particle of charge z'e approach a heavy nucleus N of charge ze. There will be a force of repulsion between them. The force increases as the particle gets closer to the nucleus. The positively charged particle of initial velocity $\mathrm{v}_{\mathrm{o}}$ is repelled by the heavy nucleus and changes from a straight line to a hyperbola PAQ having one focus at N . The asymptotes PO and OQ give the initial and final directions of the particle. As the initial and final directions are not the same, the particle is said to be scattered.

The perpendicular distance of PO from $\mathrm{N}=\mathrm{MN}=\mathrm{s}$. This is the shortest distance from the nucleus to the initial direction called impact parameter.

The equation of the orbit

$$
\begin{aligned}
& \frac{1}{r}=\frac{1}{p}\left[1+\varepsilon \cos \left(\theta-\theta^{\prime}\right)\right] \\
& p=\frac{l^{2}}{m k} \quad \text { and } \quad \varepsilon=\left[1+\frac{2 E l^{2}}{m k^{2}}\right]^{1 / 2}
\end{aligned}
$$

In this case $\mathrm{k}=-\mathrm{zz}^{\prime} \mathrm{e}^{2}$ and hence

$$
\begin{aligned}
& \frac{1}{p}=-\frac{m z z^{\prime} e^{2}}{l^{2}} \\
& \frac{1}{r}=-\frac{m z z^{\prime} e^{2}}{l^{2}}\left[1+\varepsilon \cos \left(\theta-\theta^{\prime}\right)\right]
\end{aligned}
$$

If the initial line is set such that $\theta^{\prime}=0$, then

$$
\begin{aligned}
\frac{1}{r} & =-\frac{m z z^{\prime} e^{2}}{l^{2}}[1+\varepsilon \cos \theta] \\
\varepsilon & =\left[1+\frac{2 E l^{2}}{m k^{2}}\right]^{1 / 2} \\
& =\left[1+\frac{2 E l^{2}}{m\left(-z z^{\prime} e^{2}\right)^{2}}\right]^{1 / 2} \\
& =\left[1+\frac{2 E l^{2}}{m z^{2} z^{\prime 2} e^{4}}\right]^{1 / 2}
\end{aligned}
$$

If the initial velocity is $\mathrm{v}_{\mathrm{o}}$, then

$$
\begin{aligned}
E=\frac{1}{2} m \mathrm{v}_{o}^{2} & \text { and } \\
l=m \mathrm{v}_{o} s & =\sqrt{2 m E} \\
& \text { and } \\
& m \mathrm{v}_{o}=\frac{l}{s}
\end{aligned}
$$

According to principle of conservation of angular momentum

$$
\begin{aligned}
& m \mathrm{v}_{o} s=m r^{2} \dot{\theta}=l \\
& m \mathrm{v}_{o}=\frac{l}{s}
\end{aligned}
$$

$$
\begin{aligned}
& \frac{l}{\mathrm{~s}}=\sqrt{2 \mathrm{mE}} \\
& l=s \sqrt{2 m E} \\
& \varepsilon=\left[1+\frac{2 E(s \sqrt{2 m E})^{2}}{m z^{2} z^{\prime 2} e^{4}}\right]^{1 / 2} \\
& =\left[1+\left(\frac{2 E s}{z z^{\prime} e^{2}}\right)^{2}\right]^{1 / 2}
\end{aligned}
$$

From this equation it is clear that $\varepsilon>1$.

$$
\therefore \frac{1}{r}=-\frac{m z z^{\prime} e^{2}}{l^{2}}[1+\varepsilon \cos \theta]
$$

represents a hyperbola.

## (ii) Angle of scattering:

The angle between initial and final directions of the positively charged particle is called angle of scattering. That is the angle between the asymptotes is called angle of scattering. Here $\phi$ is the angle of scattering.

The asymptotic directions are those for which r is infinite and $\theta \rightarrow \infty$,

$$
\begin{aligned}
1+\varepsilon \cos \alpha & =0 \\
\cos \alpha & =-\frac{1}{\varepsilon}
\end{aligned}
$$

From figure

$$
\phi+2 \alpha=\pi
$$

$$
\begin{aligned}
\alpha & =\frac{\pi}{2}-\frac{\phi}{2} \\
\therefore \cos \left(\frac{\pi}{2}-\frac{\phi}{2}\right) & =-\frac{1}{\varepsilon} \\
\sin \frac{\phi}{2} & =-\frac{1}{\varepsilon} \\
\operatorname{cosec} \frac{\phi}{2} & =-\varepsilon
\end{aligned}
$$

$$
\begin{aligned}
\operatorname{cosec}^{2} \frac{\phi}{2} & =\varepsilon^{2} \\
1+\cot ^{2} \frac{\phi}{2} & =\varepsilon^{2}=1+\left[\frac{2 E s}{z z^{\prime} e^{2}}\right]^{2} \\
\cot ^{2} \frac{\phi}{2} & =\left[\frac{2 E s}{z z^{\prime} e^{2}}\right]^{2} \\
\cot \frac{\phi}{2} & =\left[\frac{2 \mathrm{Es}}{\mathrm{zz}^{\prime} \mathrm{e}^{2}}\right] \\
\phi & =2 \cot ^{-1}\left[\frac{2 \mathrm{Es}}{\mathrm{zz} \mathrm{e}^{2}}\right]
\end{aligned}
$$

This equation gives $\phi$ in terms of impact parameter s, energy $E$, the charge on the nucleus ze and the charge on the particle $\mathrm{z}^{\prime} \mathrm{e}$.

## (v) Rutherford scattering cross section:

The scattering cross section is defined as
$\sigma(\omega) d \omega=\frac{\text { number of particles scattered into a solid angle } \mathrm{d} \omega \text { per unit time }}{\text { incident intensity }}$
$\mathrm{d} \omega$ is the element of solid angle $\sigma(\omega)$ is the differential scattering cross section.

The incident intensity is defined as the number of particles crossing unit area normal to the incident beam in unit time.

The differential of solid angle $\mathrm{d} \omega$ in the plane whose azimuth lies between $\theta$ and $\theta+\mathrm{d} \theta$ is $\quad d \omega=2 \pi \sin \phi d \phi$

The scattering cross section through angle $\phi$ in any plane is

$$
\sigma(\omega) d \omega=\int_{o}^{2 \pi} \sigma(\phi) \sin \phi d \phi d \theta=2 \pi \sigma(\phi) \sin \phi \mathrm{d} \phi
$$

The number of particles scattered into solid angle $\mathrm{d} \omega$ per unit time $=2 \pi \mathrm{I} \sigma(\phi) \sin \phi \mathrm{d} \phi$ I is the incident intensity.

The cross section for the particles having collision parameter between s and $\mathrm{s}+\mathrm{ds}$ is the area of ring of radius $s$ and width ds so that

$$
\sigma(s, d s)=2 \pi s d s
$$

The number of particles lying between $s$ and $s+d s=2 \pi$ Is $d s$

$$
\text { Now } 2 \pi \mathrm{Is} \mathrm{ds}=-2 \pi \mathrm{I} \sigma(\phi) \sin \phi \mathrm{d} \phi
$$

The negative sign is due to the decrease in $\mathrm{d} \phi$ as the increase in ds.

$$
\begin{aligned}
\sigma(\phi) & =-\frac{\operatorname{sds}}{\sin \phi \mathrm{d} \phi} \\
\cot \frac{\phi}{2} & =\frac{2 E s}{z z^{\prime} e^{2}} \\
\text { gives } s & =\frac{z z^{\prime} e^{2}}{2 E} \cot \frac{\phi}{2} \\
\text { Then } d s & =-\frac{z z^{\prime} e^{2}}{2 E} \operatorname{cosec} c^{2} \frac{\phi}{2} \frac{d \phi}{2} \\
\therefore \sigma(\phi) & =\frac{-\left(\frac{z z^{\prime} e^{2}}{2 E}\right) \cot \frac{\phi}{2}\left(\frac{-z z^{\prime} e^{2}}{2 E}\right) \cos e c^{2} \frac{\phi}{2} \frac{d \phi}{2}}{2 \sin \frac{\phi}{2} \cos \frac{\phi}{2} d \phi} \\
& =\frac{1}{4}\left(\frac{z z^{\prime} e^{2}}{2 E}\right)^{2} \cos e c^{4} \frac{\phi}{2}
\end{aligned}
$$

This is Rutherford scattering cross section.
The scattering cross section must be proportional to i) $\operatorname{cosec}^{4} \frac{\phi}{2}$, ii) the square of (ze), iii) the square of ( $z^{\prime} \mathrm{e}$ ) and iv) inversely proportional to square of kinetic energy (E).

## HAMILTON - JACOBI THEORY

In canonical transformation, the method involves the transformation of old set of coordinates $\left(q_{k}\right)$ to new set of coordinates $\left(Q_{k}\right)$ which are all cyclic and hence all momenta are constants provided the Hamiltonian is conserved.

In case the Hamiltonian involves time, an alternate approach is used to a canonical transformation which leads to the new Hamiltonian $H^{\prime}=0$ so that the new coordinates and momenta $Q_{k}$ and $P_{k}$ are constants. This procedure is due to Jacobi which is a transformation as well as a method itself and applied when Hamiltonian involves time.

### 3.8. HAMILTON - JACOBI EQUATION:

If we make a canonical transformation from old set of variables $\left(q_{k}, p_{k}\right)$ to a new net of variables ( $Q_{k}, P_{k}$ ), then the new equation of motion are

$$
\begin{equation*}
\dot{P}_{k}=-\frac{\partial H^{\prime}}{\partial Q_{k}} \text { and } \dot{Q}_{k}=\frac{\partial H^{\prime}}{\partial P_{k}} \tag{1}
\end{equation*}
$$

If we require that the transformed Hamiltonian $\mathrm{H}^{\prime}=0$, then equations of motion (1) assume the form

$$
\begin{gather*}
\dot{P}_{k}=0 \text { and } \dot{Q}_{k}=0 \\
P_{k}=\text { constant and } Q_{k}=\mathrm{constant} \tag{2}
\end{gather*}
$$

Thus the coordinates and momenta are constants in time and they are cyclic.
The new Hamiltonian $H^{\prime}$ is related to old Hamiltonian H by

$$
H^{\prime}=H+\frac{\partial F}{\partial t}
$$

Which will be zero when F satisfies the relation

$$
\begin{equation*}
H\left(q_{k}, p_{k}, t\right)+\frac{\partial F}{\partial t}=0 \tag{3}
\end{equation*}
$$

Where $H\left(q_{k}, p_{k}, t\right)$ is written for $H\left(q_{1}, q_{2}, \ldots q_{n}, p_{1}, p_{2}, \ldots p_{n}, t\right)$

We take the generating function F as a function of the old coordinate $q_{k}$, the new constant momenta $P_{k}$ and time tie, $F_{2}\left(q_{k}, P_{k}, t\right)$. Then

$$
\begin{equation*}
p_{k}=\frac{\partial F_{2}}{\partial q_{k}} \tag{4}
\end{equation*}
$$

Therefore

$$
\begin{array}{r}
H\left(q_{k}, \frac{\partial F_{2}}{\partial q_{k}}, t\right)+\frac{\partial F_{2}}{\partial t}=0  \tag{5}\\
F_{2}=F_{2}\left(q_{k}, P_{k}, t\right)
\end{array}
$$

The total time derivative of $\mathrm{F}_{2}$ is

$$
\frac{d F_{2}}{d t}=\sum_{k=1}^{n} \frac{\partial F_{2}}{\partial q_{k}} \dot{q}_{k}+\sum_{k=1}^{n} \frac{\partial F_{2}}{\partial P_{k}} \dot{P}_{k}+\frac{\partial F_{2}}{\partial t}
$$

$$
\text { Here } \dot{P}_{k}=0, \frac{\partial F_{2}}{\partial t}=-H \text { and } \frac{\partial F_{2}}{\partial q_{k}}=p_{k}
$$

Therefore

$$
\begin{align*}
& \frac{d F_{2}}{d t}=\sum_{k=1}^{n} p_{k} \dot{q}_{k}-H=L \\
& \text { (or) } F_{2}=\int L d t=S \tag{6}
\end{align*}
$$

$$
=\text { Hamilton's principal function }
$$

Put $F_{2}=S$ in equation (5), we get $\quad H\left(q_{k}, \frac{\partial S}{\partial q_{k}}, t\right)+\frac{\partial S}{\partial t}=0$

This is known as Hamilton - Jacobi equation. It is a partial differential equation of first order in ( $\mathrm{n}+1$ ) variables $q_{1}, q_{2}, \ldots q_{n}, t$.

## Solution to Hamilton - Jacobi Equation :

Let the solution of equation (7) be of the form

$$
\begin{equation*}
S=S\left(q_{1}, q_{2}, \ldots q_{n}, \alpha_{1}, \alpha_{2}, \ldots \alpha_{n}, t\right) \tag{8}
\end{equation*}
$$

Where $\alpha_{1}, \alpha_{2}, \ldots \alpha_{n}$ are n independent constants of integration.

In equation (8), the solution S is a function of n co-ordinates of $q_{k}$, time t and n independent constants. We can take these n constants of integration as the new constant momenta

$$
\begin{equation*}
\text { ie } \quad P_{k}=\alpha_{k} \tag{9}
\end{equation*}
$$

Now the n transformation equation are

$$
\begin{equation*}
p_{k}=\frac{\partial S\left(q_{1}, q_{2}, \ldots q_{n}, \alpha_{1}, \alpha_{2}, \ldots \alpha_{n}, t\right)}{\partial q_{k}} \tag{10}
\end{equation*}
$$

These are n equations at $\mathrm{t}=\mathrm{t}_{0}$ give the n values of in terms of $\alpha_{k}$ in terms of $q_{k}$ and $p_{k}$. The other n transformation equations are

$$
\begin{align*}
& Q_{k}=\frac{\partial s}{\partial P_{k}}=\beta_{k} \\
& \beta_{k}=\frac{\partial S\left(q_{1}, q_{2}, \ldots q_{n}, \alpha_{1}, \alpha_{2}, \ldots \alpha_{n}, t\right)}{\partial \alpha_{k}} \tag{11}
\end{align*}
$$

Similarly one can calculate the constants $\beta_{k}$ by using initial condition at $t=t_{0}$, the known initial values of $q_{k}$. Thus $\alpha_{k}$ and $\beta_{k}$ constants are known and equation (10) will give $q_{k}$ in terms of $\alpha_{k}, \beta_{k}$ and t. that is

$$
\begin{equation*}
q_{k}=q_{k}\left(\alpha_{1}, \alpha_{2}, \ldots \alpha_{n}, \beta_{1,}, \beta_{2} \ldots \beta_{n}, t\right) \tag{12}
\end{equation*}
$$

On differentiation of equation (10), equation (12) may be substituted for $q_{k}$ to obtain momenta $p_{k}$. Thus $p_{k}$ will be obtained as function of constants $\alpha_{k}, \beta_{k}$ and t That is

$$
\begin{equation*}
p_{k}=p_{k}\left(\alpha_{1}, \alpha_{2}, \ldots \alpha_{n}, \beta_{1}, \beta_{2} \ldots \beta_{n}, t\right) \tag{13}
\end{equation*}
$$

Thus we see that the Hamilton's principal function S is the generaor of a canonical transformation to constant coordinates $\left(\beta_{k}\right)$ and momenta $\left(q_{k}\right)$. Also in solving the Hamilton- Jacobi equation, we obtain simultaneously a solution to the mechanical problem.

### 3.9 SOLUTION OF HARMONIC OSCILLATOR PROBLEM BY HAMILTON JACOBI METHOD:-

Consider a one - dimensional Harmonic oscillator. For such a system forces are conservative. The force acting on the oscillator at a displacement q is

$$
\begin{gathered}
f=-k q \\
\mathrm{k}=\text { Force constant. } \\
\text { Potential energy } V=\int_{o}^{q}-k q d q=\frac{1}{2} k q^{2} \\
\text { Kinetic energy } T=\frac{1}{2} m v^{2}=\frac{p^{2}}{2 m}
\end{gathered}
$$

Hamiltonian $\quad H=T+V$

$$
=\frac{p^{2}}{2 m}+\frac{1}{2} k q^{2}
$$

But $P=\frac{\partial S}{\partial q}$ and therefore

$$
H=\frac{1}{2 m}\left(\frac{\partial S}{\partial q}\right)^{2}+\frac{1}{2} k q^{2}
$$

Hence the Hamilton - Jacobi equation corresponding to the Hamiltonian is

$$
\begin{align*}
& H+\frac{\partial S}{\partial t}=0 \\
& \frac{1}{2 m}\left(\frac{\partial S}{\partial q}\right)^{2}+\frac{1}{2} k q^{2}+\frac{\partial S}{\partial t}=0 \tag{1}
\end{align*}
$$

Since we can separate the variables, solution will be of the form

$$
\begin{equation*}
S(q, \alpha, t)=W(q, \alpha)-\alpha t \tag{2}
\end{equation*}
$$

$\alpha$ is a constant.

$$
\frac{\partial S}{\partial q}=\frac{\partial W}{\partial q} \text { and } \frac{\partial S}{\partial t}=-\alpha
$$

Now equation (1) takes the form

$$
\begin{align*}
& \frac{1}{2 m}\left(\frac{\partial W}{\partial q}\right)^{2}+\frac{1}{2} k q^{2}=\alpha  \tag{3}\\
& \frac{1}{2 m}\left(\frac{\partial W}{\partial q}\right)^{2}=\left(\alpha-\frac{1}{2} k q^{2}\right) \\
& \left(\frac{\partial W}{\partial q}\right)^{2}=2 m\left(\alpha-\frac{1}{2} k q^{2}\right) \\
& \frac{\partial W}{\partial q}=\sqrt{2 m\left(\alpha-\frac{1}{2} k q^{2}\right)}
\end{align*}
$$

On integrating we get

$$
\begin{aligned}
& \mathrm{W}=\int \sqrt{2 m\left(\alpha-\frac{1}{2} k q^{2}\right)} d q+c \\
& \mathrm{c}=\text { constant of integration }
\end{aligned}
$$

$$
\text { Then } \mathrm{S}=\int \sqrt{2 m\left(\alpha-\frac{1}{2} k q^{2}\right)} d q-\alpha t+c
$$

c is an additive constant and will not affect the transformation. Because to obtain the new positon coordinate $\beta=\frac{\partial S}{\partial \alpha}$ only partial derivative of S w. r. to $\alpha$ is required. Hence c is dropped. Thus

$$
\begin{equation*}
\mathrm{S}=\int \sqrt{2 m\left(\alpha-\frac{1}{2} k q^{2}\right)} d q-\alpha t \tag{4}
\end{equation*}
$$

Now

$$
\alpha=\text { new momentum } \mathrm{P} \text {. }
$$

The new constant co - ordinate is obtained by the transformation.

$$
\begin{aligned}
\beta=\frac{\partial S}{\partial \alpha} & =\frac{\sqrt{2 m}}{2} \int \frac{d q}{\sqrt{\alpha-\frac{1}{2} k q^{2}}}-t \\
& =\sqrt{\frac{m}{2}} \int \frac{d q}{\sqrt{\alpha-\frac{1}{2} k q^{2}}}-t \\
& =\sqrt{\frac{m}{2}} \int \frac{d q}{\sqrt{\frac{k}{2}} \sqrt{\frac{2 \alpha}{k}-k q^{2}}}-t \\
\beta & =\sqrt{\frac{m}{k}} \int \frac{d q}{\sqrt{\frac{2 \alpha}{k}-k q^{2}}}-t \\
t+\beta & =\sqrt{\frac{m}{k}} \int \frac{d q}{\sqrt{\frac{2 \alpha}{k}-k q^{2}}} \\
& =\sqrt{\frac{m}{k}} \sin ^{-1} q \sqrt{\frac{k}{2 \alpha}} \\
\sin ^{-1} \sqrt{\frac{k}{2 \alpha}} & =\sqrt{\frac{k}{m}}(t+\beta)
\end{aligned}
$$

$$
\begin{align*}
\omega & =\sqrt{\frac{k}{m}} \\
\sin ^{-1} q \sqrt{\frac{k}{2 \alpha}} & =\omega(t+\beta) \\
q & =\sqrt{\frac{2 \alpha}{k}} \sin \omega(t+\beta)  \tag{5}\\
& =q_{0} \sin \omega(t+\beta)
\end{align*}
$$

Which is the familiar solution for the harmonic oscillator.

$$
\begin{align*}
\text { Now } p & =\frac{\partial S}{\partial q}=\frac{\partial W}{\partial q} \\
& =\sqrt{2 m\left(\alpha-\frac{1}{2} k q^{2}\right)} \\
& =\sqrt{2 m \alpha-m^{2} \omega^{2} q^{2}}  \tag{6}\\
p & =\sqrt{2 m \alpha-m^{2} \omega^{2} \frac{2 \alpha}{k} \sin ^{2} \omega(t+\beta)} \\
& =\sqrt{2 m \alpha-2 m \alpha \sin ^{2} \omega(t+\beta)} \\
& =\sqrt{2 m \alpha} \cos \omega(t+\beta)  \tag{7}\\
& =p_{0} \cos \omega(t+\beta)
\end{align*}
$$

The constants $\alpha$ and $\beta$ are to be known from initial conditions.

At $\mathrm{t}=0$ the particle is at rest
ie, $\mathrm{p}=0$ and it is at the displacement $q=q_{0}$ from the equilibrium position .
From (6) $\sqrt{2 m \alpha-m^{2} \omega^{2} q^{2}}=0$

$$
\begin{align*}
2 m \alpha & =m^{2} \omega^{2} q^{2} \\
\alpha & =\frac{1}{2} m \omega^{2} q^{2} \\
& =\frac{1}{2} k q_{0}^{2} \tag{8}
\end{align*}
$$

$$
q_{0}=\sqrt{\frac{2 \alpha}{m \omega^{2}}}=\sqrt{\frac{2 \alpha}{k}}
$$

and hence the solution (5) takes the form

$$
\begin{equation*}
q=q_{0} \sin \omega(t+\beta) \tag{9}
\end{equation*}
$$

at $t=0 q=q_{0}, \cos \omega \beta=0$ and $\sin \omega \beta=1$

$$
\omega \beta=\frac{\pi}{2} \text { (or) } \beta=\frac{\pi}{2 \omega}
$$

Thus the new constant canonical coordinate measures the initial phase angle and in the present initial conditions the initial phase $\omega \beta=\frac{\pi}{2}$.

Now equation (9) become

$$
\begin{equation*}
q=q_{0} \cos \omega t . \tag{10}
\end{equation*}
$$

Hamilton's characteristic function $\mathrm{W}(\mathrm{q}, \alpha)$ and principal function S are related by

$$
S=W(q, \alpha)-\alpha t ; \text { Also } H^{\prime}=H+\frac{\partial s}{\partial t}=H-\alpha=0
$$

$H=\alpha$ But the system is conservative.
Hence $H=E$ Thus the new canonical momentum $(P)$ is the total energy of the oscillator

## H.J method to Harmonic oscillator :

Hamilton's principal function S can he obtained as

$$
\begin{aligned}
& S=\int p d q-\alpha t \\
& P=\sqrt{2 m \alpha} \cos \omega(t+\beta) \\
& q=q_{0} \sin \omega(t+\beta) \\
&=\sqrt{\frac{2 \alpha}{k}} \sin \omega(t+\beta) \\
& d q=\omega \sqrt{\frac{2 \alpha}{k}} \cos \omega(t+\beta) d t \\
& S=\int \sqrt{2 m \alpha} \cos \omega(t+\beta)\left(\omega \sqrt{\frac{2 \alpha}{k}}\right) \cos \omega(t+\beta) d t-\alpha t
\end{aligned}
$$

$$
\begin{aligned}
& =\sqrt{2 m \alpha}\left(\omega \sqrt{\frac{2 \alpha}{k}}\right) \int \cos ^{2} \omega(t+\beta) d t-\alpha t \\
& =+2 \alpha \int \cos ^{2} \omega(t+\beta) d t-\alpha t \\
& =2 \alpha \int\left[\cos ^{2} \omega(t+\beta)-\frac{1}{2}\right] d t
\end{aligned}
$$

The Lagrangian L is given by

$$
\begin{aligned}
L & =\frac{p^{2}}{2 m}-\frac{1}{2} k q^{2} \\
& =\alpha \cos ^{2} \omega(t+\beta)-\frac{1}{2} k q_{0}^{2} \sin ^{2} \omega(t+\beta) \\
& =\alpha \cos ^{2} \omega(t+\beta)-\frac{1}{2} k \frac{2 \alpha}{k} \sin ^{2} \omega(t+\beta) \\
& =\alpha \cos ^{2} \omega(t+\beta)-\alpha \sin ^{2} \omega(t+\beta) \\
& =\alpha\left[\cos ^{2} \omega(t+\beta)-\sin ^{2} \omega(t+\beta)\right] \\
& =\alpha\left[\cos ^{2} \omega(t+\beta)-\left(1-\sin ^{2} \omega(t+\beta)\right)\right] \\
& =\alpha\left[2 \cos ^{2} \omega(t+\beta)-1\right] \\
& =2 \alpha\left[\cos ^{2} \omega(t+\beta)-\frac{1}{2}\right]
\end{aligned}
$$

There fore $\quad S=\int L d t$

Thus for Harmonic oscillator we prove that the Hamilton's principal function is the time integral of Lagrangian.

### 3.10 HAMILTON'S PRINCIPAL FUNCTION :

From the solution of Hamilton Jacobi equation, we recognize $S$, the Hamilton's principal function, as the generating function which gives rise to a canonical transformation involves constant momenta and constant co - ordinates.

Consider the total time derivative of

$$
F_{2}=F_{2}\left(q_{k}, P_{k}, t\right)
$$

$$
\frac{d F_{2}}{d t}=\sum_{k=1}^{n} \frac{\partial F_{2}}{\partial q_{k}} \dot{q}_{k}+\sum_{k=1}^{n} \frac{\partial F_{2}}{\partial P_{k}} \dot{P}_{k}+\frac{\partial F_{2}}{\partial t}
$$

$$
\text { Here } \dot{P}_{k}=0, \frac{\partial F_{2}}{\partial t}=-H \text { and } \frac{\partial F_{2}}{\partial q_{k}}=p_{k}
$$

Therefore

$$
\begin{aligned}
& \frac{d F_{2}}{d t}=\sum_{k=1}^{n} p_{k} \dot{q}_{k}-H=L \\
& \text { (or) } F_{2}=\int L d t=S
\end{aligned}
$$

S is known as the Hamilton's principal function in relation to the variational principle

### 3.11 HAMILTON'S CHARACTERISTIC FUNCTION:

## Conservative systems:-

In a particle moving under central force in which $H$ does not depend on time $t$ explicitly and hence $\mathrm{H}=$ constant $=\alpha_{1}=\mathrm{E}$. In such cases, it is Hamilton's characteristic function W. In Hamilton's principal function S, an explicit dependence on time is involved.

Hamilton - Jacobi equation for Hamilton's principal function $\mathrm{S}\left(q_{k}, \alpha_{k}, t\right)$ becomes

$$
\begin{equation*}
H\left[q_{k}, \frac{\partial S}{\partial q_{k}}\right]+\frac{\partial S}{\partial t}=0 \tag{1}
\end{equation*}
$$

We can assume the solution $S$ in the form

$$
\begin{equation*}
S\left(q_{k}, \alpha_{k}, t\right)=W\left(q_{k}, \alpha_{k}\right)-\alpha_{1} t \tag{2}
\end{equation*}
$$

There fore $\frac{\partial S}{\partial q_{k}}=\frac{\partial W}{\partial q_{k}}$ and $\frac{\partial S}{\partial t}=-\alpha_{1}$
and hence the Hamilton - Jacobi equation take the form

$$
\begin{equation*}
H\left[q_{k}, \frac{\partial W}{\partial q_{k}}\right]=\alpha_{1} \tag{3}
\end{equation*}
$$

(or)

$$
\begin{equation*}
\mathrm{H}\left[q_{1}, q_{2}, \ldots q_{n}, \frac{\partial W}{\partial q_{1}}, \frac{\partial W}{\partial q_{2}}, \ldots \frac{\partial W}{\partial q_{n}}\right]=\alpha_{1} \tag{4}
\end{equation*}
$$

This is time - independent Hamilton - Jacobi equation.

For conservative system $\mathrm{H}=\alpha_{1}=\mathrm{E}=$ =total energy of the system. Now Hamilton - Jacobi equation is written as

$$
\begin{equation*}
H\left[q_{k}, \frac{\partial W}{\partial q_{k}}\right]=E \tag{5}
\end{equation*}
$$

Equation (4) can also be obtained directly by taking W as the generating function $\mathrm{W}\left(q_{k}, P_{k}\right)$ independent of time. The transformation equation are

$$
\begin{equation*}
p_{k}=\frac{\partial W}{\partial q_{k}} \text { and } Q_{k}=\frac{\partial W}{\partial P_{k}} \tag{6}
\end{equation*}
$$

Now if the new momenta $P_{k}$ are all constant of motion $\alpha_{k}$, where $\alpha_{1}$ in particular is the constant of motion H , then $Q_{k}=\frac{\partial W}{\partial \alpha_{k}}$

The condition to determine W is that

$$
H\left(q_{k}, p_{k}\right)=\alpha_{1}
$$

Using $p_{k}=\frac{\partial W}{\partial q_{k}}$, we obtain

$$
H\left(q_{k}, \frac{\partial W}{\partial q_{k}}\right)=\alpha_{1}
$$

which is identical to equation (4).

$$
\text { Also } H^{\prime}=H+\frac{\partial W}{\partial t}
$$

But $w\left(q_{k}, p_{k}\right)$ does not involve time and hence

$$
\begin{align*}
& H^{\prime}=H=\alpha_{1}(=E)  \tag{7}\\
& W=\text { Hamilton's characteristic function. }
\end{align*}
$$

It generates a canonical transformation where all new coordinates $Q_{k}$ are cyclic because $H^{\prime}=\alpha_{1}$, depending on one of the new momenta $P_{1}=\alpha_{1}$, and does not contain any $Q_{k}$.

Now

$$
\dot{P}_{k}=-\frac{\partial H^{\prime}}{\partial Q_{k}}=0(o r) P_{k}=\alpha_{k}
$$

and

$$
\begin{equation*}
\dot{Q}_{k}=\frac{\partial H^{\prime}}{\partial \alpha_{k}}=1 \text { for } k=1 \tag{8}
\end{equation*}
$$

$$
\dot{Q}_{k}=\frac{\partial H^{\prime}}{\partial \alpha_{k}}=0 \text { for } k \neq 1
$$

Hence the solution are

$$
\begin{align*}
& Q_{1}=t+\beta_{1}=\frac{\partial W}{\partial \alpha_{1}} \text { for } k=1 \\
& Q_{k}=\beta_{k}=\frac{\partial W}{\partial \alpha_{k}} \text { for } k \neq 1 \tag{9}
\end{align*}
$$

and

Thus out of all the new coordinates $Q_{k}, Q_{1}$ is the only coordinate which is not a constant of motion. Here we observe the conjugate relationship between the time as the new coordinate and Hamiltonian as the conjugate momentum.

## Physical significance of the Hamilton's characteristic function W:-

The function W has a physical significance similar to the Hamilton's principal function S . since $\mathrm{W}\left(q_{k}, P_{k}\right)$ does not involve time t explicitly, its total time derivative is

$$
\frac{d W}{d t}=\sum_{k=1}^{n} \frac{\partial W}{\partial q_{k}} \dot{q}_{k}+\sum_{k=1}^{n} \frac{\partial W}{\partial P_{k}} \dot{P}_{k}
$$

Since

$$
P_{k}=\alpha_{k} \Rightarrow \dot{P}_{k}=0 \text { and therefore }
$$

$$
\begin{align*}
& \frac{d W}{d t}=\sum_{k=1}^{n} p_{k} \dot{q}_{k} \\
& W=\int \sum_{k} p_{k} \dot{q}_{k} d t=\int \sum_{k} p_{k} d q_{k} \tag{10}
\end{align*}
$$

Which is the action.

$$
\text { and } \begin{aligned}
S & =\int L d t=\int \sum_{k}\left[p_{k} \dot{q}_{k}-H\right] d t \\
& =W-\int H d t
\end{aligned}
$$

When H does not involve time t explicitly

$$
\int H d t=\alpha_{1} t
$$

Now

$$
S=W-\alpha_{1} t
$$

$$
\begin{align*}
& S\left(q_{k}, \alpha_{k}, t\right)=W\left(q_{k}, \alpha_{k}\right)-\alpha_{1} t \\
& S\left(q_{k}, t\right)=W\left(q_{k}\right)-\alpha_{1} t \tag{11}
\end{align*}
$$

Here $\quad \begin{aligned} & p_{k}=\alpha_{k} \text { are constants. } \\ & \\ & \alpha_{1}=\mathrm{E}=\text { total energy. }\end{aligned}$
When the Hamiltonian does not involve time explicitly, one can solve a mechanical problem by using either Hamilton's principal function (or) Hamilton's characteristic function.

### 3.12 ACTION AND ANGLE VARIABLES:

In the motion of a system with many degrees of freedom the Hamilton- Jacobi equation is completely separable in coordinate variables. We consider conservative system in which the Hamiltonian does not involve time explicitly. The Hamilton-Jacobi equation is given by

$$
\begin{equation*}
H\left(q_{1}, q_{2}, \ldots \ldots . . q_{n} ; \frac{\partial W}{\partial q_{1}}, \frac{\partial W}{\partial q_{2}}, \ldots \ldots \ldots . \frac{\partial W}{\partial q_{n}}\right)=\alpha_{1} \tag{1}
\end{equation*}
$$

The variables $q_{k}$ are separable, if a solution of the form

$$
\begin{equation*}
W=\sum_{k} W_{k}\left(q_{k} ; \alpha_{1}, \alpha_{2}, \ldots . . \alpha_{n}\right) \tag{2}
\end{equation*}
$$

splits the equation into $n$ equations:

$$
\begin{equation*}
H_{k}\left(q_{k} ; \frac{\partial W_{k}}{\partial q_{k}} ; \alpha_{1}, \alpha_{2}, \ldots . \alpha_{n}\right)=\alpha_{1} \tag{3}
\end{equation*}
$$

Each of equations (3) involves only one of the coordinates $\mathrm{q}_{\mathrm{k}}$ and the corresponding $\frac{\partial W_{k}}{\partial q_{k}}$ The equations of canonical transformation has the form

$$
\begin{equation*}
p_{k}=\frac{\partial W_{k}\left(q_{k} ; \alpha_{1}, \alpha_{2} \ldots \ldots \alpha_{n}\right)}{\partial q_{k}} \tag{4}
\end{equation*}
$$

it gives

$$
\begin{equation*}
p_{k}=\left(p_{k} ; \alpha_{1}, \alpha_{2}, \ldots . . \alpha_{n}\right) \tag{5}
\end{equation*}
$$

Equation (5) represents the orbit equation of the projection of the representative point of the system on the $\left(q_{k}, p_{k}\right)$ plane in the phase space. Now action-angle variables can be defined if the orbit equations for all the $\left(p_{k}, q_{k}\right)$ pairs describe either closed orbits or periodic functions of $\mathrm{q}_{\mathrm{k}}$.

The action variables $\mathbf{J}_{\mathrm{k}}$ are defined as $J_{k}=\oint p_{k} d q_{k}$
Here the integration is to be carried out over a complete period.
Suppose $\mathrm{q}_{\mathrm{k}}$ is cyclic coordinate, then $p_{k}=$ constant.
If $q_{k}$ is angle coordinate, then integral for action variable is to be taken from 0 to $2 \pi$ giving.

$$
\begin{align*}
J_{k} & =p_{k} \int_{0}^{2 \pi} d q_{k}=2 \pi p_{k}  \tag{7}\\
\text { Since } \quad \text { action } \quad A & =\int_{k} \Sigma p_{k} \dot{q}_{k} d t=\int_{k} \Sigma p_{k} d q_{k}
\end{align*}
$$

Using equation (4), we obtain

$$
\begin{equation*}
J_{k}=\oint \frac{\partial W_{k}}{\partial q_{k}}\left(q_{k} ; \alpha_{1}, \alpha_{2}, \ldots \ldots \ldots \alpha_{n}\right) d q_{k} \tag{8}
\end{equation*}
$$

Since $\mathrm{q}_{\mathrm{k}}$ is a variable of integration and it will be out, when integration is over. Thus $\mathrm{J}_{\mathrm{k}}$ is a function of the n constants $\alpha_{k}$. Thus
(or)

$$
\begin{equation*}
J_{k}=J_{k}\left(\alpha_{1}, \alpha_{2}, \ldots \ldots . \alpha_{n}\right) \tag{9}
\end{equation*}
$$

$$
\begin{equation*}
\alpha_{k}=\alpha_{k}\left(J_{1}, J_{2}, \ldots \ldots J_{n}\right) \tag{10}
\end{equation*}
$$

Thus the Hamilton's characteristic function is

$$
\left.\begin{array}{rl}
W & =W\left(q_{1}, q_{2}, \ldots \ldots . . q_{n} ; J_{1}, J_{2}, \ldots . J_{n}\right) \\
=\sum_{k} W_{k}\left(q_{k} ; J_{1,}, J_{k, \ldots}, \ldots . J_{n}\right)
\end{array}\right\}, \begin{aligned}
& \text { and } \quad \alpha_{1}=\alpha_{1}\left(J_{1}, J_{2}, \ldots \ldots J_{n}\right) \\
& H=H^{\prime}=
\end{aligned} \alpha_{1} \quad \begin{aligned}
& \therefore H^{\prime}=H^{\prime}\left(J_{1}, J_{2}, \ldots \ldots J_{n}\right) \tag{12}
\end{aligned}
$$

The generalized coordinate $\omega_{\mathrm{k}}$ conjugate to $\mathrm{J}_{\mathrm{k}}$ is defined as angle variable, given by

$$
\begin{equation*}
\omega_{k}=\frac{\partial W}{\partial J_{k}}=\sum_{1=1}^{n} \frac{\partial W_{l}}{\partial J_{k}}\left(q_{1} ; J_{1}, J_{2}, \ldots \ldots . . J_{n}\right) \tag{13}
\end{equation*}
$$

Now the equation of motions for the angle variables are

$$
\begin{align*}
\dot{\omega}_{k} & =\frac{\partial H}{\partial J_{k}}\left(J_{1}, J_{2}, \ldots \ldots J_{n}\right) \\
& =v_{k}\left(J_{1}, J_{2}, \ldots \ldots J_{n}\right) \tag{14}
\end{align*}
$$

This gives solution of the form

$$
\begin{equation*}
\omega_{k}=v_{k} t+\beta_{k} \tag{15}
\end{equation*}
$$

$v_{k}^{\prime} s$ are constants and functions of action variables only and are frequencies of the periodic motion. Here the frequencies of the periodic motion can be obtained without complete solution of the problem.

Suppose that the change in angle variable $\omega_{\mathrm{k}}$ with the completion of one cycle by $\mathrm{q}_{l}$ is $\Delta_{l} \omega_{\mathrm{k}}$, then

Using

$$
\Delta_{l} \omega_{k}=\oint \frac{\partial \omega_{k}}{\partial q_{l}} d q_{l}
$$

$$
\omega_{k}=\frac{\partial W}{\partial J_{k}} \text { we get }
$$

$$
\Delta_{1} \omega_{k}=\oint \frac{\partial^{2} W_{k}}{\partial q_{l} \partial J_{k}} d q_{l}
$$

$$
=\frac{\partial}{\partial J_{k}} \oint \frac{\partial W}{\partial q_{l}} d q_{l}
$$

$$
=\frac{\partial}{\partial J_{k}} \oint p_{l} d q_{l}
$$

$$
=\frac{\partial J_{l}}{\partial J_{k}}=\delta_{k l}
$$

$$
\text { Thus } \left.\begin{array}{rl}
\Delta_{k} \omega_{k} & =1  \tag{16}\\
& \mathrm{k}=l \\
& =0
\end{array} \quad \mathrm{k} \neq l \quad\right\}
$$

$\tau_{\mathrm{k}}$ is the period corresponding to $\mathrm{q}_{\mathrm{k}}$ then
using equation (15), $\quad \Delta_{k} \omega_{k}=v_{k} \Delta t_{k}=v_{k} \tau_{k}$
But $\Delta_{k} \omega_{k}=1$ hence

$$
\begin{equation*}
\mathrm{v}_{k} \tau_{k}=1 \text { (or) } \mathrm{v}_{k}=\frac{1}{\tau_{k}}=\omega_{k} \tag{18}
\end{equation*}
$$

Thus $v_{k}^{\prime} s$ are identified to the frequencies of the periodic motion.

### 2.13 KEPLER'S PROBLEM IN ACTION-ANGLE VARIABLES:

For a particle of mass m , moving in an inverse square force field $\left[V(r)=-\frac{k}{r}\right.$ ], the Hamiltonian of the system is given by

$$
H=\frac{1}{2 m}\left[p_{r}{ }^{2}+\frac{p_{\theta}^{2}}{r^{2}}\right]-\frac{k}{r}
$$

Determine the frequency by the method of action-angle variables and discuss degeneracy. Show that the period of the orbit is given by

$$
\tau=\pi k \sqrt{-\frac{m}{2 E^{3}}}
$$

## Solution :

The action variable $\mathrm{J}_{\mathrm{k}}$ are given by

$$
\mathrm{J}_{\mathrm{k}}=\oint \mathrm{p}_{\mathrm{k}} \mathrm{dq}_{\mathrm{k}}
$$

In the case of Kepler's problem, the action variables are given by
and

$$
J_{\theta}=\oint p_{\theta} d \theta
$$

$$
\begin{aligned}
& J_{r}=\oint p_{r} d r \\
& p_{\theta}=\frac{\partial W}{\partial \theta}=\alpha_{2}
\end{aligned}
$$

and therefore

$$
J_{\theta}=\oint \frac{\partial W}{\partial \theta} d \theta=\oint \alpha_{2} d \theta=\int_{0}^{2 \pi} \alpha_{2} d \theta=2 \pi \alpha_{2}
$$

$$
p_{r}=\frac{\partial W}{\partial r}=\sqrt{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}}
$$

Where we have replaced E by $\alpha_{1}$

$$
\begin{aligned}
\therefore J_{r} & =\oint p_{r} d_{r}=\oint \frac{\partial W}{\partial r} d r \\
& =\oint \sqrt{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha^{2}{ }_{2}}{r^{2}}} d r
\end{aligned}
$$

The motion is bounded and is elliptical path for negative value of the total energy E. Further the limits are given by $r_{\text {min }}$ and $r_{\text {max }}$ values of $r$.

These values are determined by the zero of the quadratic equation in

$$
\left.\begin{array}{c}
\int \frac{\alpha_{2} d r}{r^{2} \sqrt{2 m E+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}}}=\theta-\beta_{2} . \\
\text { ie } \sqrt{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}}=0 \\
2 m \alpha_{1} r^{2}+2 m k r-\alpha_{2}^{2}=0 \\
r^{2}+\frac{k}{\alpha_{1}} r-\frac{\alpha_{2}^{2}}{2 m \alpha_{1}}=0 \\
r=\frac{-k}{2 \alpha_{1}} \pm \frac{1}{2 \alpha_{1}} \sqrt{k^{2}+\frac{2 \alpha_{1} \alpha_{2}^{2}}{m}} \\
=\frac{k}{2 \alpha_{1}}\left[-1 \pm \sqrt{1+\frac{2 \alpha_{1} \alpha_{2}^{2}}{m k^{2}}}\right] \\
\text { ie } r_{\min }= \\
r_{\max }=\frac{k}{2 \alpha_{1}}\left[-1-\sqrt{\left.\frac{1+2 \alpha_{1} \alpha_{2}^{2}}{m k^{2}}\right]}\right. \text { and } \\
2 \alpha_{1}
\end{array}-1+\sqrt{\frac{1+2 \alpha_{1} \alpha_{2}^{2}}{m k^{2}}}\right]
$$

In a complete cycle of the co-ordinate $r$, it varies from $r_{\text {min }}$ to $r_{\text {max }}$ and back to $r_{\text {min }}$.

Now

$$
\begin{aligned}
\mathrm{J}_{\mathrm{r}} & =2 \int_{r_{\min }}^{r_{\max }} \sqrt{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}} d r \\
& =2 \int_{r_{\min }}^{r_{\max }} \frac{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}}{\sqrt{2 m \alpha_{1}+\frac{2 m k}{r}-\frac{\alpha_{2}^{2}}{r^{2}}}} d r \\
& =2 \int_{r_{\min }}^{r_{\max }} \frac{2 m \alpha_{1} r+2 m k}{\sqrt{2 m \alpha_{1} r^{2}+2 m k r-\alpha_{2}^{2}}} d r-2 \alpha_{2}^{2} \int \frac{d r}{r \sqrt{2 m \alpha_{1} r^{2}+2 m k r-\alpha_{2}^{2}}} \\
\mathrm{~J}_{\mathrm{r}} & =\frac{2 \pi \mathrm{mk}}{\sqrt{\left(-2 \mathrm{~m} \alpha_{1}\right)}}-2 \pi \alpha_{2} \\
\mathrm{~J}_{\theta}+\mathrm{J}_{\mathrm{r}} & =\frac{2 \pi m k}{\sqrt{-2 m \alpha_{1}} \Rightarrow-2 m \alpha_{1}=\frac{(2 \pi m k)^{2}}{\left(J_{\theta}+J_{r}\right)^{2}}} \\
& \alpha_{1}=-\frac{2 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{2}}
\end{aligned}
$$

But $\mathrm{H}=\mathrm{H}^{\prime}=\alpha_{1}=\mathrm{E}$
Therefore $\quad H^{\prime}=E=\alpha_{1}=-\frac{2 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{2}}$

Now the frequencies $v_{\theta}$ and $v_{\mathrm{r}}$ are given by

$$
v_{\theta}=\frac{\partial H^{\prime}}{\partial J_{\theta}}=\frac{\partial}{\partial J_{\theta}}\left[\frac{-2 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{2}}\right]=\frac{4 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{3}}
$$

and

$$
v_{r}=\frac{\partial H^{\prime}}{\partial J_{r}}=\frac{\partial}{\partial J_{r}}\left[\frac{-2 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{2}}\right]=\frac{4 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{3}}
$$

Thus

$$
v_{\theta}=v_{r}=\frac{4 \pi^{2} m k^{2}}{\left(J_{0}+J_{r}\right)^{2}}
$$

The two frequencies are equal and the motion of the system is said to be degenerated.
Manonmaniam Sundaranar University, Directorate of Distance \& Continuing Education, Tirunelveli.

The period of the orbit:

$$
\begin{aligned}
\tau & =\frac{1}{r}=\frac{\left(J_{\theta}+J_{r}\right)^{3}}{4 \pi^{2} m k^{2}} \\
E & =-\frac{2 \pi^{2} m k^{2}}{\left(J_{\theta}+J_{r}\right)^{2}} \\
\left(J_{\theta}+J_{r}\right)^{2} & =-\frac{2 \pi^{2} m k^{2}}{E} \\
\left(J_{\theta}+J_{r}\right) & =\left[-\frac{2 \pi^{2} m k^{2}}{E}\right]^{\frac{1}{2}} \\
\tau & =\frac{1}{4 \pi^{2} m k^{2}}\left[-\frac{2 \pi^{2} m k^{2}}{E}\right]^{\frac{3}{2}} \\
& =\frac{1}{4 \pi^{2} m k^{2}}\left[\frac{2 \pi^{2} m k^{2}}{E}\right]\left[-\frac{2 \pi^{2} m k^{2}}{E}\right]^{\frac{1}{2}} \\
& =\frac{1}{2 \mathrm{E}}\left[-\frac{2 \pi^{2} \mathrm{mk}}{\mathrm{E}}\right]^{\frac{1}{2}} \\
& =\pi \mathrm{k}\left[-\frac{\mathrm{m}}{2 \mathrm{E}^{3}}\right]^{\frac{1}{2}}
\end{aligned}
$$

This formula agrees with Kepler's third law that the semi-major axis $a=-\frac{k}{2 E}$.

## UNIT IV : CLASSICAL STATISTICAL MECHANICS

Foundations of Statistical Mechanics: The macroscopic and microscopic states, postulate of equal a priori probability, Contact between statistics and thermodynamics; Ensemble theory: Concept of ensemble, phase space, Density function, Ensemble average, Liouville's theorem, Stationary ensemble; The microcanonical ensemble, Application to the classical ideal gas; The canonical and grand canonical ensembles, Canonical and grand canonical partition functions, Calculation of statistical quantities; Thermodynamics of a system of non-interacting classical harmonic oscillators using canonical ensemble, and of classical ideal gas using grand canonical ensemble, Energy and density fluctuations; Entropy of mixing and the Gibb's paradox, Sackur-Tetrode equation.

### 4.1 FOUNDATIONS OF STATISTICAL MECHANICS:

- Statistical mechanics is the branch of science which gives the interpretation of the macroscopic behavior of a system in terms of its microscopic properties.
- Statistical mechanics is not concerned with the actual motion of individual particle but investigates average or most probable or statistical properties of the system.
- The larger is the number of particles in the physical system considered, the more nearly correct are the statistical predictions. The smaller is the number of particles in the mechanical system, statistical mechanics cease to have meaning.
- Statistical mechanics is applicable for a system consisting large number of particles.
- There are two statistical methods known as classical statistics and Quantum statistics.
- Classical statistics explained many observed physical phenomenon like temperature , pressure ,energy etc., but could not explain several experimentally observed phenomenon like black body radiation, specific heat at low temperature etc.
- For explaining such phenomenon Bose-Einstein and Fermi-Dirac made new approach known as quantum statistics.
- Quantum statistic can be classified as,
i. Bose-Einstein statistics
ii. Fermi-Dirac statistics


### 4.2 MICROSTATE AND MACROSTATE:

## Microstate:

- The specification of individual position of phase points for each system or molecule of the ensemble.


## Macrostate:

- The specification of the number of phase points in each cell of phase space. Many different microstates may corresponds to same macrostate.
- Consider a system consists of four particles a,b,c, and d and two cells A and B. The distribution of 4 particles in two cells can be illustrated here.

| Cell A | Cell B |
| :---: | :---: |
| 4 | 0 |
| 3 | 1 |
| 2 | 2 |
| 1 | 3 |
| 0 | 4 |

(2,2)-macrostate

| ab | cd |
| :---: | :---: |
| bc | da |
| cd | ab |
| da | bc |

(3,1 macrostate)

| abc | d |
| :---: | :---: |
| bcd | a |
| cda | b |
| dab | c |

- If we interchange any two phase points from different cells we have different microstates but the same macrostate.
- If we interchange any two phase points in the same cell, we have same microstate and same macrostate.
- The number of microstates corresponding to a given macrostate in called the thermodynamic probability of the macrostate.
- The probability that the ensemble possessing energy E is proportional to $\Omega(\mathrm{E})$.

$$
\begin{aligned}
& P(E)=c \Omega(E) \\
& \mathrm{c} \rightarrow \text { proportionality constant } \\
& \Omega(\mathrm{E}) \rightarrow \text { thermodynamic probability }
\end{aligned}
$$

### 4.3 POSTULATE OF EQUAL A PRIORI PROBABILITY:

## Statement:

- The probability of finding the phase point for a given system in any one region of phase space is identical with that for any other region of equal volume.
- The necessity of this postulate arises due to incompleteness of our knowledge concerning the system of interest.
- This postulate appears to be reasonable in character with the principles of statistical mechanics derived from Liouville's theorem.
- According to the principle of conservation of density, the density of a group of phase points remains constant.
- At any time the phase points are distributed uniformly in the phase space.
- There is no crowding of phase points in any particular region of phase space
- Any arbitrary element of volume in the phase space bounded by a moving surface and containing a definite number of phase points does not change with time.
- The property of no crowding of phase points in any particular region of phase space and the constancy of volume element of phase space with time indicate the validity of the postulate.
- That is the probability of finding a phase point in any particular region of phase space is directly proportional to the volume of that region.
- The postulate replaces the postulate of equal priori probability when different volumes in the phase space are considered.


### 4.4 CONTACT BETWEEN STATISTICS AND THERMODYNAMICS : (BOLTZMANN RELATION BETWEEN ENTROPY AND PROBABILITY)

- Boltzmann used the idea that the probability of the system in equilibrium state is maximum.
- Thus in equilibrium state both the entropy and thermodynamical probability have their maximum values.
- Boltzmann concluded that the entropy ' S ' is a function of thermodynamic probability $\Omega$.

$$
\begin{equation*}
\text { ie, } \quad S=f(\Omega) \tag{1}
\end{equation*}
$$

- Consider two independent systems A and B having entropies $S_{1}$ and $S_{2}$ and thermodynamic probabilities $\Omega_{1}$ and $\Omega_{2}$.
- Entropy is an additive quantity and hence the entropy of systems together must be equal to the sum of their individual entropies.

$$
\begin{equation*}
S=S_{1}+S_{2} \tag{2}
\end{equation*}
$$

- The probability $\Omega$ of finding both systems will be the product of the two probabilities $\Omega_{1}$ and $\Omega_{2}$.

$$
\begin{equation*}
\text { ie } \quad \Omega=\Omega_{1} \Omega_{2} \tag{3}
\end{equation*}
$$

Substituting equations (2) and (3) in equation (1) we get,

$$
\begin{gather*}
S=f(\Omega)=f\left(\Omega_{1} \Omega_{2}\right)  \tag{4}\\
S=S_{1}+S_{2} \\
f\left(\Omega_{1} \Omega_{2}\right)=f\left(\Omega_{1}\right)\left(\Omega_{2}\right) \tag{5}
\end{gather*}
$$

- Differentiating with respect to $\Omega_{1}$ we get,

$$
\begin{equation*}
\Omega_{2} f^{\prime}\left(\Omega_{1} \Omega_{2}\right) f^{\prime}\left(\Omega_{1}\right) \tag{6}
\end{equation*}
$$

- Differentiating with respect to $\Omega_{2}$ we get,

$$
\begin{equation*}
\Omega_{1} f^{\prime}\left(\Omega_{1} \Omega_{2}\right)=f^{\prime}\left(\Omega_{2}\right) \tag{7}
\end{equation*}
$$

- Divide equation (7)/(6), we get

$$
\begin{gather*}
\frac{\Omega_{1}}{\Omega_{2}}=f^{\prime}\left(\Omega_{2}\right) / f^{\prime}\left(\Omega_{1}\right) \\
\Omega_{1} f^{\prime}\left(\Omega_{1}\right)=\Omega_{2} f^{\prime}\left(\Omega_{2}\right) \\
\Omega f^{\prime}(\Omega)=\text { constant }=k \\
f^{\prime}\left(\Omega_{1}\right)=\frac{k}{\Omega} \\
f(\Omega)=k \log \Omega+c \\
S=k \log \Omega+c \tag{8}
\end{gather*}
$$

Integrating,

- For a thermo dynamical system at absolute zero $\Omega=1$ and $\mathrm{S}=0$ so that $\mathrm{c}=0$.

$$
S=k \log \Omega
$$

- This gives the Boltzmann's relation between entropy and probability.
(a) Identification of constant ' $k$ ':
- Consider the expansion of one mole of an ideal gas at pressure $p_{1}$ and volume $V_{1}$ into an evacuated chamber of volume $\mathrm{V}_{2}$.
- The find pressure is $p_{2}$ and the final volume is $V_{1}+V_{2}$.
- The probability of finding one molecule in the first container with volume $V_{1}$ is,

$$
\frac{V_{1}}{V_{1}+V_{2}}
$$

- There are N molecules and hence the probability of finding one mole of the gas in the first container with volume $V_{1}$ is,

$$
\begin{equation*}
\Omega_{1}=\left[\frac{V_{1}}{V_{1}+V_{2}}\right]^{N} \tag{10}
\end{equation*}
$$

- The probability of finding one mole of the gas in the container has volume $V_{1}+V_{2}$ is

$$
\begin{equation*}
\Omega_{2}=\left[\frac{V_{1}+V_{2}}{V_{1}+V_{2}}\right]^{N}=[1]^{N} \tag{11}
\end{equation*}
$$

From Boltzmann relation

$$
\begin{align*}
\Delta S & =S_{2}-S_{1} \\
& =k \log \Omega_{2}-k \log \Omega_{1} \\
& =k \log \left(\frac{\Omega_{2}}{\Omega_{1}}\right) \\
& =k \log \left[\frac{1}{\frac{V_{1}}{V_{1}+V_{2}}}\right]^{N} \\
\Delta S & =k \log \left[\frac{V_{1}+V_{2}}{V_{1}}\right]^{N} \\
= & \log \left[\frac{V_{1}+V_{2}}{V_{1}}\right]^{N k} \tag{12}
\end{align*}
$$

- The change in entropy when the gas changes from one state with volume $V_{1}$ and temperature $T_{1}$ to another state with volume $V_{2}$ and temperature $T_{2}$ is given by,

$$
\Delta S=C_{v} \log \frac{T_{2}}{T_{1}}+R \log \left[\frac{V_{1}+V_{2}}{V_{1}}\right]
$$

For isothermal change $T_{2}=T_{1}$ and hence $C_{v} \log \frac{T_{2}}{T_{1}}=0$

$$
\begin{align*}
\Delta S= & R \log \left[\frac{V_{1}+V_{2}}{V_{1}}\right] \\
& =\log \left[\frac{V_{1}+V_{2}}{V_{1}}\right]^{R} \tag{13}
\end{align*}
$$

Comparing equation (12) and (13), we get

$$
\begin{aligned}
N k & =R \\
k & =R / N \\
& =1.03 \times 10^{-23} \mathrm{~J} / K=\text { Boltzmann's constant }
\end{aligned}
$$

### 4.5 ENSEMBLE THEORY: CONCEPT OF ENSEMBLES:

- A system is defined as a collection of identical particles.
- An ensemble is defined as a collection of macroscopically identical, but essentially independent systems.
- Macroscopically identical means each system satisfies the same macroscopic conditions ex: volume, energy, pressure etc.
- Independent systems mean the systems are non interacting.
- There are three most commonly used ensembles namely,
(i) micro canonical ensemble
(ii) canonical ensemble
(iii) grand canonical ensemble.

Micro canonical ensemble:
 essentially independent systems with same energy E , volume V , and the number of particles N .

- All the particles are identical.
- The individual systems are separated by rigid, impermeable and well insulated walls.
- No exchange of heat energy as well as the number of particles between the systems takes place.


## Canonical ensemble:

T,V,N

- Collection of large number of essentially independent systems with same temperature T , volume V and the number of particles N .
- All the particles are identical.
- The individual systems are separated by rigid, impermeable but conducting walls.
- Exchange of heat energy between the system takes place. But not the particles.


## Grand canonical ensemble:

T,

- Collection of large number of essentially independent systems with same temperature T , volume V , and the chemical potential $\mu$.
- All the particles are identical.
- The individual systems are separated by rigid, permeable and conducting walls.
- Exchange of heat energy as well as the particles between the system takes place.
- The state of any ensemble can be completely specified by a large number of phase points in the phase space called dust cloud.
- Thus the behavior of an ensemble can be represented by a large number of trajectories (or) phase lines (or) streaming motion of the dust cloud.


### 4.6 PHASE SPACE:

- The instantaneous position of a single particle is described by three independent co-ordinates $x, y$ and $z$.
- The instantaneous motion of a particle is described by momentum co- ordinates $p_{x}, p_{y}, p_{z}$.
- Thus the state of a single particle is completely specified by position co-ordinates $x, y, z$ and momentum co-ordinates $p_{x}, p_{y}, p_{z}$
- We may imagine a six dimensional space with volume $d_{x} d_{y} d_{z} d p_{x} d p_{y} d p_{z}$.
- The position of a point particle in this space can be described by a set of 6 coordinates $x$ y z $p_{x}, p_{y}, p_{z}$.
- This 6 dimensional space for a single particle is damped as phase space.( $\mu=$ space)
- If the system contains a large number of particles such that f independent position co-ordinates $q_{1}, q_{2}, \ldots \ldots \ldots, q_{f}$ and f momentum co-ordinates $p_{1}, p_{2}, \ldots \ldots ., p_{f}$, then 2 f combined position, momentum co-ordinates may be allowed to define 2fdimensional space called phase space( $\Gamma$-space)
- The $\Gamma$-space is considered to be a conceptual Euclidean space having 2 f rectangular axes and an element of volume represented by $d q_{1}, d q_{2}, \ldots \ldots, d q_{f} d p_{1}, d p_{2}, \ldots \ldots, d p_{f}$
- The instantaneous state of a particle in the phase-space is represented by a point known as phase point (or) representative point.
- The number of phase points per unit volume is known as phase density.


### 4.7 COUNTING THE NUMBER OF MICROSTATES IN THE ENERGY RANGE

## $\varepsilon$ TO $\varepsilon+d \varepsilon:$

- For a single particle we have six dimensional phase space.
- Three position co-ordinates $(x, y, z)$ and three momentum co-ordinates $\left(p_{x}, p_{y}, p_{z}\right)$ specify the microstate of a particle in the phase space.
- An element of volume in phase space is,

$$
\delta_{x} \delta_{y} \delta_{z} \delta_{p_{x}} \delta_{p_{y}} \delta_{p_{z}}=h^{3}
$$



- The total volume of phase space is $\iiint \iiint d_{x} d_{y} d_{z} d_{p_{x}} d_{p_{y}} d_{p_{z}}$
- We have $\iiint \iiint d_{x} d_{y} d_{z}=V$
- So the volume in phase space $=V \iiint d_{p_{x}} d_{p_{y}} d_{p_{z}}$
- Volume of momentum space containing momentum between p and $p+d p$ will be given by the volume of a spherical cell with radius $p$ and thickness $d p$.
- Therefore,

$$
\begin{aligned}
& \iiint d_{p_{x}} d_{p_{y}} d_{p_{z}}=4 \pi p^{2} d p \\
& \qquad=\frac{p^{2}}{2 m} \rightarrow p^{2}=2 m \varepsilon \\
& 2 p d p=2 m d \varepsilon \\
& d p=\frac{m}{\varphi} d \varepsilon \\
& \quad=\frac{m}{\sqrt{2 m \varepsilon}} d \varepsilon \quad=\sqrt{\frac{m}{2 \varepsilon}} d \varepsilon
\end{aligned}
$$

- Now volume of phase space

$$
\begin{aligned}
&= V .4 \pi p^{2} d p \\
&=V \times 4 \pi(2 m \varepsilon) \sqrt{\frac{m}{2 \varepsilon}} d \varepsilon \\
&=4 \pi V \sqrt{2} m^{3 / 2} \varepsilon^{1 / 2} d \varepsilon
\end{aligned}
$$

- The number of cells within the phase space.

$$
\text { ie, } \Omega(\varepsilon) d \varepsilon=\frac{4 \pi V \sqrt{2}}{h^{3}} m^{3 / 2} \varepsilon^{1 / 2} d \varepsilon
$$

- For a single particle the number of accessible microstates will be equal to the number of cells in phase space.
- Hence the number of microstates in this energy range $\varepsilon$ to $\varepsilon+\mathrm{d} \varepsilon$ is given by,

$$
\Omega(\varepsilon) d \varepsilon=\frac{4 \pi V \sqrt{2}}{h^{3}} m^{3 / 2} \varepsilon^{1 / 2} d \varepsilon
$$

### 4.8 TIME AND ENSEMBLE AVERAGE:

- An ensemble consists of a large number of independent systems.
- It may be represented by a particular point in phase space.
- A gas containing a large number of molecules forming a system.
- The gas molecules move constantly and hence they change the position and momentum with time.
- The entire gas shows a time independent property (eg: temperature, energy etc.) which may be considered as the average of the specified property of the constituent gas molecules .
- Here, we discuss this type of average property of the ensemble.
- Let the state of the ensemble changes with time.
- Let u be the property of the ensemble.
- u takes values $u_{1}, u_{2}, \ldots \ldots, u_{m}$ having probabilities $P_{1}, P_{2}, \ldots \ldots, P_{m}$.

$$
\begin{align*}
\bar{u} & =\frac{P_{1} u_{1}+P_{2} u_{2}+\cdots \ldots \ldots+P_{i} u_{i}+\cdots \ldots \ldots P_{m} u_{m}}{P_{1}+P_{2}+\cdots \ldots \ldots+P_{i}+\cdots \ldots \ldots P_{m}} \\
& =\frac{\sum_{i=1}^{m} P_{i} u_{i}}{\sum_{i=1}^{m} P_{i}} \tag{1}
\end{align*}
$$

- The sum of the probabilities of the all possible state must be equal to one.

$$
\begin{equation*}
\text { ie, } P_{1}+P_{2}+\cdots \ldots .+P_{i}+\cdots \ldots \ldots+P_{m}=\sum_{i=1}^{m} P_{i}=1 \tag{2}
\end{equation*}
$$

- This called normalization condition.
- Now equation (1) becomes

$$
\bar{u}=\sum_{i=1}^{m} P_{i} u_{i}
$$

- If the ensemble consists of N systems, u can be expressed as the function of all position and momentum co-ordinates of the systems.
- If the probability distribution function is continuous, then equation(1) can be expressed as,

$$
\begin{aligned}
\bar{u} & =\frac{\int u(q, p) P(q, p) d \Gamma}{\int P(q, p) d \Gamma} \\
d \Gamma & =d q_{1}, d q_{2}, \ldots \ldots \ldots, d q_{f} d p_{1}, d p_{2}, \ldots, d p_{f}
\end{aligned}
$$

$$
\int P(q, p) d \Gamma=1
$$

- Hence

$$
\bar{u}=\int u(q, p) P(q, p) d \Gamma
$$

- This gives the ensemble average.


### 4.9 LIOUVILLE'S THEOREM:

- Liouville's theorem gives information about the rate of change of phase density in the phase space. The theorem may be stated in two parts.
- The rate of change of density of phase points in the neighborhood of a moving phase point in the $\Gamma$ space is zero. This part represents the principle of conservation of density in the phase space.

$$
\begin{equation*}
d \rho / d t=0 \tag{1}
\end{equation*}
$$

- Any arbitrary element of volume or extension in phase in the $\Gamma$ space bounded by a moving surface and containing a number of phase points does not change with time. This part represents the principle of conservation of extension in the phase space.

$$
\begin{equation*}
\frac{d}{d t}(\delta \Gamma)=\frac{d}{d t}\left(\prod_{i}^{f} d q_{i} d p_{i}\right)=0 \tag{2}
\end{equation*}
$$

(i) The principle of conservation of density in the phase space:

- Consider any arbitrary hyper volume $\delta \Gamma=\delta q_{1} \delta q_{2} \ldots \ldots . \delta q_{f} \delta p_{1} \delta p_{2} \ldots \ldots . \delta p_{f}$ in the phase space located between $q_{1}$ and $q_{1}+\delta q_{1} \ldots \ldots \ldots q_{f}$ and $q_{f}+\delta q_{f}$, $p_{1}$ and $p_{1}+\delta p_{1}, \ldots \ldots \ldots p_{f}$ and $p_{f}+\delta p_{f}$. The number of phase points in this volume element changes with time due to the motion of phase points.
- If $\rho$ is the density of phase points, the number
 of phase points in this volume element at any instant t is,
$\delta N=\rho . \delta \Gamma=\rho \delta q_{1} \delta q_{2} \ldots \ldots . \delta q_{f} \delta p_{1} \delta p_{2} \ldots \ldots \ldots \delta p_{f}$
- The change in number of phase points in volume element per unit time,

$$
\begin{equation*}
\frac{d(\delta N)}{d t}=\frac{d}{d t}(\rho . \delta \Gamma)=\dot{\rho} \delta \Gamma=\dot{\rho} \delta q_{1} \delta q_{2} \ldots \ldots \delta q_{f} \delta p_{1} \delta p_{2} \ldots \ldots \ldots \delta p_{f} \tag{4}
\end{equation*}
$$

- This change in the number of phase points in the given hyper volume is due to the difference between the number of phase points entering the hyper volume through any face and the number of those leaving the opposite face per second.
- Consider two faces of hyper volume with co-ordinates $q_{1}$ and $q_{1}+\delta q_{1}$. If $\dot{q}_{1}$ is the component of velocity of phase point at $q_{1}, q_{2}, \ldots \ldots . q_{f}, p_{1}, p_{2}, \ldots \ldots \ldots p_{f}$, then the number of phase points entering the first face AD per second

$$
\begin{equation*}
=\rho \dot{q_{1}} \delta q_{2} \ldots \ldots . \delta q_{f} \delta p_{1} \ldots \ldots \delta p_{f} \tag{5}
\end{equation*}
$$

- As density $\rho$ changes with change in position and momentum co-ordinates and at the opposite face BC the co-ordinate $\mathrm{q}_{1}$ changes to $q_{1}+\delta q_{1}$ and the density $\rho$ changes to ( $\rho+\frac{\partial \rho}{\partial q_{1}} \delta q_{1}$ ) at the face BC. The velocity $\dot{q}_{1}$ changes to ( $\dot{q}_{1}+$ $\left.\frac{\partial \dot{q}_{1}}{\partial q_{1}} \delta q_{1}\right)$. Therefore the number of phase points leaving the opposite face BC at $\mathrm{q}_{1}+\delta \mathrm{q}_{1}$ per second.

$$
=\left(\rho+\frac{\partial \rho}{\partial q_{1}} \delta q_{1}\right)\left(\dot{q}_{1}+\frac{\partial \dot{q}_{1}}{\partial q_{1}} \delta q_{1}\right) \delta q_{2} \ldots \ldots \delta q_{f} \delta p_{1}, \ldots \ldots \ldots \delta p_{f}
$$

- Neglecting higher order differentials, we get

$$
\begin{equation*}
=\left[\rho \dot{q}_{1}+\left(\rho \frac{\partial \dot{q}_{1}}{\partial q_{1}}+\dot{q}_{1} \frac{\partial \rho}{\partial q_{1}}\right) \delta q_{1}\right] \delta q_{2} \ldots \ldots \delta q_{f} \delta p_{1}, \ldots \ldots \ldots \delta p_{f} \tag{6}
\end{equation*}
$$

- Subtracting (6) from (5) we get the expression for change in the number of phase points per second corresponding to $\mathrm{q}_{1}$.

$$
\begin{equation*}
=-\left(\rho \frac{\partial \dot{q}_{1}}{\partial q_{1}}+\dot{q}_{1} \frac{\partial \rho}{\partial q_{1}}\right) \delta q_{1} \delta q_{2} \ldots \ldots \delta q_{f} \delta p_{1}, \ldots \ldots \ldots \delta p_{f} \tag{7}
\end{equation*}
$$

- Similarly, the expression for the change into the number of phase points per second corresponding to $p_{1}$ is

$$
\begin{equation*}
=-\left(\rho \frac{\partial \dot{p}_{1}}{\partial p_{1}}+\dot{p}_{1} \frac{\partial \rho}{\partial p_{1}}\right) \delta q_{1} \delta q_{2} \ldots \ldots \delta q_{f} \delta p_{1}, \ldots \ldots \ldots \delta p_{f} \tag{8}
\end{equation*}
$$

- Since the change in number of phase points per second corresponding to all position and momentum coordinates are like equation (7) and (8), then they are summed up.
- The net increase in the number of phase points in the given hyper volume per second is given by,

$$
\begin{equation*}
\frac{d(\delta N)}{d t}=-\sum_{i=1}^{f}\left[\rho\left(\frac{\partial \dot{q}_{i}}{\partial q_{i}}+\frac{\partial \dot{p}_{i}}{\partial p_{i}}\right)+\left(\dot{q}_{1} \frac{\partial \rho}{\partial q_{i}}+\dot{p}_{i} \frac{\partial \rho}{\partial p_{i}}\right)\right] \delta q_{1} \ldots \delta q_{f} \delta p_{1}, \ldots \delta p_{f} \tag{9}
\end{equation*}
$$

- using equation (4)we get,

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=-\sum_{i=1}^{f}\left[\rho\left(\frac{\partial \dot{q}_{i}}{\partial q_{i}}+\frac{\partial \dot{p}_{i}}{\partial p_{i}}\right)+\left(\dot{q}_{1} \frac{\partial \rho}{\partial q_{i}}+\dot{p}_{i} \frac{\partial \rho}{\partial p_{i}}\right)\right] \tag{10}
\end{equation*}
$$

- From canonical equation,

$$
\frac{\partial \dot{q}_{i}}{\partial q_{i}}=\frac{\partial^{2} H}{\partial q_{i} \partial p_{i}} \text { and } \frac{\partial \dot{p}_{i}}{\partial p_{i}}=\frac{-\partial^{2} H}{\partial p_{i} \partial q_{i}}
$$

- Since the order of differentiation is immaterial i.e,

$$
\begin{array}{r}
\frac{\partial^{2} H}{\partial q_{i} \partial p_{i}}=\frac{\partial^{2} H}{\partial p_{i} \partial q_{i}} \\
\text { We get } \begin{array}{r}
\frac{\partial \dot{q}_{i}}{\partial q_{i}}=-\frac{\partial \dot{p}_{i}}{\partial p_{i}} \\
\sum_{i=1}^{f}\left[\frac{\partial \dot{q}_{i}}{\partial q_{i}}+\frac{\partial \dot{p}_{i}}{\partial p_{i}}\right]=0
\end{array},=0 \text {. }
\end{array}
$$

- Now equation (10) becomes

$$
\begin{gather*}
\left(\frac{\partial \rho}{\partial t}\right)_{q, p}=-\sum_{i=1}^{f}\left[\dot{q}_{1} \frac{\partial \rho}{\partial q_{i}}+\dot{p}_{i} \frac{\partial \rho}{\partial p_{i}}\right] \\
\left(\frac{\partial \rho}{\partial t}\right)_{q, p}+\sum_{i=1}^{f}\left[\frac{\partial \rho}{\partial q_{i}} \dot{q}_{1}+\frac{\partial \rho}{\partial p_{i}} \dot{p}_{i}\right]=0 \tag{12}
\end{gather*}
$$

- This equation represents Liouville's theorem.

$$
\begin{align*}
& \frac{d \rho}{d t}\left(q_{1}, \ldots ., q_{f}, p_{1}, \ldots \ldots, p_{f}, t\right)=0 \\
& \text { ie, } \frac{d \rho}{d t}=0 \tag{13}
\end{align*}
$$

- This expression represents the principle of conservation of density in phase space.


## (ii) The principle of conservation of extension in phase space:

- Consider a very small region of hyper volume $\delta \Gamma$ in the $\Gamma$ space, so that the density of phase points $\rho$ can be taken as uniform throughout the hyper volume. The number of phase points in this hyper volume, $\delta N=\rho . \delta \Gamma$

$$
\begin{gather*}
\frac{d}{d t}(\delta N)=\frac{d}{d t}(\rho . \delta \Gamma) \\
\quad=\frac{d \rho}{d t} \delta \Gamma+\rho \frac{d(\delta \Gamma)}{d t} \tag{14}
\end{gather*}
$$

- As each phase point represents a definite system and systems can neither be created nor destroyed, the number of phase points $\delta \mathrm{N}$ must remain fixed.
i.e

$$
\begin{array}{r}
\frac{d}{d t}(\delta N)=0 \\
\frac{d \rho}{d t} \delta \Gamma+\rho \frac{d(\delta \Gamma)}{d t}=0
\end{array}
$$

- from equation (14)

$$
\begin{array}{r}
\frac{d \rho}{d t}=0 \\
\rho \frac{d(\delta \Gamma)}{d t}=0 \\
\frac{d(\delta \Gamma)}{d t}=0 \\
\delta \Gamma=\text { constant } \tag{15}
\end{array}
$$

- This expression represents the principle of conservation of extension in the phase space.


## STATIONARY ENSEMBLE:

### 4.10 MICRO CANONICAL ENSEMBLE (ISOLATED SYSTEM):

- An ensemble in which each system has the same fixed energy as well as the same number of particles is called micro canonical ensemble.
- In this ensemble, density $\rho$, for a closed isolated thermo dynamical system is a function of energy and we take

$$
\begin{aligned}
\rho(E) & =\text { constant } & & \text { between the energy shells } E \text { and } E+\delta E \text { of phase space. } \\
& =0 & & \text { outside the region of phase space. }
\end{aligned}
$$

- We call this region in which $\rho(\mathrm{E})=$ constant as accessible region $\mathrm{d} \Gamma$ of phase space.
- The above choice of $\rho(\mathrm{E})$ being constant in $\mathrm{d} \Gamma$ and zero outside $\mathrm{d} \Gamma$ indicating accessibility can be justified as follows:
- Suppose we consider a gas of volume V , separated into smaller volumes $\mathrm{V}_{1}$ and $\mathrm{V}_{2}$ by a thin perfectly conducting wall of negligible heat capacity through which the particles of the gas can diffuse very slowly, hut through which energy can be exchange freely.
- Let at a particular instant, we determine the pressure in the two volumes, and let at this instant $n$ out of total $n$ particles be in volume $V_{1}$. The particles in volume $\mathrm{V}_{2}$ will be then ( $\mathrm{n}-\mathrm{n}$ ). Now,
- (i) For an experiment of short duration, it would not be appropriate to take all particles could be found with equal probability anywhere within the volume V and therefore accessible region is the region of phase space in which all the first $n$ particles are in $V_{1}$ and remaining ( $n-n$ ) are in $V_{2}$.
- (ii) For an experiment of long duration in which a considerable amount of diffusion could occur, the whole of phase space is accessible.
- Thus for short duration experiments $\mathrm{d} \Gamma$ is accessible and it is inappropriate to include in the ensemble, the assembly lying outside this region $\mathrm{d} \Gamma$, which means $\rho(\mathrm{E})=$ constant for $\mathrm{d} \Gamma$ while zero outside $\mathrm{d} \Gamma$.
- In general, all accessible regions of phase space are given equal weightage in averaging over a microcanonical ensemble. This is known as the 'Principle of equal a priori probabilities'.


## (i) Partition Function:

- Consider an assembly of ideal gas obeying classical statistics.
- Let the distribution of gas molecules be such that $n_{i}$ molecules occupy the $i^{\text {th }}$ state with energy between $\varepsilon_{i}$ and $\varepsilon_{i}+d \varepsilon_{i}$
- Let $g_{i}$ be the degeneracy of the $i^{\text {th }}$ state.
- According to M-B distribution law,

$$
\begin{aligned}
n_{i}= & g_{i} e^{-\alpha} e^{-\beta \varepsilon i} \\
& =g_{i} e^{-\alpha} e^{-\varepsilon_{i} / k T} \\
e^{-\alpha} & =A
\end{aligned}
$$

Then

$$
n_{i}=A g_{i} e^{-\varepsilon_{i} / k T}
$$

- Let the total number of gas molecules be N .

$$
\begin{aligned}
N & =\sum_{i} n_{i} . \\
& =\sum_{i} A g_{i} e^{-\varepsilon_{i} / k T} \\
& =A \sum_{i} g_{i} e^{-\varepsilon_{i} / k T} \\
\frac{N}{A} & =\sum_{i} g_{i} e^{-\varepsilon_{i} / k T} \\
Z & =\sum_{i} g_{i} e^{-\varepsilon_{i} / k T}
\end{aligned}
$$

- Z is known as partition function and Z indicates how the gas molecules of an assembly are distributed (or) partitioned among the various energy levels.
- If the energy of the $i^{\text {th }}$ level is $\varepsilon_{i}$ then the weight of an individual level is unity.

$$
\text { ie, } \begin{aligned}
g_{i} & =1 \\
Z & =\sum_{i} e^{-\varepsilon_{i} / k T}
\end{aligned}
$$

- Here the energy term may contain the rotational, vibrational and electronic components in addition to translational component.
- 'Z' can be used for calculating the various thermodynamic properties of ensembles.
- In classical treatment the energy distribution is continuous.
- The number of energy levels of the momentum interval p and $p+d p$ is given by,

$$
\begin{aligned}
g(p) d p & =\frac{V 4 \pi p^{2} d p}{h^{3}} \\
p^{2} & =2 m \varepsilon \\
2 p d p & =2 m d \varepsilon \\
d p & =\frac{m}{p} d \varepsilon \\
& =\frac{m}{\sqrt{2 m \varepsilon}} d \varepsilon \quad=\sqrt{\frac{m}{2 \varepsilon}} d \varepsilon
\end{aligned}
$$

- Now the number of energy levels in the energy range $\varepsilon$ and $\varepsilon+d \varepsilon$ is obtained as,

$$
\begin{aligned}
g(\varepsilon) d \varepsilon= & \frac{V}{h^{3}} 4 \pi(2 m \varepsilon) \sqrt{\frac{m}{2 \varepsilon}} d \varepsilon \\
& =\frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \varepsilon^{1 / 2} d \varepsilon \\
Z & =\sum_{i} g_{i} e^{-\varepsilon_{i} / k T} \\
& =\int_{0}^{\infty} g(\varepsilon) e^{-\varepsilon / k T} d \varepsilon \\
& =\int_{0}^{\infty} \frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \varepsilon^{1 / 2} e^{-\varepsilon / k T} d \varepsilon
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \int_{0}^{\infty} \varepsilon^{1 / 2} e^{-\varepsilon / k T} d \varepsilon \\
& =\frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \frac{1}{2} \sqrt{\frac{\pi}{\beta^{3}}} \\
& =\frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \frac{1}{2} \sqrt{\pi(k T)^{3}} \\
Z= & \frac{V}{h^{3}}(2 \pi m K T)^{3 / 2}
\end{aligned}
$$

- This is the translational partition function for a gas molecule.


### 4.11 CLASSICAL IDEAL GAS USING MICRO CANONICAL ENSEMBLE:

- Consider a micro canonical ensemble of a perfect gas.
- Let there be n point particles with mass m confined in a volume V with total energy u within the energy range $\delta u$.
- The corresponding volume

$$
\begin{aligned}
\Delta \Gamma & =\int d q_{1} \ldots \ldots \ldots . d q_{3 n} \int d p_{1} \ldots \ldots \ldots . d p_{3 n} \\
\int d q_{1} \ldots \ldots \ldots d q_{3 n} & =V^{n} . \\
\text { Hence } \quad \Delta \Gamma & =V^{n} \int d q_{1} \ldots \ldots \ldots . d q_{3 n}
\end{aligned}
$$

- The momentum space integral is to be evaluated subject to the constraint of the ensemble

$$
\begin{gathered}
u-\delta u \leq u_{r} \leq u . \\
u_{r}=\sum_{i=1}^{n} p_{i}^{2} / 2 m . \\
u-\delta u \leq \frac{1}{2 m} \sum_{i=1}^{n} p_{i}^{2} \leq u .
\end{gathered}
$$

- The accessible volume in momentum space is the volume of a spherical shell of radius $(2 m u)^{1 / 2}$ and thickness $\left(\frac{m}{2 u}\right)^{\frac{1}{2}} \delta u$.
- The volume of three dimensional sphere of radius ' $R$ ' is,

$$
\begin{aligned}
& V_{3}(R)=\frac{4}{3} \pi R^{3}=\frac{\pi^{3 / 2}}{\Gamma\left(\frac{3}{2}+1\right)} R^{3}=\frac{\pi^{3 / 2}}{\left(\frac{3}{2}\right)!} R^{3}=C_{3} R^{3} \\
& V_{f}(R)=\frac{\pi^{f / 2}}{(f / 2)!} R^{f}=c_{f} R^{3} \\
& \text { where } C_{f}=\frac{\pi^{f / 2}}{(f / 2)!}
\end{aligned}
$$

- Therefore for 3 n dimensional hyper-sphere of radius $(2 m u)^{1 / 2}$, the volume is,

$$
V_{3 n}(R)=\frac{\pi^{3 n / 2}}{(3 n / 2)!} \quad(2 m u)^{3 n / 2}
$$

- The volume coupled between hyper spheres of radii $(2 m u)^{1 / 2}$ to $[2 m(u-$ $\delta u] 1 / 2$ is

$$
\begin{aligned}
\int d p_{1} \ldots \ldots \ldots \ldots d p_{3 n}=\frac{\pi^{3 n / 2}}{(3 n / 2)!} & {\left[(2 m u)^{3 n / 2}-\{2 m(u-\delta u)\}^{3 n / 2}\right] } \\
& =\frac{\pi^{3 n / 2}}{(3 n / 2)!}(2 m u)^{3 n / 2}\left[1-\left(1-\frac{\delta u}{u}\right)^{3 n / 2}\right] \\
& =\frac{\pi^{3 n / 2}}{(3 n / 2)!}(2 m u)^{3 n / 2}\left[1-\exp \left(-\frac{3 n}{2} \cdot \frac{\delta u}{u}\right)\right]
\end{aligned}
$$

- For a macroscopic system $3 \mathrm{n}=10^{23} ; \quad \frac{3 n}{2} \frac{\delta u}{u} \gg \mathrm{u}$.
- And hence we can drop the exponential term.

$$
\begin{aligned}
& \int d p_{1} \ldots \ldots \ldots \ldots \ldots d p_{n}=\frac{\pi^{3 n / 2}}{(3 n / 2)!}(2 m u)^{3 n / 2} \\
& \Delta \Gamma=V^{n} \int d p_{1} \ldots \ldots \ldots \ldots \ldots d p_{3 n} \\
& =V^{n} \frac{\pi^{3 n / 2}}{(3 n / 2)!}(2 m u)^{3 n / 2}
\end{aligned}
$$

- According to classical statistical mechanics, the entropy $\sigma$ in statistical equilibrium is given by,

$$
\begin{aligned}
\sigma & =\log \Delta \Gamma \\
= & \log \left[V^{n} \frac{\pi^{3 n / 2}}{(3 n / 2)!}(2 m u)^{3 n / 2}\right] \\
= & n \log \left[V \pi^{3 / 2}(2 m u)^{3 / 2}\right]-\log (3 n / 2)! \\
= & n \log \left[V \pi^{3 / 2}(2 m u)^{3 / 2}\right]-(3 n / 2) \log (3 n / 2)+3 n / 2 \\
& =n \log \left[V \pi^{3 / 2}(2 m u)^{3 / 2}\right]-n \log (3 n / 2)^{3 / 2}+3 n / 2 \\
& =n \log \left[\frac{V \pi^{3 / 2}(2 m u)^{3 / 2}}{(3 n / 2)^{3 / 2}}\right]+3 n / 2 \\
& \sigma=n \log \left[V\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}\right]+\frac{3 n}{2}
\end{aligned}
$$

- We know that the entropy should not depend on the unit of hyper volume $\Delta \Gamma$. To make it dimensionless we divide it by $h^{3 n}$.

$$
\begin{aligned}
& \sigma=\log \left[\Delta \Gamma / h^{3 n}\right] \\
& =n \log \left[V \frac{\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{3 n}{2}
\end{aligned}
$$

- The above equation does not satisfy the additive property and hence to satisfy the additive property we must divide by n !

$$
\begin{aligned}
\sigma & =\log \left[\frac{\Delta \Gamma}{h^{3 n} n!}\right] \\
& =n \log \left[V \frac{\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{3 n}{2}-\log n! \\
& =n \log \left[V \frac{\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{3 n}{2}-n \log n+n \\
\sigma & =n \log \left[\frac{\left(\frac{V}{n}\right)\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{5}{2} n
\end{aligned}
$$

- This expression satisfies the additive property because instead of V and u we have $\mathrm{V} / \mathrm{n}$ and $\mathrm{u} / \mathrm{n}$.
- We shall now establish the connection of statistical quantities with corresponding thermodynamic quantities.
(a) Internal energy( $\mathbf{U}$ ):

By the definition of statistical temperature $\tau$,

$$
\begin{aligned}
\frac{1}{\tau} & =\left(\frac{\partial \sigma}{\partial u}\right)_{T, n} \\
& =\frac{\partial}{\partial u}\left\{n \log \left[\frac{\left(\frac{V}{n}\right)\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{5}{2} \mathrm{n}\right\}_{T, n}
\end{aligned}
$$

$$
=\frac{\partial}{\partial u}\left[n \log v-n \log n+n \log \left(\frac{4 \pi m}{3}\right)^{3 / 2}+n \log \left(\frac{u}{n}\right)^{3 / 2}-n \log h^{3}\right]+\frac{\partial}{\partial u}\left(\frac{5}{2} n\right)
$$

$$
=\frac{\partial}{\partial u}\left[n \log v-n \log n+n \log \left(\frac{4 \pi m}{3}\right)^{3 / 2}+\frac{3}{2} n \log u-\frac{3}{2} n \log n-n \log h^{3}\right]+
$$ $\frac{\partial}{\partial u}\left(\frac{5}{2} n\right)$

$$
\begin{aligned}
& =\frac{\partial}{\partial u}\left(\frac{3}{2} n \log u\right) \\
\frac{1}{\tau} & =\frac{3}{2} n \frac{1}{u} \\
u & =\frac{3}{2} n \tau \quad \text { (or) } \quad u=\frac{3}{2} n k T
\end{aligned}
$$

- Which is the well known result for the internal energy of a perfect mono atomic gas.
(b) Relation between $\tau$ and $T$ :

The statistical temperature

$$
\begin{aligned}
\tau & =k \times \text { thermodynamic temperature. } \\
\tau & =k T
\end{aligned}
$$

(c) Relation between $\tau$ and $p$ :

We have $\quad \frac{p}{\tau}=\left(\frac{\partial \sigma}{\partial V}\right)_{n . u}$

$$
\begin{gathered}
=\left(\frac{\partial}{\partial V}\right)\left[\left\{n \log v-n \log n+n \log \left(\frac{4 \pi m}{3}\right)^{\frac{3}{2}}+\frac{3}{2} n \log u-\frac{3}{2} n \log n-\right.\right. \\
n \log h 3+\partial \partial V(52 n) n, u
\end{gathered}
$$

$$
\begin{aligned}
& =\left(\frac{\partial}{\partial V}\right)[n \log V] \\
& =n / V \\
P V & =n \tau \quad(\text { or }) \quad P V=n k T
\end{aligned}
$$

- Which is well known ideal gas equation for a perfect mono atomic gas.


## (d) Thermodynamic entropy (S): (Sackur - Tetrode equation)

The relation between thermodynamic entropy and statistical entropy is given by,

$$
\begin{aligned}
S & =k \sigma \\
& =n k \log \left[\frac{\left(\frac{V}{n}\right)\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{u}{n}\right)^{3 / 2}}{h^{3}}\right]+\frac{5}{2} n k \\
& =n k \log \left[\left(\frac{V}{n h^{3}}\right)\left(\frac{4 \pi m}{3}\right)^{3 / 2}\left(\frac{3}{2} k T\right)^{3 / 2}\right]+\frac{5}{2} n k
\end{aligned}
$$

$$
\text { Since } \begin{aligned}
u & =\frac{3}{2} n k T \\
= & n k \log \left[\frac{V}{n h^{3}}(2 \pi m k T)^{3 / 2}\right]+\frac{5}{2} n k \\
= & n k \log \left[\frac{V}{n}\left(\frac{2 \pi m k T}{h^{2}}\right)^{3 / 2}\right]+\frac{5}{2} n k \\
& =n k \log \left[\frac{V}{n}\left(\frac{2 \pi m k T}{h^{2}}\right)^{3 / 2} e^{5 / 2}\right]
\end{aligned}
$$

- This is the famous Sackur - Tetrode equation for the entropy of a perfect gas. This formula is valid for the mono atomic gas of atoms with zero total angular momentum.
- The thermal de-broglie wavelength associated with a molecule may be defined as,

$$
\begin{aligned}
\lambda & =h / \text { average thermal momentum of a molecule. } \\
\lambda & =h /(2 \pi m k T)^{1 / 2} \\
\lambda^{3} & =h^{3} /(2 \pi m k T)^{3 / 2} \\
\frac{1}{\lambda^{3}} & =\left(2 \pi m k T / h^{2}\right)^{3 / 2} \\
\sigma & =n \log \left[\frac{V}{n} \frac{1}{\lambda^{3}}\right]+\frac{5}{2} n \\
S & =n k \log \left[\frac{V}{n} \frac{1}{\lambda^{3}}\right]+\frac{5}{2} n k
\end{aligned}
$$

Now

- Thus the entropy of a perfect gas is determined essentially by the ratio of the volume per particle to the volume $\lambda^{3}$ associated with de-Broglie wavelength.
(e) Chemical potential of a perfect gas:

The chemical potential of a perfect gas is given by,

$$
\begin{aligned}
\frac{-\mu}{\tau} & =\left(\frac{\partial \sigma}{\partial n}\right)_{u, V} \\
& =\frac{\partial}{\partial n}\left[n \log \left[\frac{V}{n} \frac{1}{\lambda^{3}}\right]+\frac{5}{2} n\right]_{u, V} \\
& =\frac{\partial}{\partial n}\left[n \log V-n \log n-n \log \lambda^{3}\right]_{u, v}+\frac{\partial}{\partial n}\left(\frac{5}{2} n\right)_{u, v}
\end{aligned}
$$

$$
\begin{aligned}
& =\log V-1-\log n-\log \lambda^{3}+\frac{5}{2} \\
& =\log \left(\frac{V}{n \lambda^{3}}\right)+\frac{3}{2} \\
\frac{\mu}{\tau} & =\log \left(\frac{n \lambda^{3}}{V}\right)-\frac{3}{2} \\
\frac{n}{V} & =\frac{p}{\tau} \\
\frac{\mu}{\tau} & =\log \left(\frac{p \lambda^{3}}{\tau}\right)-\frac{3}{2} \\
\mu & =\tau \log p+\tau \log \left(\frac{\lambda^{3}}{\tau}\right)-\frac{3 \tau}{2} . \\
& =\tau \log p+f(\tau)
\end{aligned}
$$

- Where $f(\tau)$ is the function of the temperature alone.


### 4.12 GIBB'S CANONICAL ENSEMBLE:

## (i) System in contact with heat reservoir:

- The micro canonical ensemble describes the systems which are perfectly insulated and have given energy.
- In thermodynamics we do not know the exact value of energy as we usually deal with systems kept in thermal contact with a heat reservoir at a given temperature. Thus we know only its temperature i.e its average energy.
- The energy varies from instant to instant but the time average is known.
- On the other hand the canonical ensemble describes those systems which are not isolated, but are in thermal contact with a heat reservoir.
- In this situation the system of interest together with a heat reservoir forms a large closed system and the system of interest is treated as a subsystem.
- If the energy of the large closed system is constant, then it would represent a microcanonical system where as the subsystem which can exchange energy with a heat reservoir would represent canonical system.
- Thus any part of sub system of an isolated system in thermal equilibrium can be represented by a canonical ensemble .
- Consider a micro canonical ensemble representing a very large isolated system. Imagine that each system of the ensemble is made up of large number of subsystems which are in mutual thermal contact and can exchange energy.
- Choose a sub system s. The rest of the subsystem is denoted by r called heat reservoir. The total sub system is denoted by $t$. As the total system is a member of the microcanonical ensemble, it is isolated and $\mathrm{E}_{\mathrm{t}}$ is constant.
- Let the energies of the sub system and heat reservoir be $E_{s}$ and $E_{r}$ so

$$
E_{t}=E_{r}+E_{s}
$$

- As s can exchange energy but not the particles,
r heat reservoir

S sub system it is a member of the canonical ensemble. $s$ is comparatively small but usually macroscopic containing $10^{24}$ particles. In the case of a gas, the sub system may be a single molecule.

## (ii) Thermodynamical functions and partition function:

- We shall calculate the entropy, energy, Helmholtz free energy and partition function of the canonical ensemble.
- Consider an isolated system with total energy $\mathrm{E}_{0}$. This system is a part of a micro canonical ensemble.
- The micro canonical ensemble minus system is heat reservoir. Our system is in thermal equilibrium with the heat reservoir in such a way that $\bar{E}=\mathrm{E}_{0}$.
- Let our system in the microcanonical ensemble be defined in the energy range between $\mathrm{E}_{0}$ and $\mathrm{E}_{0}+\delta \mathrm{E}$. But in microcanonical ensemble $\delta \mathrm{E}$ is unimportant.
- Then we may choose $\delta \mathrm{E}$ to be equal to the range of reasonably probable values of the energy in the canonical ensemble.
- Therefore we define the entropy of the canonical ensemble with the mean energy E to be equal to the entropy of a microcanonical ensemble with energy $\bar{E}$.
- Consider the volume $\delta \Gamma$ of the phase space corresponding to the energies between $\bar{E}$ and $\bar{E}+\delta E$

$$
\Delta \Gamma==\left[\frac{\partial \Gamma(E)}{\partial E}\right]_{E} \delta E
$$

## To estimate $\delta \mathbf{E}$ :

- Let $\omega(\mathrm{E}) \mathrm{dE}$ represent the canonical ensemble probability for a system to have energy in the range $E$ and $E+d E$.
- $\rho(E)$ is the probability density of unit volume of the phase space at energy $E$, then the probability of volume $\Delta \Gamma$ in the range $E$ and $E+d E$ will be $\rho(E) \Delta \Gamma(E)$.

So that,

$$
\begin{align*}
& \omega(E) d E=\rho(E) \Delta \Gamma(E)  \tag{1}\\
& \quad=\rho(E)\left[\frac{\partial \Gamma(E)}{\partial E}\right]_{E} d E
\end{align*}
$$

- Figure represents the variation $\omega(\mathrm{t})$ as a function of E .
- The normalization condition is,

$$
\begin{equation*}
\int \omega(\mathrm{E}) \mathrm{dE}=1 \tag{2}
\end{equation*}
$$

- The simply means that the area under the curve $\omega=\omega(\mathrm{E})$ is equal to unity.
- Since the mean energy of the canonical ensemble is $\bar{E}$ the function $\omega(\mathrm{E})$ will have an extremely sharp
 maximum at $\mathrm{E}=\bar{E}$ differing appreciably from zero only in the immediate neighbourhood of this point.
- So on normalizing the plot we can introduce the width $\delta \mathrm{E}$ of the curve of $\omega=\omega(\mathrm{E})$ defining it as the width of the rectangle whose height is equal to the value of the function $\omega(\mathrm{E})$ at its maximum and whose area is equal to unity.
- Thus the width $\delta \mathrm{E}$ is determined by the normalization condition.

$$
\int \omega(\bar{E}) \delta \mathrm{E}=1
$$

- Comparing equations (1) and (2) with $\mathrm{E}=\bar{E}$, we get

$$
\text { Now, } \begin{aligned}
\rho(\bar{E}) \Delta \Gamma & =1 \\
\Delta \Gamma & =\frac{1}{\rho(\bar{E})}
\end{aligned}
$$

- But we have,

$$
\begin{gather*}
\rho(\bar{E})=A e^{-\bar{E} / \tau} \\
\Delta \Gamma=A^{-1} e^{\bar{E} / \tau} \\
=A^{-1} e^{U / k T} \tag{3}
\end{gather*}
$$

- where $\bar{E}=\mathrm{U}=$ energy of the system and $\tau=\mathrm{kT}$
- So that the statistical entropy $\sigma$ is given by,

$$
\begin{gather*}
\sigma=\log \Delta \Gamma \\
=\log \left[A^{-1} \cdot e^{U / k T}\right] \\
=-\log A+\frac{U}{k T} \\
\log A=\frac{U}{k T}-\sigma \\
=\frac{U-k \sigma T}{k T} \\
=\frac{U-S T}{k T} \tag{4}
\end{gather*}
$$

where $S=k \sigma=$ thermodynamic entropy.

## Helmholtz free energy:

$$
\begin{gathered}
F=U-T \sigma=U-S T \\
\log A=\frac{F}{k T} \\
A=e^{F / k T}
\end{gathered}
$$

- So that the canonical distribution function takes form,

$$
\begin{aligned}
\rho(E) & =A e^{-E / \tau} \\
& =e^{F / k T} e^{-E / k T} \\
& =e^{(F-E) / k T}
\end{aligned}
$$

- Now applying the normalization condition

$$
\begin{aligned}
\int \rho(E) d \Gamma & =1 \\
\int e^{(F-E) / k T} d \Gamma & =1 \\
e^{-F / k T} & =\int e^{-E(p, q) / k T} d \Gamma
\end{aligned}
$$

- Now the partition function is defined as,

$$
\begin{align*}
Z & =\int e^{-E(p, q) / k T} d \Gamma \text { (classical) } \\
Z & =\sum_{i} e^{-E i / k T} \text { (quantum) } \\
\text { So, } e^{-F / k T} & =Z \\
-F / k T & =\log Z \\
-F & =k T \log Z \\
-F & =\tau \log Z \rightarrow F=-\tau \log Z . \tag{5}
\end{align*}
$$

- This equation represents the expression for the Helmholtz free energy in terms of Z.
- Suppose N independent identical spinless particles, we must correct the classical partition function dimensionally and take into account the indistinguishability of the particles so that the correct expression is,

$$
\begin{equation*}
Z=\frac{1}{N!h^{3 N}} \int e^{-E(p, q) / k T} d \Gamma \text { (classical) } \tag{6}
\end{equation*}
$$

## Entropy of a system:

- The statistical entropy of a system in canonical ensemble is given by,

$$
\begin{align*}
& \sigma=-\left(\frac{\partial F}{\partial \tau}\right)_{V} \\
& =\frac{\partial}{\partial \tau}(\tau \log Z) \\
& =\log Z+\tau \frac{\partial}{\partial \tau}(\log Z) \tag{7}
\end{align*}
$$

- If $\mathrm{E}_{\mathrm{i}}$ is the $\mathrm{i}^{\text {th }}$ energy eigen value of a system, we have

$$
\begin{aligned}
Z & =\sum_{i} e^{-E_{i} / \tau} \\
\log Z & =\log \left(\sum_{i} e^{-E_{i} / \tau}\right) \\
\frac{\partial}{\partial \tau}(\log Z) & =\frac{\partial}{\partial \tau}\left[\log \left(\sum_{i} e^{-E_{i} / \tau}\right)\right] \\
& =\frac{\left.\sum e^{-E_{i} / \tau}\left(\frac{E_{i}}{\tau^{2}}\right)\right)}{\sum_{i} e^{-E i / \tau}}
\end{aligned}
$$

$$
\begin{align*}
& =\frac{1}{\tau^{2}} \frac{\sum E_{i} e^{-E i / \tau}}{\sum e^{-E i / \tau}} \\
& =\frac{1}{\tau^{2}} \bar{E}=\frac{U}{\tau^{2}} \tag{8}
\end{align*}
$$

- Now statistical entropy $\sigma=\log Z+\frac{U}{\tau}$
- The thermo dynamic entropy $S=k \sigma=k\left[\log z+\frac{U}{\tau}\right]$

$$
\begin{equation*}
S=k \log Z+\frac{U}{T} \tag{10}
\end{equation*}
$$

### 4.13 A SYSTEM OF NON-INTERACTING CLASSICAL HARMONIC OSCILLATORS USING CANONICAL ENSEMBLE:

- We now take up the quantum-mechanical situation, according to which the energy eigenvalues of a one-dimensional harmonic oscillator are given by

$$
\begin{equation*}
\varepsilon_{n}=\left(n+\frac{1}{2}\right) \hbar \omega ; n=0,1,2, \ldots \tag{1}
\end{equation*}
$$

- Accordingly, we have for the single-oscillator partition function

$$
\begin{align*}
Q_{1}(\beta) & =\sum_{n=0}^{n=\infty} \exp \left(-\beta \varepsilon_{n}\right) \\
& =\sum_{n=0}^{n=\infty} \exp \left[-\beta\left(n+\frac{1}{2}\right) \hbar \omega\right] \\
& =\frac{\exp \left(-\frac{1}{2} \beta \hbar \omega\right)}{1-\exp (-\beta \hbar \omega)} \\
& =\left\{2 \sinh \left(\frac{1}{2} \beta \hbar \omega\right)\right\}^{-1} \tag{2}
\end{align*}
$$

- The N - oscillator partition function is then given by

$$
\begin{align*}
Q_{N}(\beta)=\mid Q_{1}(\beta)^{N} & =\left[\frac{\exp \left(-\frac{1}{2} \beta \hbar \omega\right)}{1-\exp (-\beta \hbar \omega)}\right]^{N} \\
& =\frac{\exp \left(-\frac{N}{2} \beta \hbar \omega\right)}{[1-\exp (-\beta \hbar \omega)]^{N}}=e^{-(N / 2) \beta \hbar \omega}\left[1-e^{-\beta \hbar \omega}\right]^{-N} \tag{3}
\end{align*}
$$

- For the Helmholtz free energy of the system, we get

$$
\begin{align*}
A & =-k T \ln Q_{N} \\
A & =-k T \ln \left\{e^{-(N / 2) \beta \hbar \omega}\left[1-e^{-\beta \hbar \omega}\right]^{-N}\right\} \\
& =N k T \ln \left[e^{1 / 2^{\beta \hbar \omega}}\right]+N k T \ln \left[1-e^{-\beta \hbar \omega}\right] \\
& =N\left[\frac{1}{2} \hbar \omega+k T \ln \left(1-e^{-\beta \hbar \omega}\right)\right] \tag{4}
\end{align*}
$$

- whereby

$$
\begin{align*}
& \mu=\mathrm{A} / \mathrm{N}  \tag{5}\\
& \mathrm{P}=0  \tag{6}\\
& S=\beta k U+k \ln Q_{N} \\
& S=\beta k N\left[\frac{1}{2} \hbar \omega+\frac{\hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}\right]+k \ln \left\{e^{-(N / 2) \beta \hbar \omega}\left[1-e^{-\beta \hbar \omega}\right]^{-N}\right\} \\
& S=\beta k N\left[\frac{1}{2} \hbar \omega+\frac{\hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}\right]+k \ln \left(e^{-(N / 2) \beta \hbar \omega}\right)+k \ln \left[1-e^{-\beta \hbar \omega}\right]^{-N} \\
& S=\beta k N \frac{\hbar \omega}{2}+\beta k N \frac{\hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}-\beta k N \frac{\hbar \omega}{2}+k \ln \left[1-e^{-\beta \hbar \omega}\right]^{-N}
\end{align*}
$$

$S=k N\left\{\frac{\beta \hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}-\ln \left[1-e^{-\beta \hbar \omega}\right]\right\}$

- Then

$$
\begin{equation*}
S=k N\left\{\frac{\beta \hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}-\ln \left[1-e^{-\beta \hbar \omega}\right]\right\} \tag{7}
\end{equation*}
$$

Also

$$
\begin{aligned}
S & =N k\left[\frac{1}{2} \beta \hbar \omega \operatorname{coth}\left(\frac{1}{2} \beta \hbar \omega\right)-\ln \left\{2 \sinh \left(\frac{1}{2} \beta \hbar \omega\right)\right\}\right] \\
U & =-\frac{\partial}{\partial \beta} \ln Q_{N} \\
& =-\frac{\partial}{\partial \beta} \ln \left\{e^{-(N / 2) \beta \hbar \omega}\left[1-e^{-\beta \hbar \omega}\right]^{-N}\right\} \\
& =-\frac{\partial}{\partial \beta} \ln \left(e^{-(N / 2) \beta \hbar \omega}\right)-\frac{\partial}{\partial \beta} \ln \left[1-e^{-\beta \hbar \omega}\right]^{-N} \\
& =-\left[\frac{e^{-(N / 2) \beta \hbar \omega}(-N / 2 \hbar \omega)}{e^{-(N / 2) \beta \hbar \omega}}\right]-\left[\frac{-N\left(1-e^{-\beta \hbar \omega}\right)^{-N-1} e^{-\beta \hbar \omega}(-\hbar \omega)}{\left(1-e^{-\beta \hbar \omega}\right)^{-N}}\right]
\end{aligned}
$$

$$
\begin{align*}
& =\frac{N \hbar \omega}{2}+\frac{N \hbar \omega}{e^{\beta \hbar \omega}\left(1-e^{-\beta \hbar \omega}\right)} \\
& =\frac{N \hbar \omega}{2}+\frac{N \hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)} \\
U & =N\left[\frac{1}{2} \hbar \omega+\frac{\hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}\right]=\frac{1}{2} N \hbar \omega \operatorname{coth}\left(\frac{1}{2} \beta \hbar \omega\right) \tag{8}
\end{align*}
$$

and

$$
\begin{aligned}
C_{p} & =C_{v}=\frac{d U}{d T} \\
& =\frac{d}{d T} N\left[\frac{1}{2} \hbar \omega+\frac{\hbar \omega}{\left(e^{\beta \hbar \omega}-1\right)}\right] \\
& =\frac{d}{d T} N\left[\frac{\hbar \omega}{\left(e^{\hbar \omega / k T}-1\right)}\right] \\
& =N \hbar \omega\left[-\frac{e^{\frac{\hbar \omega}{k T}}\left(\frac{-\hbar \omega}{k T^{2}}\right)}{\left(e^{\hbar \omega / k T}-1\right)^{2}}\right] \\
& =N k\left(\frac{\hbar \omega}{k T}\right)^{2} \frac{e^{\beta \hbar \omega}}{\left(e^{\beta \hbar \omega}-1\right)^{2}}
\end{aligned}
$$

- Then

$$
C_{p}=C_{v}=N k(\beta \hbar \omega)^{2} \frac{e^{\beta \hbar \omega}}{\left(e^{\beta \hbar \omega}-1\right)^{2}}
$$

- Also

$$
\begin{aligned}
\mathrm{C}_{\mathrm{p}}=\mathrm{C}_{\mathrm{v}} & =\mathrm{Nk}\left(\frac{1}{2} \beta \hbar \omega\right)^{2} \operatorname{cosech}^{2}\left(\frac{1}{2} \beta \hbar \omega\right) \\
\langle\Delta U\rangle & =\text { standard deviation in energy distribution } \\
\langle\Delta U\rangle^{2} & =k T^{2}\left(\frac{\partial U}{\partial T}\right)_{V} \\
& =k T^{2} N k(\beta \hbar \omega)^{2} \frac{e^{\beta \hbar \omega}}{\left(e^{\beta \hbar \omega}-1\right)^{2}} \quad \text { [From equation (9)] } \\
& =N k^{2} T^{2} \frac{1}{k^{2} T^{2}}(\hbar \omega)^{2} \frac{e^{\beta \hbar \omega}}{\left(e^{\beta \hbar \omega}-1\right)^{2}}
\end{aligned}
$$

$$
=N(\hbar \omega)^{2} \frac{e^{\beta \hbar \omega}}{\left(e^{\beta \hbar \omega}-1\right)^{2}}
$$

- Now $\langle\Delta U\rangle=\sqrt{N} \hbar \omega \frac{e^{\beta \hbar \omega / 2}}{\left(e^{\beta \hbar \omega}-1\right)}$
- Thus $\quad\langle\Delta U\rangle \propto \sqrt{N}$
- Formula (8) is especially significant, for it shows that the quantum-mechanical oscillators do not obey the equipartition theorem.
- The mean energy per oscillator is different from the equipartition value kT ; actually, it is always greater than
- Only in the limit of high temperatures, where the
 thermal energy kT is much larger than the energy quantum $\hbar \omega$, does the mean energy per oscillator tend to the equipartition value.
- It should be noted here that if the zero-point energy $1 / 2 \hbar \omega$ were not present, the limiting value of the mean energy would be $(k T-1 / 2 \hbar \omega)$, and not kT - we may call such an oscillator the Planck oscillator, see curve 1 in figure .
- In passing, we observe that the specific heat which is the same for the Planck oscillator as for the Schrodinger oscillator, is temperature dependent; moreover, it is always less than, and at high temperatures tends to, the classical value.
- Indeed, for $\mathrm{kT} \gg \hbar \omega$, formulae (2) through (9) go over to their classical counterparts, respectively.


### 4.14Grand Canonical Ensemble:

(i) System in contact with a particle reservoir:

- In microcanonical ensemble each system contains same fixed energy as well as same number of particles.
- The microcanonical ensemble would not be applied to thermodynamics because we deal with systems kept in contact with heat reservoir. Then we know only the time average of energy.
- In canonical ensemble we relaxed the condition of constant energy and allowed the subsystem to exchange energy with heat reservoir. But this model could not be
applied to processes where not of particle varies. e.g. chemical processes and quantum processes.
- Therefore, we seek an ensemble which allows the subsystem to exchange energy as well as the particles with reservoir.
- Such an ensemble which allows the subsystem to exchange energy as well as the number of particles with the heat reservoir is called grand Canonical Ensemble.
- In grand canonical ensemble the independent variables are T,V and $\mu$. Then we have the grand potential.

$$
\Omega=U-T S-\mu n
$$

which is minimal when $T, V$ and $\mu$ are held fixed.

- Consider a microcanonical ensemble representing very large isolated system.
- Each system is made up of large number of sub system which are in mutual thermal contact and can exchange energy as well as particles with each other.
- Choose a sub system s , heat reservoir r and the total system t .
- $E_{s}$ and $E_{r}$ represent the energies of the sub system and the reservoir.
- $n_{s}$ and $n_{r}$ represent the number of particles in the sub system and the reservoir.
- Then the subsystem and the reservoir may exchange energy and particles subject to the conditions

$$
E_{s}+E_{r}=E_{t} \text { and } n_{s}+n_{r}=n_{t}
$$

- Now we find the probability $d \omega_{s}\left(n_{s}\right)$ of finding the sub systems in a state in which sub system $S$ contains $n$ particles and is found in the element $d \Gamma\left(n_{s}\right)$ of its phase space.
- $d \Gamma\left(n_{s}\right)$ indicates that the nature of the phase space of the subsystem changes with $n_{s}$.
- For grand canonical ensemble

$$
d \omega(n)=A \exp [(n \mu-E) / \tau] d \Gamma(n)
$$

- Normalization constant

$$
A=\exp \left(\frac{\Omega}{\tau}\right)
$$

- $\Omega$ is called grand potential or thermodynamic potential.

$$
\begin{gathered}
d \omega(n)=\exp [(\Omega+n \mu-E) / \tau] d \Gamma(n) \\
\int d \omega(n)=1 \\
\int \exp [(\Omega+n \mu-E) / \tau] d \Gamma(n)=1
\end{gathered}
$$

- From the normalization condition $\int \rho(n) d \Gamma(n)=1$
- $\rho(n)$ is the density of distribution of phase points in the phase space.
- Now we get

$$
\rho(n)=\exp [(\Omega+n \mu-E) / \tau]
$$

- An ensemble characterized by the probability distribution $\rho(n)$ given by the above equation is called grand canonical ensemble.
(ii) Partition function and thermodynamic function for grand canonical ensemble :
- In grand canonical ensemble sub system is allowed to exchange energy and the particles with the heat reservoir under the condition,

$$
\begin{equation*}
E_{s}+E_{r}=E_{t} \text { and } n_{s}+n_{r}=n_{t} \tag{1}
\end{equation*}
$$

$E_{s}, n_{s} \rightarrow$ the energy and the number of particles of the sub system.
$E_{r}, n_{r} \rightarrow$ the energy and the number of particles of the heat reservoir.
$E_{t}, n_{t} \rightarrow$ the energy and the number of particles of the total system.

- The probability distribution $\rho(n)$ is given by,

$$
\begin{align*}
\rho(n)= & \exp [(\Omega+n \mu-E) / \tau]  \tag{2}\\
& \Omega \rightarrow \text { grand potential } \\
& \mu \rightarrow \text { chemical potential }
\end{align*}
$$

- The grand partition function is defined as,

$$
\begin{aligned}
& Z=\exp (-\Omega / \tau) \\
& \qquad \begin{array}{l}
=e^{\mu n / \tau} \int e^{E / \tau} d \Gamma(n) \text { (classical) } \\
=\sum_{n} \sum_{i} \exp \left(\mu_{n}-E_{n, i}\right) / \tau \quad \text { (quantum) } \\
\quad Z=\sum_{n} e^{\mu n} Z_{n}
\end{array}
\end{aligned}
$$

$$
\begin{aligned}
Z_{n} & =\sum_{i} e^{-E / \tau} d \Gamma(n)(\text { classical }) \\
& =\sum e^{-E_{n, i} / \tau}(\text { quantum })
\end{aligned}
$$

is the canonical partition function .

- i.e the grand partition function $Z$ is the sum of canonical partition functions $Z_{i}$ for ensemble with different $n ' s$ with weighing factor $e^{-\mu n / \tau}$.
- From equation (3) the partition function is given by,

$$
\begin{align*}
& z=\exp (-\Omega / \tau) \\
& \Omega=-\tau \log Z \tag{4}
\end{align*}
$$

- The entropy $\sigma$ may be written as,

$$
\begin{gather*}
\sigma=\log \Delta \Gamma \\
=\log \left[\frac{1}{\rho(\bar{n}, \bar{E})}\right] \\
=-(\Omega+\bar{n} \mu-\bar{E}) / \tau \\
=-(\Omega+\bar{n} \mu-U) / \tau  \tag{5}\\
\tau \sigma=-(\Omega+\bar{n} \mu-U) \\
U-\tau \sigma=(\Omega+\bar{n} \mu)
\end{gather*}
$$

$$
\begin{equation*}
\text { Helmholtz free energy } F=U-\tau \sigma \tag{6}
\end{equation*}
$$

$$
\begin{equation*}
=\Omega+\bar{n} \mu \tag{7}
\end{equation*}
$$

$$
G=F+p V
$$

$$
=U-\tau \sigma+p V
$$

$$
d G=d U-\tau d \sigma-\sigma d \tau+p d V+V d p
$$

$$
\text { But } d U=\tau d \sigma-p d V+\mu d n
$$

$$
\text { Hence } d G=\tau d \sigma-p d V+\mu d n-\tau d \sigma-\sigma d \tau+p d V+V d p
$$

$$
\begin{equation*}
\left(\frac{d G}{d n}\right)_{\tau, p}=\mu \tag{10}
\end{equation*}
$$

Hence $G=\mu n$ for fixed p and $\tau$.

In this case

$$
\begin{array}{r}
G=\mu \bar{n} \\
\Omega+\bar{n} \mu+p V=\bar{n} \mu \\
\Omega=-p V \\
F+p V=\mu \bar{n} \\
U-\tau \sigma+p V=\mu \bar{n} \\
U-\tau \sigma-\Omega=\mu \bar{n} \\
U-\tau \sigma-\mu \bar{n}=\Omega \tag{12}
\end{array}
$$

$$
d \Omega=d U-\tau d \sigma-\sigma d \tau-\mu d \bar{n}-\bar{n} d \mu
$$

$$
=\tau d \sigma-p d V+\mu d \bar{n}-\tau d \sigma-\sigma d \tau-\mu d \bar{n}-\bar{n} d \mu
$$

$$
\begin{equation*}
=-p d V-\sigma d \tau-\bar{n} d \mu \tag{13}
\end{equation*}
$$

Then

$$
\begin{gathered}
p=-\left(\frac{\partial \Omega}{\partial V}\right)_{\tau, \mu} \\
\sigma=-\left(\frac{\partial \Omega}{\partial \tau}\right)_{V, \mu} \\
\bar{n}=-\left(\frac{\partial \Omega}{\partial \mu}\right)_{V, \tau}
\end{gathered}
$$

- From the above three relations we can evaluate thermodynamic quantities for the grand canonical ensemble.


### 4.15 CLASSICAL IDEAL GAS USING GRAND CANONICAL ENSEMBLE:

- The grand partition function is given by,

$$
\begin{equation*}
Z=\sum_{n} e^{\mu n / \tau} Z_{n} \tag{1}
\end{equation*}
$$

- Canonical partition function

$$
\begin{align*}
& \quad Z_{n}=\frac{1}{n!h^{3 n}} \int e^{-E(n) / \tau} d \Gamma(n)=\frac{f^{N}}{n!}  \tag{2}\\
& \text { where } f=\left(\frac{2 \pi m k T}{h^{2}}\right)^{3 / 2} V=\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V
\end{align*}
$$

- $\therefore$ The grand partition function

$$
\begin{equation*}
z=\sum_{n} e^{\mu n / \tau} \frac{f^{n}}{n!}=\sum_{n} \frac{\left(e^{\mu / \tau} \tau\right)^{n}}{n!} \tag{3}
\end{equation*}
$$

- From the series expansion $\sum_{n} \frac{x^{n}}{n!}=e^{x}$

$$
\begin{align*}
& Z=\exp \left(e^{\mu / \tau} f\right)  \tag{4}\\
& \Omega=-\tau \log Z=-\tau e^{\mu / \tau} f \\
& \quad \Omega=\tau e^{\mu / \tau}\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V \tag{5}
\end{align*}
$$

(a) Chemical potential per particle ( $\mu$ ):

$$
\begin{gather*}
\bar{n}=-\left(\frac{\partial \Omega}{\partial \mu}\right)_{V, \tau} \\
=-\frac{\partial}{\partial \mu}\left[-\tau e^{\mu / \tau}\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V\right]_{V, \tau} \\
=\frac{\partial}{\partial \mu}\left[\tau e^{\mu / \tau}\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V\right]_{V, \tau} \\
=\tau\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\mu / \tau} \frac{1}{\tau} \\
\bar{n}=\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\mu / \tau}  \tag{6}\\
=-\frac{\Omega}{\tau} \\
\Omega=-\tau \bar{n}  \tag{7}\\
\Omega=-\tau\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\mu / \tau}  \tag{8}\\
-\tau \bar{n}=-\tau\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\mu / \tau}
\end{gather*}
$$

This gives $e^{-\mu / \tau}=\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} \frac{V}{\bar{n}}=\frac{f}{\bar{n}}$

$$
\begin{array}{r}
-\frac{\mu}{\tau}=\log \left(\frac{f}{\bar{n}}\right) \\
\mu=-\tau \log \left(\frac{f}{\bar{n}}\right) \tag{9}
\end{array}
$$

## (b) Entropy: (Sackur-Tetrode equation)

- The statistical entropy $\sigma$ is given by,

$$
\begin{align*}
& \sigma=-\left(\frac{\partial \Omega}{\partial \tau}\right)_{V, \mu} \\
&=\frac{\partial}{\partial \tau}\left[\tau e^{\mu / \tau}\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V\right] \\
&=\left(\frac{2 \pi m}{h^{2}}\right)^{3 / 2} V \frac{\partial}{\partial \tau}\left[\tau^{5 / 2} e^{\mu / \tau}\right] \\
&=\left(\frac{2 \pi m}{h^{2}}\right)^{3 / 2} V\left[\frac{5}{2} \tau^{3 / 2} e^{\mu / \tau}+\tau^{5 / 2} e^{\mu / \tau}\left(-\mu / \tau^{2}\right)\right] \\
&=\left(\frac{2 \pi m}{h^{2}}\right)^{3 / 2} V \tau^{3 / 2} e^{\mu / \tau}\left[\frac{5}{2}-\frac{\mu}{\tau}\right] \\
& \sigma=\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\mu / \tau}\left[\frac{5}{2}-\frac{\mu}{\tau}\right]  \tag{10}\\
& \sigma= \bar{n}\left[\frac{5}{2}-\frac{\mu}{\tau}\right] \tag{11}
\end{align*}
$$

- From equation (9) we have $\frac{\mu}{\tau}=-\log \left(\frac{f}{\bar{n}}\right) \rightarrow \mu=-\tau \log \left(\frac{f}{\bar{n}}\right)$
- Now equation (10) becomes $\sigma=\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V e^{\log \left(\frac{\bar{n}}{f}\right)}\left[\frac{5}{2}+\log \left(\frac{f}{\bar{n}}\right)\right]$

$$
\begin{aligned}
& =\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V\left(\frac{\bar{n}}{f}\right)\left[\frac{5}{2}+\log \left(\frac{f}{\bar{n}}\right)\right] \\
& =\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} V \bar{n}\left(\frac{2 \pi m \tau}{h^{2}}\right)^{-3 / 2} \frac{1}{V}\left[\frac{5}{2}+\log \left(\frac{f}{\bar{n}}\right)\right] \\
& =\bar{n}\left[\frac{5}{2}+\log \left(\frac{f}{\bar{n}}\right)\right]
\end{aligned}
$$

$\sigma=\bar{n}\left[\frac{5}{2}+\right.$
$\log 2 \pi m \tau h 23 / 2 V n$

- Thermodynamic entropy

$$
\begin{gather*}
\mathrm{S}=k \sigma \\
=\bar{n} k\left[\frac{5}{2}+\log \left\{\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} \frac{v}{\bar{n}}\right\}\right] \\
=\bar{n} k \log \left[\left\{\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} \frac{V}{\bar{n}}\right\} e^{5 / 2}\right] \tag{13}
\end{gather*}
$$

- This gives the famous Sackur-Tetrode equation for the entropy of a perfect gas and this is in agreement with the equation for microcanonical ensemble and canonical ensemble.
(c) Internal energy:

$$
\begin{aligned}
& \text { We have } \quad \begin{aligned}
\Omega & =U-\tau \sigma-\mu \bar{n} \\
U & =\Omega+\tau \sigma+\mu \bar{n} \\
\Omega & =-\bar{n} \tau \quad[\text { from equation (7)] } \\
\sigma & =\bar{n}\left[\frac{5}{2}-\frac{\mu}{\tau}\right] \quad \text { [from equation (11)] } \\
\text { Now } \quad U & =-\bar{n} \tau+\tau \bar{n}\left[\frac{5}{2}-\frac{\mu}{\tau}\right]+\mu \bar{n} \\
& =-\bar{n} \tau+\frac{5}{2} \bar{n} \tau-\mu \bar{n}+\mu \bar{n} \\
& =\frac{3}{2} \bar{n} \tau . \\
U & =\frac{3}{2} n k T .
\end{aligned}
\end{aligned}
$$

- which is well known relation for the internal energy of a perfect gas.


### 4.16 ENERGY AND DENSITY FLUCTUATIONS IN ENSEMBLES:

(a) Canonical ensemble:

- In canonical ensemble the systems are in thermal equilibrium with the heat reservoir and so energy fluctuations take place.
- For canonical ensemble partition function,

$$
\begin{aligned}
& Z=\sum_{i} e^{-\beta E_{i}} \\
& \text { where } \beta=\frac{1}{k T} \\
& \frac{\partial Z}{\partial \beta}=\sum_{i} e^{-\beta E_{i}}\left(-E_{i}\right) \\
&=\sum_{i} E_{i} e^{-\beta E_{i}} \\
& \sum_{i} E_{i} e^{-\beta E_{i}}=-\frac{\partial z}{\partial \beta} .
\end{aligned}
$$

- Mean energy

$$
\begin{gather*}
\bar{E}=\frac{\sum_{i} E_{i} e^{-\beta E_{i}}}{\sum_{i} e^{-\beta E_{i}}} . \\
=\frac{\sum_{i} E_{i} e^{-\beta E_{i}}}{Z} . \\
\bar{E}=-\frac{1}{z} \frac{\partial z}{\partial \beta}  \tag{2}\\
\frac{\partial^{2} z}{\partial \beta^{2}}=\sum_{i} E_{i}^{2} e^{-\beta E_{i}} \\
\sum E_{i}^{2} e^{-\beta E_{i}}=\frac{\partial^{2} z}{\partial \beta^{2}} \\
\bar{E}^{2}=\frac{\sum_{i} E_{i}^{2} e^{-\beta E_{i}}}{\sum_{i} e^{-\beta E_{i}}} \\
=\frac{\sum_{i} E_{i}^{2} e^{-\beta E_{i}}}{Z} . \\
\bar{E}^{2}=\frac{1}{z} \frac{\partial^{2} z}{\partial \beta^{2}} \tag{3}
\end{gather*}
$$

- Using equation (2) $\frac{\partial \bar{E}}{\partial \beta}=\frac{\partial}{\partial \beta}\left(-\frac{1}{z} \frac{\partial z}{\partial \beta}\right)$

$$
\begin{align*}
& =-\frac{\partial}{\partial \beta}\left(\frac{1}{z} \frac{\partial z}{\partial \beta}\right)=-\left[\frac{1}{z} \frac{\partial^{2} z}{\partial \beta^{2}}-\frac{1}{z^{2}}\left(\frac{\partial z}{\partial \beta}\right)^{2}\right] \\
& =-\left[\bar{E}^{2}-(\bar{E})^{2}\right] \\
= & -(\overline{\delta E})^{2} \tag{4}
\end{align*}
$$

$$
\begin{align*}
& C_{V}=\left(\frac{\partial \bar{E}}{\partial T}\right)_{V} \\
&=\left(\frac{\partial \bar{E}}{\partial \beta}\right)\left(\frac{\partial \beta}{\partial T}\right) \\
&=-(\overline{\delta E})^{2}\left(-\frac{1}{k T^{2}}\right) \\
& C_{V}=\left(\frac{1}{k T^{2}}\right)(\overline{\delta E})^{2}  \tag{5}\\
&(\overline{\delta E})^{2}=k T^{2} C_{V} \\
& \sqrt{(\overline{\delta E})^{2}}=T\left(k C_{V}\right)^{1 / 2} \tag{6}
\end{align*}
$$

- The energy fluctuation is measured by the ratio

$$
\begin{align*}
& \frac{\Delta E}{E}=\frac{\sqrt{(\overline{\delta E})^{2}}}{\bar{E}} \\
& =\frac{T\left(k C_{V}\right)^{1 / 2}}{\bar{E}} \tag{7}
\end{align*}
$$

- For large values of T, $\mathrm{C}_{\mathrm{v}}$ and $\bar{E}$ are proportional to the number of molecules N and hence fluctuation is proportional to $N^{-1 / 2}$.
- For an ideal gas

$$
\begin{align*}
& \bar{E}=N k T \text { and } C_{V}=N k \\
& \frac{\Delta E}{E}=\frac{T}{N k T}[k N k]^{1 / 2} \\
& =\frac{N^{1 / 2}}{N}=N^{-1 / 2} \tag{8}
\end{align*}
$$

- For a macroscopic system $\mathrm{N}=10^{22}$.
- So the fluctuations are very small in the order $10^{-11}$.
- Therefore in canonical ensemble the distribution of energies is so peaked about the ensemble average energy that in practice regarded as a microcanonical ensemble.


## (b) Grand canonical ensemble:

- In ground canonical ensemble the fluctuations take place in concentration as well as energy.
- The energy fluctuation can be calculated as for canonical ensemble.
- For Grand canonical ensemble the partition function,

$$
\begin{gather*}
Z=\sum_{n, i} e^{\left(n \mu-E_{n, i}\right) / \tau}  \tag{9}\\
\frac{\partial Z}{\partial \mu}=\sum_{n, i} e^{\left(n \mu-E_{n, i}\right) / \tau} \frac{n}{\tau} \\
=\frac{1}{\tau} \sum_{n, i} n e^{\left(n \mu-E_{n, i}\right) / \tau} \\
\sum n e^{\left(\mu n-E_{n, i}\right) / \tau}= \\
=\frac{\partial Z}{\partial \mu}
\end{gather*}
$$

- Mean concentration $\quad \bar{n}=\frac{\sum_{n, i} n e^{\left(n \mu-E_{n, i}\right) / \tau}}{\sum_{n, i} e^{\left(n \mu-E_{n, i}\right) / \tau}}$

$$
=\frac{\sum_{n, i} e^{\left(n \mu-E_{n, i}\right) / \tau}}{z}
$$

$$
\begin{equation*}
\bar{n}=\frac{\tau}{z} \frac{\partial Z}{\partial \mu} \tag{10}
\end{equation*}
$$

$$
\begin{align*}
\frac{\partial^{2} Z}{\partial \mu^{2}} & =\frac{1}{\tau^{2}} \sum_{n, i} n^{2} e^{\left(n \mu-E_{n, i}\right) / \tau} \\
\sum_{n, i} n^{2} e^{\left(n \mu-E_{n, i}\right) / \tau} & =\tau^{2} \frac{\partial^{2} Z}{\partial \mu^{2}} \\
\bar{n}^{2} & =\frac{\sum_{n, i} n^{2} e^{\left(n \mu-E_{n, i}\right) / \tau}}{\sum_{n, i} e^{\left(n \mu-E_{n, i}\right) / \tau}} \\
& =\frac{\sum_{n, i} n^{2} e^{\left(n \mu-E_{n, i}\right) / \tau}}{Z} \\
\frac{\partial \bar{n}}{\partial \mu} & =\frac{\partial}{\partial \mu}\left[\frac{\tau}{z} \frac{\partial Z}{\partial \mu}\right]  \tag{11}\\
& =\frac{\tau}{z} \frac{\partial^{2} Z}{\partial \mu^{2}}-\frac{\tau}{z^{2}}\left(\frac{\partial Z}{\partial \mu}\right)^{2}
\end{align*}
$$

$$
\begin{align*}
& \quad \tau \frac{\partial \bar{n}}{\partial \mu}=\frac{\tau^{2}}{z} \frac{\partial^{2} z}{\partial \mu^{2}}-\frac{\tau^{2}}{z^{2}}\left(\frac{\partial z}{\partial \mu}\right)^{2} \\
& \tau \frac{\partial \bar{n}}{\partial \mu}=(\overline{\delta n})^{2} \tag{12}
\end{align*}
$$

- For an ideal classical gas $\bar{n}=e^{\mu / \tau} V\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2}$

$$
\begin{aligned}
\frac{\partial \bar{n}}{\partial \mu} & =\frac{1}{\tau} e^{\mu / \tau} V\left(\frac{2 \pi m \tau}{h^{2}}\right)^{3 / 2} \\
\frac{\partial \bar{n}}{\partial \mu} & =\frac{1}{\tau} \bar{n} \\
\tau \frac{\partial \bar{n}}{\partial \mu} & =\bar{n} \\
(\overline{\delta n})^{2} & =\bar{n} \\
\sqrt{(\overline{\delta n})^{2}} & =\sqrt{\bar{n}}
\end{aligned}
$$

- The concentration fluctuation is measured by the ratio

$$
\begin{aligned}
\frac{\Delta n}{n} & =\frac{\sqrt{(\overline{\delta n})^{2}}}{\bar{n}}=\frac{\sqrt{\bar{n}}}{\bar{n}}=\frac{1}{\sqrt{\bar{n}}} \\
p V & =\bar{n} k T \\
\bar{n} & =\frac{p V}{k T} \\
\frac{\Delta n}{n} & =\left[\frac{k T}{p V}\right]^{1 / 2}
\end{aligned}
$$

- Smaller of the volume greater is the fractional fluctuation.


### 4.17 ENTROPY OF MIXING AND THE GIBB'S PARADOX:

- The partition function of a perfect gas is given by,

$$
\begin{equation*}
Z=\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \tag{1}
\end{equation*}
$$

- The entropy of a perfect gas is given by,

$$
\begin{align*}
& S=N k \log Z+\frac{3}{2} N k  \tag{2}\\
= & N k \log \left[\frac{V}{h^{3}}(2 \pi m K T)^{3 / 2}\right]+\frac{3}{2} N k
\end{align*}
$$

$$
\begin{equation*}
=N k\left[\log V+\frac{3}{2} \log m+\frac{3}{2} \log T+C\right] \tag{3}
\end{equation*}
$$

C is a constant term including $\mathrm{h}, \mathrm{k}$

- The entropy given by equation (3) does not satisfy the additive property and giving paradoxial results.


## Explanation:

- Consider two systems a and b at the same temperature $T_{a}=T_{b}=T$

- $\quad a$ and $b$ are partitioned by a barrier as shown in figure.
- The particles of the two system are identical and distinguishable.
- The entropies of $a$ and $b$ are given by,

$$
\left.\begin{array}{rl}
S_{a} & =N_{a} k\left[\log V_{a}+\frac{3}{2} \log m_{a}+\frac{3}{2} \log T+C\right]  \tag{4}\\
S_{b} & =N_{b} k\left[\log V_{b}+\frac{3}{2} \log m_{b}+\frac{3}{2} \log T+C\right]
\end{array}\right\}
$$

- Here $\mathrm{N}_{\mathrm{a}}, \mathrm{m}_{\mathrm{a}}$ and $\mathrm{V}_{\mathrm{a}}$ represent the number of particles, the mass of each particle and volume of system a.
- Here $\mathrm{N}_{\mathrm{b}}, \mathrm{m}_{\mathrm{b}}$ and $\mathrm{V}_{\mathrm{b}}$ represent the number of particles, the mass of each particle and volume of system $b$.
- Entropy is an extensive quantity and satisfy the additive property.
- If the entropy given by equation (3) had satisfied the additive property , then by removing partition and allowing the gas molecules to mix freely, the entropy of the joint system would be

$$
\begin{align*}
& \quad S_{a b}=S_{a}+S_{b} \\
& =N_{a} k\left[\log V_{a}+\frac{3}{2} \log m_{a}+\frac{3}{2} \log T+C\right]+N_{b} k\left[\log V_{b}+\frac{3}{2} \log m_{b}+\right. \\
& \left.\frac{3}{2} \log T+C\right] . \tag{5}
\end{align*}
$$

- If the particles of the two system are the same and for convenience we take $V_{a}=V_{b}=V, N_{a}=N_{b}=N$ and $m_{a}=m_{b}=m$,then the entropy of the individual system be,

$$
\begin{align*}
S_{a} & =S_{b} \\
& =N k\left[\log V+\frac{3}{2} \log m+\frac{3}{2} \log T+C\right] \tag{6}
\end{align*}
$$

- Now the entropy of the combined system be,

$$
\begin{equation*}
S_{a b}=2 N k\left[\log V+\frac{3}{2} \log m+\frac{3}{2} \log T+C\right] \tag{7}
\end{equation*}
$$

- Now we shall find actual entropy. Let the partition is removed.
- Allow the molecules of the gas to mix freely.
- Now we have a system with 2 N particles and volume 2 V .
- Then the entropy of the joint system ab is given by,

$$
\begin{align*}
S_{a b} & =2 N k\left[\log 2 V+\frac{3}{2} \log m+\frac{3}{2} \log T+C\right] \\
& =2 N k\left[\log V+\frac{3}{2} \log m+\frac{3}{2} \log T+C\right]+2 N K \log 2 \\
& =S_{a}+S_{b}+2 N K \log 2 \tag{8}
\end{align*}
$$

- Equation (8) is not equal to equation (7), but has an additional factor $2 \mathrm{Nk} \log 2$.
- Thus by mixing of two gases with each containing N molecules and by removing a partition between them , then the entropy of the joint system increases by 2 Nk $\log 2$.
- This additional entropy is called entropy of mixing.
- Thus if we use equation (3) for entropy we got the paradoxial results.
- This peculiar behavior of the entropy is called Gibb's paradox.


## To resolve Gibb's paradox:

- Gibb's solved this paradox by considering the two systems with the molecules are identical and distinguishable.
- If two systems containing same number N are mixed by removing the partition then the diffusion takes place unnoticeably.
- In this situation N molecules of each system cannot be distinguished in N ! ways.
- Hence the weight of the configuration $W=N!\Pi \frac{g_{i}^{n i}}{n_{i}!}$
can be replaced by

$$
\begin{gathered}
W=\prod \frac{g_{i}^{n i}}{n_{i}!} \\
\log W=\Sigma n_{i} \log g_{i}-\Sigma \log n_{i}! \\
=\Sigma n_{i} \log g_{i}-\Sigma n_{i} \log n_{i}+\Sigma n_{i} \\
=\Sigma n_{i} \log g_{i}-\Sigma n_{i} \log n_{i}+N
\end{gathered}
$$

- From Maxwell- Boltzmann law,

$$
\begin{aligned}
n_{i} & =g_{i} e^{-\alpha} e^{-\beta \varepsilon i} \\
\log W_{\max } & =\Sigma n_{i} \log g_{i}-\Sigma n_{i} \log \left[g_{i} e^{-\alpha} e^{-\beta \varepsilon i}\right]+N \\
& =\Sigma n_{i} \log g_{i}-\Sigma n_{i} \log g_{i}+\Sigma n_{i} \alpha+\Sigma n_{i} \beta \varepsilon_{i}+N \\
\log W_{\max } & =\alpha N+\beta E+N
\end{aligned}
$$

Let us substitute $A=e^{-\alpha}$; ie, $\alpha=-\log A$

$$
\begin{align*}
& \log W_{\max }=-N \log A+\beta E+N \\
&=N-N \log A+\beta E \\
&=N[1-\log A]+\beta E \\
& S=k \log W_{\max } \\
&=N k[1-\log A]+\beta E k \\
&=N k[1-\log A]+\frac{1}{k T} \frac{3}{2} N k T k \\
&=N k[1-\log A]+\frac{3}{2} N k . \\
&=N k-N k \log A+\frac{3}{2} N k . \\
&=-N k \log A+\frac{5}{2} N k \\
&=-N k \log \frac{N}{Z}+\frac{5}{2} N k \\
&=N k \log \frac{Z}{N}+\frac{5}{2} N k \\
& S=N k \log \left[\frac{V}{h^{3}} \frac{(2 \pi m K T)^{3 / 2}}{N}\right]+\frac{5}{2} N k \\
&=N k \log \left[\left(\frac{V}{N}\right)\left(\frac{2 \pi m K T}{h^{2}}\right)^{3 / 2}\right]+\frac{5}{2} N k . \tag{9}
\end{align*}
$$

- The entropy given by this equation satisfies the additive property since here in the argument of logarithm we have V/N in place of V.
- In equation (9) replacing N by 2 N and V by 2 V , the entropy of the combined system be given by,

$$
\begin{align*}
& S_{a b}=2 N k \log \left[\left(\frac{2 V}{2 N}\right)\left(\frac{2 \pi m K T}{h^{2}}\right)^{3 / 2}\right]+\frac{5}{2} 2 N k . \\
= & 2\left\{N k \log \left[\left(\frac{V}{N}\right)\left(\frac{2 \pi m K T}{h^{2}}\right)^{3 / 2}\right]+\frac{5}{2} N k\right\} \\
= & 2 S=S_{a}+S_{b} \tag{10}
\end{align*}
$$

- Thus Gibb's paradox is resolved.The resolution of Gibb's paradox is an example of the success of the quantum theory.


## UNIT V : QUANTUM STATISTICAL MECHANICS

Quantum-mechanical ensemble theory: Density matrix, Equation of motion for density matrix, Quantum- mechanical ensemble average; Statistics of indistinguishable particles, Two types of quantum statistics- Fermi-Dirac and Bose-Einstein statistics, Fermi-Dirac and Bose-Einstein distribution functions using microcanonical and grand canonical ensembles (ideal gas only), Statistics of occupation numbers; Ideal Bose gas: Internal energy, Equation state, Bose-Einstein Condensation and its critical conditions; BoseEinstein condensation in ultra-cold atomic gases: its detection and thermodynamic properties: Ideal Fermi gas: Internal energy, Equation of state, Completely degenerate Fermi gas.

## QUANTUM MECHANICAL ENSEMBLE THEORY

### 5.1 THE DENSITY MATRIX :

- A pure quantum state of a system is represented by a single eigenvector $\psi_{\alpha}$.
- When the system is described by non-negative probabilities $p_{\alpha}, p_{\beta}, \ldots \ldots .$. for being in states $\psi_{\alpha}, \psi_{\beta} \ldots \ldots . . .$. a statistical approach is necessary.
- A pure classical state is represented by a single moving point in phase space, that have definite value of coordinates $\mathrm{q}_{1}, \mathrm{q}_{2}, \ldots . . . . . . . \mathrm{q}_{\mathrm{f}}$ and canonical momenta $p_{1}, p_{2}, \ldots \ldots . . p_{f}$ at each instant of time.
- The statistical state can be described by a non-negative density function

$$
f\left(\mathrm{q}_{1}, \ldots \mathrm{q}_{\mathrm{f}}, \mathrm{p}_{1} \ldots . \mathrm{p}_{\mathrm{f}}, \mathrm{t}\right)
$$

- The probability that the system is found in the interval $\mathrm{dq}_{1}, \ldots . . \mathrm{dq}_{\mathrm{f}} \ldots \mathrm{dp}_{1} \ldots \mathrm{dp}_{\mathrm{f}}$ at time $t$ is

$$
\rho\left(d q_{1} \ldots . . d q_{f}, d p_{1} \ldots . . d p_{f}\right)
$$

- The quantum analogue of the classical density function is known as density operator.
- We know that operators can be expressed by matrices and hence the density operator expressed as matrix is known as density matrix.
- The density matrix expresses the result of taking quantum mechanical matrix elements and ensemble averages in the same operation.
- Consider an ensemble consisting of $N$ systems in the normalized states $\psi_{\mathrm{i}}, \mathrm{i}=1,2,3 \ldots . \ldots \mathrm{N} . \operatorname{Let} \omega_{\mathrm{i}}$ be the probability that an assembly will be in the state $\psi_{i}$.
- We then define the density matrix in the $\left\{\psi_{i}\right\}$ representation as

$$
\begin{equation*}
\rho_{\mathrm{ij}}=\omega_{\mathrm{i}} \delta_{\mathrm{ij}} \tag{1}
\end{equation*}
$$

- Suppose now we wish to calculate the probability that if a measurement is made on an observable whose operator is $\hat{A}$ having Eigen functions $\phi_{\mathrm{i}}$, the result will be the Eigen value $a_{n}$ corresponding to the Eigen function $\phi_{\mathrm{n}}$.
- If the assembly is in the state $\psi_{i}$ and we express $\psi_{i}$ as a linear combination of the $\phi_{i}$ we obtain

$$
\begin{equation*}
\psi_{i}=\sum_{j} c_{i j} \phi_{j} \tag{2}
\end{equation*}
$$

- The probability that a measurement of $\hat{\mathrm{A}}$ will give $a_{n}$ is then simply $c_{i n} * c_{i n}$.
- But the probability that the assembly is in the state $\psi_{i}$ is $\omega_{i}$. Therefore the probability that the measurement of A will yield $a_{n}$ is just

$$
\begin{align*}
& \Sigma \omega_{i} c_{i n} * c_{i n}=\sum_{i} \sum_{j} \omega_{i} \delta_{i j} c_{i n} * c_{i n} \\
&=\sum_{\mathrm{i}} \sum_{\mathrm{j}} \rho_{\mathrm{ij}} \mathrm{c}_{\mathrm{in}} \mathrm{c}_{\mathrm{in}} * \\
&=\sum_{\mathrm{i}} \sum_{\mathrm{j}} \mathrm{c}_{\mathrm{in}} \mathrm{c}_{\mathrm{in}} * \int \psi_{\mathrm{i}} * \hat{\rho} \psi_{\mathrm{j}} \mathrm{dq} \\
&=\int\left(\sum_{i} c_{i n} \psi *\right) \hat{\rho}\left(\sum c_{i n} * \psi_{j}\right) d q \\
&=\int \psi_{\mathrm{n}} * \hat{\rho} \psi_{\mathrm{n}} \mathrm{dq} \tag{3}
\end{align*}
$$

- Therefore the probability that the measurement on $\hat{\mathrm{A}}$ will give $a_{n}$ is just

$$
\begin{equation*}
\int \phi_{n} * \hat{\rho} \phi_{n} d q=\rho_{n n}^{\prime} \tag{4}
\end{equation*}
$$

- Now suppose we wish to calculate the average value of A. This will be simply

$$
\begin{aligned}
\overline{\langle\hat{A}\rangle}\rangle & =\sum a_{n} \rho_{n n}^{\prime} \\
& =\sum_{n} \int \phi_{n} * \hat{\rho} a_{n} \phi_{n} d q \\
& =\sum \int \phi_{\mathrm{n}} * \hat{\rho} \hat{\mathrm{~A}}_{\mathrm{n}} \phi_{\mathrm{n}} \mathrm{dp} \\
& =\operatorname{Trace}[\hat{\rho} \hat{\mathrm{A}}] .
\end{aligned}
$$

We note that theaverage $\langle\hat{A}\rangle$ is a double average, quantum mechanical average and a statistical mechanical average.

### 5.2 EQUATION OF MOTION FOR DENSITY MATRIX

## (A QUANTUM MECHANICAL VERSION OF THE LIOUVILLE'S THEOREM ):

- From the definition of $\rho$ in $\left\{\varphi_{\mathrm{k}}\right\}$ representation, we write

$$
\begin{equation*}
\rho_{m n}=\frac{1}{N} \sum_{i=1}^{N} c_{i n}^{*} c_{i m} \tag{1}
\end{equation*}
$$

- Again

$$
\begin{equation*}
\frac{\partial \rho_{m n}}{\partial t}=\frac{1}{N} \sum_{i=1}^{N}\left(\frac{\partial c_{i n}^{*}}{\partial t} c_{i m}+c_{i m}^{*} \frac{\partial c_{i m}}{\partial t}\right) \tag{2}
\end{equation*}
$$

- The schroedinger time dependent wave equation is

$$
\begin{gather*}
i \frac{\hbar}{2 \pi} \frac{\partial}{\partial t} \Psi_{i}=\widehat{H} \Psi_{i} \\
i \frac{\hbar}{2 \pi} \sum_{k} \frac{\partial}{\partial t} c_{i k} \phi_{k}=\sum_{k} c_{i k} \widehat{H} \phi_{k} \tag{3}
\end{gather*}
$$

- Multiplying equation (3) by $\varphi_{j}^{*}$ and integration over $q$.

$$
\begin{align*}
& i \frac{\hbar}{2 \pi} \sum_{k} \frac{\partial}{\partial t} \int c_{i j} \phi_{j} * \phi_{k} d q=\sum_{k} c_{i k} \int \phi_{j} * \widehat{H} \phi_{k} d q \\
& i \frac{\hbar}{2 \pi} \frac{\partial}{\partial t} c_{i j}=\sum_{k} c_{i k} H_{j k} \quad\left[H_{j k}=\int \phi_{j} * \widehat{H} \phi_{k} d q\right] \tag{4}
\end{align*}
$$

- Taking complex conjugate we have

$$
\begin{equation*}
-i \frac{\hbar}{2 \pi} \frac{\partial}{\partial t} c_{i j} *=\sum_{k} c_{i k} * H_{j k} * \tag{5}
\end{equation*}
$$

- Substituting equations (4) and (5) in equation (2) and taking $\mathrm{H}_{\mathrm{ij}}=\mathrm{H}_{\mathrm{ji}}{ }^{*}$

$$
\begin{aligned}
i \frac{\hbar}{2 \pi} \frac{\partial \rho_{m n}}{\partial t} & =i \frac{\hbar}{2 \pi} \frac{1}{N} \sum_{i=1}^{N}\left(\frac{\partial c_{i n} *}{\partial t} c_{i m}+c_{i n} * \frac{\partial c_{i m}}{\partial t}\right) \\
& =-\frac{1}{N} \sum_{k} c_{i k} * H_{n k} * c_{i m}+\frac{1}{N} \sum_{k} c_{i n} * c_{i k} H_{m k} \\
& =-\left(\rho_{m k} H_{n k} *-\rho_{k n} H_{m k}\right) \\
& =-\left(\rho_{m k} H_{k n}-H_{m k} \rho_{k n}\right) \\
& =-[\rho, H]_{m n}
\end{aligned}
$$

Thus the time development of density matrix is given by

$$
i \frac{\hbar}{2 \pi} \frac{\partial \rho}{\partial t}=-[\hat{\rho}, \widehat{H}]
$$

This equation is analogous to the Liouville's theorem in classical mechanics.

### 5.3 QUANTUM MECHANICAL ENSEMBLE AVERAGE :

- An ensemble in quantum statistical mechanics is assumed to be a collection of a very large number of perfectly isolated (conservative) and hence independent systems in a variety of quantum mechanical state $\Psi(\mathrm{q}, \mathrm{t})$.
- Now the quantum mechanical version of Liouville's theorem is

$$
\mathrm{i} \hbar \frac{\partial \rho_{\mathrm{m}}}{\partial \mathrm{t}}=[\hat{\mathrm{H}} \hat{\rho}] \mathrm{mn}
$$

- and for the element $\rho_{\mathrm{mn}}$ to be independent of time, $\frac{\partial \rho_{\mathrm{mn}}}{\partial \mathrm{t}}=0$, so that $[H, \rho]=0$, this means $\hat{\rho}$ and $\hat{H}$ commute.
- Therefore, $\rho$ is a matrix associated with some constant of the motion of the system.
- $\hat{\rho}$ is some function of $H, \hat{\rho}=\hat{\rho}(\hat{H})$ where $\rho(\hat{H})$ can be expanded in a power series in $\hat{H}$.
- Taking $\phi_{k}$ 's as the basic set of eigenvectors, the matrix element of $\rho$ can be written as

$$
\begin{equation*}
\rho_{\mathrm{mn}}=\int \phi_{\mathrm{n}} * \rho(\hat{\mathrm{H}}) \phi_{\mathrm{n}} \mathrm{dq} \tag{1}
\end{equation*}
$$

- In the special case that the energy eigenfunctions $\psi_{\mathrm{n}}$ 's are chosen as basic vectors, equation (1) becomes

$$
\begin{equation*}
\rho_{\mathrm{mn}}=\int \psi_{\mathrm{n}} * \rho(\mathrm{H}) \psi_{\mathrm{m}} \mathrm{dq} \tag{2}
\end{equation*}
$$

- If we consider $\rho(\hat{H})$ as a power series in $\hat{H}$,then

$$
\begin{aligned}
& \rho(H)=a_{0}+a_{1} H+a_{2} H^{2}+\ldots \ldots . . \\
& \therefore \rho_{m n}=a_{0} \delta_{m n}+a_{1} E_{m} \delta_{m n}+a_{2} E_{m}{ }^{2} \delta_{m n}+\ldots \ldots . .
\end{aligned}
$$

(as $H_{m n}=E_{m} \delta_{m n}$ )

$$
=\left(a_{0}+a_{1} E_{m}+a_{2} E_{m}^{2}+\ldots . .\right) \delta_{m n}
$$

$$
=\rho\left(\mathrm{E}_{\mathrm{m}}\right) \delta_{\mathrm{mm}}
$$

- and

$$
\begin{equation*}
\rho(\mathrm{H}) \psi_{\mathrm{m}}=\rho\left(\mathrm{E}_{\mathrm{m}}\right) \psi_{\mathrm{m}} \tag{3}
\end{equation*}
$$

- Thus any $\rho(\hat{\mathrm{H}})$ is a diagonal matrix. Also, $\rho\left(E_{n}\right)$ is the probability of observing the eigenvalue $E_{n}$ :

$$
\begin{equation*}
\rho\left(\mathrm{E}_{\mathrm{n}}\right)=\omega_{\mathrm{n}} \tag{4}
\end{equation*}
$$

- From this equation it follows that in case of degenerate level, all the basic states $\psi_{\mathrm{m}}$ have the same probability $\omega_{\mathrm{n}}$ i.e.

$$
\begin{equation*}
\omega_{\mathrm{m} 1}=\omega_{\mathrm{m} 2}=\omega_{\mathrm{m} 3} \ldots=\rho\left(\mathrm{E}_{\mathrm{m} 1}\right) . \tag{5}
\end{equation*}
$$

- Now the state of a system known to have the energy E, within a range $\delta \mathrm{E}$ very small compared to L, must be represented by a superposition of basic states $\psi_{\mathrm{m}}$ belonging to eigen values $\mathrm{E}_{\mathrm{m}}$ in the range $\mathrm{E} \leq \mathrm{E}_{\mathrm{m}} \leq \mathrm{E}+\delta \mathrm{E}$.
- Let $\Omega$ be the number of basic states $\psi_{\mathrm{m}}$ belonging to eigen values $\mathrm{E}_{\mathrm{m}}$ in the range $\mathrm{E} \leq \mathrm{E}_{\mathrm{m}} \leq \mathrm{E}+\delta \mathrm{E}$, then from equation (5), we have

$$
\begin{equation*}
\omega_{\mathrm{m}_{1}}=\omega_{\mathrm{m}_{1}+1}=\omega_{\mathrm{m}_{1}+2}=\ldots . . . . . . \omega_{\mathrm{m}_{1}+\Omega-1}=\rho(\mathrm{E}) \tag{6}
\end{equation*}
$$

- Thus the probability of observing the eigen value $\mathrm{E}_{\mathrm{n}}$ in the range E and $\mathrm{E}+\delta \mathrm{E}$ is proportional to $1 / \Omega$.
(a) MICRO-CANONICAL ENSEMBLE
- For a closed, isolated thermodynamic system i.e. a system with assigned values for the independent variables $\mathrm{E} ; \mathrm{n}_{1}, \mathrm{n}_{2} \ldots \mathrm{n}_{\mathrm{r}} ; x_{1}, x_{2} \ldots x_{\mathrm{s}}$, using energy eigen functions as basic vectors, we write

$$
\begin{equation*}
\rho_{\mathrm{mn}}=\delta_{\mathrm{mn}} \omega_{\mathrm{n}}, \tag{7}
\end{equation*}
$$

- Where

$$
\begin{align*}
\omega_{\mathrm{n}} & =\frac{1}{\Omega} \text { for } \mathrm{E} \leq \mathrm{E}_{\mathrm{n}} \leq \mathrm{E}+\delta \mathrm{E}  \tag{8}\\
& =0 \text { otherwise },
\end{align*}
$$

- where $\delta \mathrm{E}$ is a very small range in E , and $\Omega$ is the number of basic states $\psi_{\mathrm{n}}$ belonging to eigen values $\mathrm{E}_{\mathrm{n}}$ in the range $\mathrm{E} \leq \mathrm{E}_{\mathrm{n}} \leq \mathrm{E}+\delta \mathrm{E}$. The constant $1 / \Omega$ result from the normalization

$$
\begin{equation*}
\sum_{\mathrm{n}} \omega_{\mathrm{n}}=1 \tag{9}
\end{equation*}
$$

- From equation (8) it is clear that for a system known to have an energy between E and $\quad \mathrm{E}+\delta \mathrm{E}$, all basic states $\psi_{\mathrm{n}}$ belonging to an eigen value $\mathrm{E}_{\mathrm{n}}$ in this range have
the same probability $\omega_{\mathrm{n}}$. This is usually called the postulate of "equal a priori probabilities".
(b) CANONICAL ENSEMBLE:
- For a closed, isothermal thermodynamic system i.e., a system with assigned values for independents variables $\mathrm{T}, \ldots n_{1} \ldots n_{v}, x_{1} \ldots x_{s}$ using arbitrary basic vectors $\phi_{k}$

$$
\begin{equation*}
\rho=\text { constant } \times e^{-\beta \hat{H}} \tag{10}
\end{equation*}
$$

- Where $\beta=$ constant $=\frac{1}{k \mathrm{~T}}$. From equation (1) we can write

$$
\begin{equation*}
\rho_{m n}=\operatorname{constant} \times \int \phi_{\mathrm{n}} * \mathrm{e}^{-\beta \hat{H}} \phi_{m} d q \tag{11}
\end{equation*}
$$

- In general, $\rho_{\mathrm{mn}}=\omega_{\mathrm{n}}$ is the probability of observing an eigen value $a_{n}$.
- Hence we can write

$$
\sum_{n} \rho_{\mathrm{nk}}=1=\text { constant } \times \sum_{n} \int \phi_{n} * \mathrm{e}^{\beta \hat{H}} \phi_{m} d q
$$

- or

$$
\begin{align*}
\text { constant } & =\frac{1}{\sum_{n} \int \phi_{n} * \mathrm{e}^{-\beta \hat{H}} \phi_{m} d q} \\
& =\frac{1}{\mathrm{Z}} \text { where } \mathrm{Z}=\sum_{n} \int \phi_{n} * \mathrm{e}^{-\beta \hat{H}} \phi_{m} d q \tag{12}
\end{align*}
$$

- and

$$
\begin{equation*}
\hat{\rho}=\frac{\mathrm{e}^{-\beta \hat{H}}}{\mathrm{Z}} \tag{13}
\end{equation*}
$$

- where $Z\left(\beta, x_{1}, \ldots x_{\mathrm{s}}, \mathrm{n}_{1} \ldots \mathrm{n}_{\mathrm{r}}\right)$ is called the partition function.
- The classical partition function is $\int \mathrm{e}^{-\beta \hat{H}(\mathrm{p}, \mathrm{q})} d p d q$
- Comparing equations (12) and (14), the integration over $\rho$ in classical mechanics is replaced by a summation over quantum states.
- $Z$ may be written in alternative ways

$$
\begin{aligned}
Z & =\sum_{n}\left(e^{-\beta \hat{H}}\right)_{n n}=\text { trace } e^{-\beta \hat{H}} \\
& =\text { sum of eign values of } \mathrm{e}^{-\beta \hat{H}}
\end{aligned}
$$

- Z is obviously invariant under a change of basic vectors.
- The most invariant special choice of basic vectors is the set of energy eigen function $\Psi_{n}$.

[^0]- Therefore we can write

$$
\begin{align*}
& \rho_{\mathrm{mn}}=\frac{1}{Z} \int \psi_{\mathrm{n}}^{*} \mathrm{e}^{-\beta \hat{H}} \psi_{\mathrm{m}} \mathrm{dq} \\
& =\frac{1}{Z} \int \psi_{n}{ }^{*} \psi_{m} e^{-\beta E_{m}} d q \tag{15}
\end{align*}
$$

- Because

$$
e^{-\beta \hat{H}}=1-\beta \hat{H}+\frac{1}{2!}(\beta \hat{H})^{2}
$$

and

$$
\hat{\mathrm{H}} \psi_{\mathrm{m}}=\mathrm{E}_{\mathrm{m}} \psi_{\mathrm{m}}
$$

- Now we obtain

$$
\begin{aligned}
\int \psi_{n}{ }^{*} e^{-\beta H} \Psi_{m} d q & =\int \psi_{n}{ }^{*} \psi_{m} e^{-\beta E_{m}} d q \\
& =\frac{1}{Z} \delta_{m n} e^{-\beta E_{n}} \\
& =\delta_{\mathrm{mn}} \omega_{\mathrm{n}}
\end{aligned}
$$

- Where $\omega_{\mathrm{n}}$ is the probability that a system, chosen at random from canonical ensemble, will be found in the energy state $\mathrm{E}_{\mathrm{n}}$
- The partition function is written as

$$
\begin{align*}
& Z=\int \psi_{n}{ }^{*} e^{-\beta \hat{H}} \psi_{n} d q \\
&=\sum_{\mathrm{n}}\left|\psi_{\mathrm{n}}\right|^{2} \mathrm{e}^{-\beta E_{\mathrm{n}}} \mathrm{dq} \\
&=\sum_{n} e^{-\beta E_{n}} \tag{16}
\end{align*}
$$

(c) GRAND CANONICAL ENSEMBLE:

- Now we consider the case of an ensemble composed of members which can differ not only in the state but also in the amounts of material of various kinds which they contain. Such an ensemble is called the grand canonical ensemble.
- Let us suppose that a system is composed of $r$ independent kinds of components and $\mathrm{n}_{1}, \mathrm{n}_{2} \ldots \mathrm{n}_{\mathrm{r}}$ be the number of molecules in any member system of grand ensemble.
- For an open, isothermal thermodynamic system i.e, a system with assigned values for the independent variables T ; $\left(\mu_{1}-\mu_{\mathrm{r}} ; \mathrm{x}_{1}-\mathrm{x}_{\mathrm{s}}\right)$ we can define the grand canonical ensemble corresponding to such a system by the formula,

$$
\begin{equation*}
\rho=\operatorname{constant} \times \mathrm{e}^{-\beta \hat{\mathrm{H}}} \times e^{-\beta \mu n} \tag{1}
\end{equation*}
$$

- where

$$
\begin{align*}
\mu n & =\mu_{1} n_{1}+\mu_{2} n_{2}+\ldots+\mu_{r} n_{r} \\
\therefore \quad \rho_{m n} & =\text { constant } \times \mathrm{e}^{-\beta \mu n} \int \psi_{n}^{*} e^{-\beta \hat{H}} \phi_{m} d q \tag{2}
\end{align*}
$$

- The total probability of finding a system in one or another state $N$ will be taken as normalized to unity. Thus we can write,

$$
\begin{equation*}
\sum_{N, n} \rho_{n n}=1 \tag{3}
\end{equation*}
$$

- Now from equation (2), we have

$$
\begin{align*}
\text { Constant } & =\frac{1}{\mathrm{e}^{-\beta \mu \mathrm{n}} \int \phi_{\mathrm{n}} \mathrm{e}^{-\beta \hat{\mathrm{H}}} \phi_{\mathrm{m}} \mathrm{dq}} \\
& =\frac{1}{Z} \tag{4}
\end{align*}
$$

- where Z is called the 'grand partition function'. Therefore

$$
\begin{equation*}
\rho=\frac{\mathrm{e}^{-\beta \hat{H}} \mathrm{e}^{-\beta \mu n}}{\mathrm{Z}} \tag{5}
\end{equation*}
$$

- From equation (5), we get

$$
\begin{align*}
\sum \rho_{\mathrm{nn}} & =\frac{\mathrm{e}^{-\beta \mu \mathrm{n}}}{\mathrm{Z}} \int \phi_{\mathrm{n}}{ }^{*} \mathrm{e}^{-\beta \hat{H}} \phi_{\mathrm{n}} \mathrm{dq} \\
& =\frac{\mathrm{e}^{-\beta \mu \mathrm{n}}}{\mathrm{Z}} \mathrm{Z}(\mathrm{n}) \\
& =\gamma(\mathrm{n}) \text { say. } . \tag{6}
\end{align*}
$$

- Combining equations (5) and (6), we get

$$
\begin{equation*}
\rho=\frac{\gamma(n) e^{-\beta \hat{H}(n)}}{Z(n)} \tag{7}
\end{equation*}
$$

- If the basis vectors are a set of energy eigen functions, then, the probability of observing the state $\psi_{\mathrm{n}}(\mathrm{N}, x)$ is

$$
\begin{equation*}
\omega_{n}(N)=\rho_{n n}=\frac{e^{-\beta \mu_{n}} e^{-\beta E_{n}}}{\sum e^{-\beta \mu_{n}} e^{-\beta E_{n}}} \tag{8}
\end{equation*}
$$

(d) CONDITION FOR STATISTICL EQUILIBRIUM:

- When a system is in equilibrium, its corresponding ensemble must be stationary.i.e
$\rho_{\mathrm{mn}}=0$.This is possible, when
i. the density matrix is constant, or
ii. the density matrix is a function of a constant of motion
(i) If the density matrix is constant, its element will be given by

$$
\begin{equation*}
\rho_{\mathrm{mn}}=\rho_{0} \delta_{\mathrm{mn}} \tag{1}
\end{equation*}
$$

- i.e., all the non-diagonal elements of the matrix will be zero and all the diagonal elements will be equal to a constant $\rho_{0}$
- In the energy representation, the basic function $\phi_{\mathrm{n}}$ are the eigen functions of the Hamiltonian $\hat{H}$.So, the matrices H and $\rho$ are diagonal. Thus

$$
\begin{equation*}
\rho_{\mathrm{mn}}=\rho_{\mathrm{n}} \delta_{\mathrm{mn}} \tag{2}
\end{equation*}
$$

- In the representation, the density operator $\hat{\rho}$ may be written as

$$
\begin{equation*}
\hat{\rho}=\sum_{\mathrm{n}} \int \phi_{\mathrm{n}}{ }^{*} \rho_{\mathrm{n}} \phi_{\mathrm{n}} \mathrm{dq}=[\hat{\mathrm{H}}, \hat{\rho}] \tag{3}
\end{equation*}
$$

- To verify this, consider an element $\rho_{k l}$. Now

$$
\begin{align*}
\rho_{\mathrm{k} l} & =\int \phi_{\mathrm{k}} \hat{\rho} \phi_{l} d q=\sum_{n}\left(\int \psi_{\mathrm{k}}{ }^{*} \psi_{n} d q\right) \rho_{n}\left(\psi_{n}{ }^{*} \psi_{l} d q\right) \\
& =\sum_{n} \delta_{\mathrm{kn}} \rho_{n} \delta_{n l}=\rho_{\mathrm{k}} \delta_{\mathrm{k} l} \tag{4}
\end{align*}
$$

- This agrees with equation (2)
- Therefore

$$
\begin{align*}
i \hbar \dot{\rho}_{m n}= & \sum_{1}[\hat{H}, \hat{\rho}] \\
& =\sum_{l}\left[H_{m l} \rho_{l n}-\rho_{m l} H_{l n}\right] \\
& =\sum_{l}\left[\rho_{0} H_{m l} \delta_{l n}-\rho_{0} \delta_{m l} H_{l n}\right] \\
& =\rho_{0}\left[\mathrm{H}_{\mathrm{mn}}-\mathrm{H}_{\mathrm{m}}\right]=0 \tag{5}
\end{align*}
$$

- The distribution does not change with time. So, the system under consideration is in equilibrium.
(ii) From eq. (5), it is obvious that $\hat{\rho}$ commutes with $\hat{H}$. Therefore, $\rho$ must be a function of a constant of motion.


### 5.4 INDISTINGUISHABILITY AND QUANTUM STATISTICS:

- By indistinguishable particles we mean that if the position and spin coordinates of two of them are interchanged, there is no physical way of measuring that a change has been made.
- In classical mechanics identical particles do not lose their individuality despite the identity of their physical properties.
- If a pair of particles is completely equivalent even then it is possible to identify them by the continuity of their trajectories because this property enables an observer to follow each particle.
- This is due to the fact that their wave packets do not overlap, and the particles move in separate, distinguishable continuous orbits.
- As an example, consider the molecules in a gas at N.T.P.

Molecular density $\quad=10^{19}$ mole. $/ \mathrm{cm} .^{2}$
Volume available to each molecule $=10^{-19} \mathrm{~cm} .^{3}$
Molecular radius $\quad=10^{-8} \mathrm{~cm}$.
Molecular volume $=10^{-24} \mathrm{~cm} .^{3}$

- Because the molecule is smaller than the volume available, we can identify every molecule of the gas. The molecules are thus distinguishable.
- The situation is quite different in quantum mechanics as follows at once from the uncertainty principle.
- Due to the uncertainty principle, the concept of the path ceases to have any meaning. If the path of an electron is exactly known at a given instant, its coordinates have no definite values even at an infinitely close subsequent instant.
- By localising and numbering the identical particles at some instant, at some other instant we cannot say which of particle arrived at that point.
- In quantum mechanics there is no way of keeping track of each particle separately when the wave functions of two identical particles overlap.
- Thus in quantum mechanics there is, in principle, no possibility of separately following each of a number of similar particles and thereby distinguishing them.
- As an example, we consider the conduction electrons of a metal:

```
Density of electrons \(\quad=10^{22}\) per cm \({ }^{3}\)
Volume available to each electron \(=10^{-22} \mathrm{~cm}^{3}\)
Momentum \(p_{x}=(2 \mathrm{mE})^{1 / 2}\) for 1 eV . \(=0.5 \times 10^{-19} \mathrm{erg}-\mathrm{sec} \mathrm{cm}^{-1}\)
Uncertainty in position \(\Delta \mathrm{x}=\mathrm{h} / \mathrm{p}_{\mathrm{x}} \quad=13 \times 10^{-8} \mathrm{~cm}\).
```

$$
\begin{aligned}
\text { Volume of conduction electron } & =\left(13 \times 10^{-8}\right)^{3} \mathrm{~cm}^{3} \\
& =2 \times 10^{-21} \mathrm{~cm}^{3} .
\end{aligned}
$$

- Comparing the volume of conduction electron to the volume available, we conclude that the electron wave functions overlap considerably and hence they are indistinguishable.
- Thus we have two categories of particles:
(i) Classical, which are identical but distinguishable.
(ii) Quantum, which are identical and indistinguishable.
- When quantum particle density is low, i.e., uncertainty is small in comparison to the volume available, the particles obey classical statistics otherwise we use quantum statistics.


### 5.5 ILLUSTRATION OF CLASSICAL AND QUANTUM STATISTICS

- Consider a gas consists of only two particles a and b.
- Assume that each particle can be in one of the possible quantum states $S=1,2,3$.
- Let us calculate the possible states of the whole gas.


## Maxwell -Boltzmann statistics:

- The particles are considered distinguishable and any number of particle can be any one state.

| $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ |
| :---: | :---: | :---: |
| ab | - | - |
| - | ab | - |
| - | - | ab |
| a | b | - |
| b | a | - |
| a | - | b |
| b | - | a |
| - | a | b |
| - | b | a |

- Total states $3^{2}=9$ possible states for the whole gas.


## Bose-Einstein statistics:

- Particles are indistinguishable, i.e $\mathrm{b}=\mathrm{a}$

| $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ |
| :---: | :---: | :---: |
| aa | - | - |

[^1]| - | aa | - |
| :---: | :---: | :---: |
| - | - | aa |
| a | a | - |
| a | - | a |
| - | a | a |

- $3+3=6$ possible states for the whole gas.


## Fermi-Dirac statistics:

- Particles are indistinguishable and no more than one particle can be in any one state.

| $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ |
| :---: | :---: | :---: |
| a | a | - |
| a | - | a |
| - | a | a |

- 3 possible states for the whole gas.

$$
\text { Let } \varepsilon=\frac{\text { probability that the two partcles are found in the same state }}{\text { probability that the two particle are found in different states }}
$$

- Thus for the three cases,

$$
\begin{aligned}
\varepsilon_{M-B} & =\frac{3}{6}=1 / 2 \\
\varepsilon_{B-E} & =\frac{3}{3}=1 \\
\varepsilon_{F-D} & =\frac{0}{3}=0
\end{aligned}
$$

- Thus in B-E statistics, there is a greater tendency for the particles to bunch together in the same states in comparison to M-B statistics.
- On the other hand, in the F-D statistics, there is a greater relative tendency to particles to remain apart in different states than there is in classical statistics.


### 5.6 BOSE-EINSTEIN STATISTICS:

- Consider a system having n identical and indistinguishable particles.
- These particles be divided into quantum groups such that there are $n_{1}, n_{2}, \ldots, n_{i}, \ldots$
number of particles with energies $\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{i}, \ldots$ respectively.
- $g_{i}$ be the number of eigen states in the $\mathrm{i}^{\text {th }}$ level.


## Conditions:

- Particles are identical and indistinguishable.
- Particles do not obey Pauli’s exclusion principle.
- The total number of particles in the system is constant.

$$
N=\sum n_{i}=\text { constant }
$$

- The total energy of the system is constant.

$$
E=\sum n_{i} \varepsilon_{i}=\text { constant }
$$

## Bose-Einstein distribution function:

- Consider the $\mathrm{i}^{\text {th }}$ level
- $g_{i}$ cells and $n_{i}$ particles. Here we have to find out how $n_{i}$ particles can be divided into $g_{i}$ cells.
- First the choice that which cell will head the sequence can be found as $g_{i}$ ways.
- Then the total number of permutations among $n_{i}$ particles and the remaining $\left(g_{i}-1\right)$ cells is $\left(n_{i}+g_{i}-1\right)$ !
- Now the total number of possible ways in which $n_{i}$ particles can be distributed in $g_{i}$ cells is
$g_{i}\left(n_{i}+g_{i} 1\right)!$
- Since the particles are indistinguishable the permutations of the particles among themselves will not give rise to different arrangements. Hence equation (1) must be divided by $n_{i}$ !

$$
\frac{g_{i}\left(n_{i}+g_{i}-1\right)!}{n_{i}!}
$$

- Similarly the permutations of cells among themselves will not give rise to different arrangements. Hence equation (1) must also be divided by $g_{i}$ !

$$
\frac{g_{i}\left(n_{i}+g_{i}-1\right)!}{n_{i}!g_{i}!}=\frac{\left(n_{i}+g_{i}-1\right)!}{n_{i}!\left(g_{i}-1\right)!}
$$

- Considering all the available groups such that $\mathrm{n}_{1}$ particles with energy $\varepsilon_{1}, \mathrm{n}_{2}$ particles with energy $\varepsilon_{2}$ and so on. Then the total number of possible arrangements is given by,

$$
\begin{gather*}
G \\
=\prod \frac{\left(n_{i}+g_{i}-1\right)!}{n_{i}!\left(g_{i}-1\right)!} \tag{2}
\end{gather*}
$$

$n_{i}$ and $g_{i} \gg 1$, hence one may be neglected.

$$
G=\prod \frac{\left(n_{i}+g_{i}\right)!}{n_{i}!g_{i}!}
$$

- The probability $\Omega$ of the system is proportional to the total number of eigen states.

$$
\Omega=G \times \text { constant }
$$

$$
\begin{aligned}
& \Omega=\prod \frac{\left(n_{i}+g_{i}\right)!}{n_{i}!g_{i}!} \times \text { constant } \\
& \qquad \log \Omega=\sum\left[\log \left(n_{i}+g_{i}\right)!-\log n!-\log g_{i}!\right]+\text { constant }
\end{aligned}
$$

- Using stirling's approximation, we get

$$
\begin{align*}
& \begin{array}{l}
\log \Omega=\sum\left[\left(n_{i}+g_{i}\right) \log \left(n_{i}+g_{i}\right)-\left(n_{i}+g_{i}\right)-n_{i} \log n_{i}+n_{i}-g_{i} \log g_{i}+g_{i}\right] \\
\quad+\text { constant }
\end{array} \\
& =\sum\left[\left(n_{i}+g_{i}\right) \log \left(n_{i}+g_{i}\right)-n_{i} \log n_{i}-g_{i} \log g_{i}\right]+\text { constant } \quad \ldots(4) \\
& \delta[\log \Omega]=\sum\left[\left(n_{i}+g_{i}\right) \frac{1}{\left(n_{i}+g_{i}\right)} \delta n_{i}+\log \left(n_{i}+g_{i}\right) \delta n_{i}-n_{i} \frac{1}{n_{i}} \delta n_{i}-\right. \tag{4}
\end{align*}
$$

$\log n i \delta n i+0$

$$
\begin{aligned}
& =\Sigma\left[\delta n_{i}+\log \left(n_{i}+g_{i}\right) \delta n_{i}-\delta n_{i}-\log n_{i} \delta n_{i}\right] \\
& =\Sigma\left[\log \left(n_{i}+g_{i}\right)-\log n_{i}\right] \delta n_{i}
\end{aligned}
$$

$$
=\Sigma\left[\log \left(\frac{n_{i}+g_{i}}{n_{i}}\right)\right] \delta n_{i}
$$

$$
=
$$

$$
\begin{equation*}
-\sum\left[\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)\right] \delta n_{i} \tag{5}
\end{equation*}
$$

$$
\delta(\log \Omega)=0
$$

$$
-\Sigma\left[\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)\right] \delta n_{i}=0
$$

$$
\begin{equation*}
\sum\left[\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)\right] \delta n_{i}=0 \tag{6}
\end{equation*}
$$

$$
\sum n_{i}=\text { constant }
$$

$$
\begin{equation*}
\sum \delta n_{i}=0 \tag{7}
\end{equation*}
$$

$$
\sum \varepsilon_{i} n_{i}=\text { constant }
$$

$$
\begin{equation*}
\sum \varepsilon_{i} \delta n_{i}=0 \tag{8}
\end{equation*}
$$

- Multiply the equation (7) by $\alpha$ and (8) by $\beta$ and then adding to equation (6),we get,

$$
\begin{aligned}
\sum\left[\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)+\alpha+\beta \varepsilon_{i}\right] \delta n_{i} & =0 \\
\delta n_{i} & \neq 0 \\
\therefore \sum\left[\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)+\alpha+\beta \varepsilon_{i}\right] & =0 \\
\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right)+\alpha+\beta \varepsilon_{i} & =0 \\
\log \left(\frac{n_{i}}{n_{i}+g_{i}}\right) & =-\left(\alpha+\beta \varepsilon_{i}\right) \\
\frac{n_{i}}{n_{i}+g_{i}} & =e^{-\left(\alpha+\beta \varepsilon_{i}\right)} \\
\frac{n_{i}+g_{i}}{n_{i}} & =e^{\alpha+\beta \varepsilon_{i}} \\
1+\frac{g_{i}}{n_{i}} & =e^{\alpha+\beta \varepsilon_{i}}
\end{aligned}
$$

$$
\begin{align*}
& \frac{g_{i}}{n_{i}}=e^{\alpha+\beta \varepsilon_{i}}-1 \\
& n_{i}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}-1}} \tag{10}
\end{align*}
$$

- This equation represents the most probable distribution for a system obeying Bose - Einstein statistics and known as Bose - Einstein distribution law.


### 5.7 FERMI-DIRAC STATISTICS:

- Consider a system having n identical and indistinguishable particles.
- These particles be divided into quantum groups such that there are $n_{1}, n_{2}, \ldots, n_{i}, \ldots$ number of particles with energies $\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{i}, \ldots$ respectively.
- $g_{i}$ be the number of eigen states in the $i^{\text {th }}$ level.


## Conditions:

- Particles are identical and indistinguishable
- Particles obey Pauli's exclusion principle. Hence each cell contains 0 (or) 1 particle. Obviously $g_{i} \geq n_{i}$.
- The total number of particles in the system is constant.

$$
N=\sum n_{i}=\text { constant }
$$

- The total energy of the system is constant.

$$
E=\sum n_{i} \varepsilon_{i}=\text { constant }
$$

## Fermi-Dirac distribution function:

- Consider the $\mathrm{i}^{\text {th }}$ level.
- There are $g_{i}$ cells and $n_{i}$ particles.
- Each cell must be occupied by zero or one particle.
- Among $g_{i}$ cells, only $n_{i}$ cells are occupied by one particle and the remaining $\left(g_{i}-n_{i}\right)$ cells are empty.
- The possible number of such a distribution is given by $g_{i}$ !
- Since the particles are indistinguishable the permutation of the particles among themselves will not give rise to different arrangements. Hence equation (1) must be divided by $n_{i}$ !

$$
\frac{g_{i}!}{n_{i}!}
$$

- $\left(g_{i}-n_{i}\right)$ ! permutations of empty cells among themselves will not give rise to different arrangements. Hence equation(1) must also be divided by $\left(g_{i}-n_{i}\right)$ !

$$
\frac{g_{i}!}{n_{i}!\left(g_{i}-n_{i}\right)!}
$$

- Considering all the available groups such that $n_{1}$ particles with energy $\varepsilon_{1}, n_{2}$ particles with energy $\varepsilon_{2}$ and so on. Then the total number of possible arrangements is given by

$$
\begin{equation*}
G=\Pi \frac{g_{i}!}{n_{i}!\left(g_{i}-n_{i}\right)!} \tag{2}
\end{equation*}
$$

- The probability $\Omega$ of the system is proportional to the total number of eigen states.

$$
\begin{gathered}
\Omega=G \times \text { constant } \\
\Omega=\prod \frac{g_{i}!}{n_{i}!\left(g_{i}-n_{i}\right)!} \times \text { constant } \\
\quad \log \Omega=\sum\left[\log g_{i}!-\log n_{i}!-\log \left(g_{i}-n_{i}\right)!\right]+\text { constant }
\end{gathered}
$$

- Using stirling' approximation, we get

$$
\begin{aligned}
& \log \Omega= \sum\left[g_{i} \log g_{i}-g_{i}-n_{i} \log n_{i}+n_{i}-\left(g_{i}-n_{i}\right) \log \left(g_{i}-n_{i}\right)+\left(g_{i}-n_{i}\right)\right] \\
&+ \text { constant } \\
&= \sum\left[g_{i} \log g_{i}-n_{i} \log n_{i}-\left(g_{i}-n_{i}\right) \log \left(g_{i}-n_{i}\right)\right]+\text { constant } \\
& \delta(\log \Omega)=\sum\left[-n_{i} \frac{1}{n_{i}} \delta n_{i}-\log n_{i} \delta n_{i}-\frac{\left(g_{i}-n_{i}\right)}{\left(g_{i}-n_{i}\right)}\left(-\delta n_{i}\right)-\log \left(g_{i}-n_{i}\right)\left(-\delta n_{i}\right)\right] \\
&= \sum\left[-\delta n_{i}-\log n_{i} \delta n_{i}+\delta n_{i}+\log \left(g_{i}-n_{i}\right) \delta n_{i}\right] . \\
&=\sum\left[\log n_{i} \delta n_{i}+\log \left(g_{i}-n_{i}\right) \delta n_{i}\right] .
\end{aligned}
$$

$$
=\Sigma\left[\log \left(\frac{g_{i}-n_{i}}{n_{i}}\right) \delta n_{i}\right] .
$$

$=-\sum\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right) \delta n_{i}\right]$
$\delta(\log \Omega)=0$
$-\sum\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right) \delta n_{i}\right]=0$.

$$
\begin{equation*}
\sum\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right) \delta n_{i}\right]=0 \tag{6}
\end{equation*}
$$

$$
\sum n_{i}=\text { constant }
$$

$\sum \delta n_{i}=0$
$\sum \varepsilon n_{i}=$ constant.
$\sum \varepsilon \delta n_{i}=0$

- Multiplying equation (7) by $\alpha$ and (8) by $\beta$ and then adding to equation (6), we get

$$
\begin{aligned}
\sum\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right)+\alpha+\beta \varepsilon_{i}\right] \delta n_{i} & =0 \\
\sum\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right)+\alpha+\beta \varepsilon_{i}\right] & =0 \\
{\left[\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right)+\alpha+\beta \varepsilon_{i}\right] } & =0 \\
\log \left(\frac{n_{i}}{g_{i}-n_{i}}\right) & =-\left(\alpha+\beta \varepsilon_{i}\right) \\
\frac{n_{i}}{g_{i}-n_{i}} & =e^{-\left(\alpha+\beta \varepsilon_{i}\right)} \\
\frac{g_{i}-n_{i}}{n_{i}} & =e^{\alpha+\beta \varepsilon_{i}} \\
\frac{g_{i}}{n_{i}}-1 & =e^{\alpha+\beta \varepsilon_{i}}
\end{aligned}
$$

$$
\begin{aligned}
& \frac{g_{i}}{n_{i}}=e^{\alpha+\beta \varepsilon_{i}}+1 \\
& n_{i}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}}+1}
\end{aligned}
$$

- This equation represents the most probable distribution for a system obeying Fermi-Dirac statistics and known as Fermi-Dirac distribution law.


### 5.8 AN IDEAL GAS IN A QUANTUM MECHANICAL MICRO CANONICAL ENSEMBLE:

- We consider a gaseous system of N non-interacting, indistinguishable particles confined to a space of volume V and energy E .
- Let $\Omega(N, V, E)$ be the number of distinct microstates accessible to the system under the macro state $\Omega(N, V, E)$.
- Let $\varepsilon_{i}$ denote the average energy of a level and $g_{i}$ be the number of levels in the $i^{\text {th }}$ cell. $g_{i} \gg 1$.
- We have $n_{1}$ particles in the first cell, $n_{2}$ particles in the second cell and so on. The distribution set $n_{i}$ must confirm to the conditions,

$$
\begin{gather*}
\sum_{i} n_{i}=N  \tag{1}\\
\sum_{i} n_{i} \varepsilon_{i}=E \tag{2}
\end{gather*}
$$

- Then $\quad \Omega(N, V, E)=\Sigma^{\prime} W\left\{n_{i}\right\}$
- $W\left\{n_{i}\right\}$ is the number of distinct microstates associated with the distribution $\operatorname{set}\left\{n_{i}\right\}$. The primed summation goes over all distribution sets that confirm to conditions (1) and (2),
- $W\left\{n_{i}\right\}=\prod_{i} w(i)$
- $w(i)$ is the number of distinct ways in which the $n_{i}$ identical and indistinguishable particles can be distributed among the $g_{i}$ levels of the $i^{\text {th }}$ cell.
- In B-E case $\quad w_{B E}(i)=\frac{\left(n_{i}+g_{i}-1\right)!}{n_{i}!\left(g_{i}-1\right)!}$
and hence $\quad W_{B E}\left(n_{i}\right)=\prod \frac{\left(n_{i}+g_{i}-1\right)!}{n_{i}!\left(g_{i}-1\right)!}$
- In the F-D case, no single level can accommodate more than one particle.

$$
\begin{array}{cc} 
& w_{F D}(i)=\frac{g_{i}!}{n_{i}!\left(g_{i}-1\right)!} \\
\text { and hence } \quad & W_{F D}\left(n_{i}\right)=\frac{g_{i}!}{n_{i}!\left(g_{i}-1\right)!} \tag{6}
\end{array}
$$

- In M-B case the particle are distinguishable.
- $\quad W_{M B}\left(n_{i}\right)=\Pi \frac{\left(g_{i}\right)^{n_{i}}}{n_{i}!}$
- Now the entropy of the system would be given by,

$$
\begin{align*}
S(N, V, E) & =k \ln \Omega(N, V, E) \\
& =k \ln \left[\sum_{n_{i}}^{\prime} W\left(n_{i}\right)\right] \\
& \approx k \ln W\left(n_{i}^{*}\right) \tag{8}
\end{align*}
$$

- $\left(n_{i}{ }^{*}\right)$ is the distribution set that maximizes the number $W\left\{n_{i}\right\} . n_{i}^{*}$ is the most probable value of the distribution number $n_{i}$.
- Our condition for determining the most probable distribution set $\left\{n_{i}^{*}\right\}$ now turns out to be,

$$
\begin{align*}
\delta \ln W\left(n_{i}\right)-\left[\alpha \sum_{i} \delta n_{i}+\beta \sum_{i} \varepsilon_{i} \delta n_{i}\right] & =0  \tag{9}\\
\ln W\left(n_{i}\right) & =\sum_{i} \ln w(i)
\end{align*}
$$

- In B-E case,

$$
\begin{aligned}
& W_{B E}\left(n_{i}\right)=\Pi \frac{\left(n_{i}+g_{i}-1\right)!}{n_{i}!\left(g_{i}-1\right)!} \\
& \approx \Pi \frac{\left(n_{i}+g_{i}\right)!}{n_{i}!g_{i}!} \\
& \ln W_{B E}\left(n_{i}\right)=\sum\left[\ln \left(n_{i}+g_{i}\right)!-\ln n_{i}!-\ln g_{i}!\right] \\
&=\sum\left[\left(n_{i}+g_{i}\right) \ln \left(n_{i}+g_{i}\right)-\left(n_{i}+g_{i}\right)-n_{i} \ln n_{i}+n_{i}-\right.
\end{aligned}
$$

$g i \ln g i+g i$

$$
=\Sigma\left[\left(n_{i}+g_{i}\right) \ln \left(n_{i}+g_{i}\right)-n_{i} \ln n_{i}-\right.
$$

$g i \ln g i$

$$
\begin{aligned}
=\sum\left[n_{i} \ln \left(n_{i}+g_{i}\right)-\right. & \left.n_{i} \ln n_{i}+g_{i} \ln \left(n_{i}+g_{i}\right)-g_{i} \ln g_{i}\right] \\
& =\sum\left\{n_{i} \ln \left[\frac{n_{i}+g_{i}}{n_{i}}\right]+g_{i} \ln \left[\frac{n_{i}+g_{i}}{g_{i}}\right]\right\} \\
& =\sum\left\{n_{i} \ln \left(\frac{g_{i}}{n_{i}}+1\right)+g_{i} \ln \left(1-a \frac{n_{i}}{g_{i}}\right)\right\}
\end{aligned}
$$

- In general,

$$
\begin{array}{cc}
\ln W\left(n_{i}\right)=\sum\left\{n_{i} \ln \left(\frac{g_{i}}{n_{i}}-a\right)-\frac{g_{i}}{a} \ln \left(1-a \frac{n_{i}}{g_{i}}\right)\right\}  \tag{10}\\
\mathrm{a}=-1 & \text { BE case } \\
\mathrm{a}=+1 & \text { FD case } \\
\mathrm{a}=0 & \text { MB case }
\end{array}
$$

$$
\delta \ln W_{B E}\left(n_{i}\right)=\sum\left[\left(n_{i}+g_{i}\right) \frac{\delta n_{i}}{\left(n_{i}+g_{i}\right)}+\ln \left(n_{i}+g_{i}\right) \delta n_{i}-n_{i} \frac{\delta n_{i}}{n_{i}}-\right.
$$

## $\ln n i \delta n i$

$$
\begin{aligned}
& =\sum\left[\ln \left(n_{i}+g_{i}\right)-\ln n_{i}\right] \delta n_{i} \\
& =\sum\left[\ln \left(\frac{n_{i}+g_{i}}{n_{i}}\right) \delta n_{i}\right] \\
& =\sum\left[\ln \left(\frac{g_{i}}{n_{i}}+1\right) \delta n_{i}\right]
\end{aligned}
$$

- In F-D case,

$$
\begin{aligned}
& W_{F D}=\prod \frac{g_{i}!}{n_{i}!\left(g_{i}-n_{i}\right)!} \\
& \ln W_{F D}=\sum\left[\ln g_{i}!-\ln n_{i}!-\ln \left(g_{i}-n_{i}\right)!\right] \\
& =\sum\left[g_{i} \ln g_{i}-g_{i}-n_{i} \ln n_{i}+n_{i}-\left(g_{i}-n_{i}\right) \ln \left(g_{i}-n_{i}\right)+\right.
\end{aligned}
$$

$g i-n i$

$$
\begin{aligned}
& =\sum\left(g_{i} \ln n_{i}-n_{i} \ln n_{i}-\left(g_{i}-n_{i}\right) \ln \left(g_{i}-n_{i}\right)\right) \\
\delta \ln W_{F D} & =\sum\left[-n_{i} \frac{\delta n_{i}}{n_{i}}-\ln n_{i} \delta n_{i}-\left(g_{i}-n_{i}\right) \frac{\left(-\delta n_{i}\right)}{g_{i}-n_{i}}-\ln \left(g_{i}-\right.\right.
\end{aligned}
$$

$n i-\delta n i$

$$
\begin{aligned}
& =\sum\left[\left(-\delta n_{i}\right)-\ln n_{i} \delta n_{i}+\delta n_{i}+\ln \left(g_{i}-n_{i}\right) \delta n_{i}\right] \\
& =\sum\left[\ln \left(\frac{g_{i}-n_{i}}{n_{i}}\right) \delta n_{i}\right]=\sum\left[\ln \left(\frac{g_{i}}{n_{i}}-1\right) \delta n_{i}\right]
\end{aligned}
$$

- In M-B case

$$
\begin{aligned}
W_{M B}\left(n_{i}\right) & =\Pi \frac{\left(g_{i}\right)^{n_{i}}}{n_{i}!} \\
\ln W_{M B} & =\sum\left[n_{i} \ln g_{i}-\ln n_{i}!\right] \\
& =\sum\left[n_{i} \ln g_{i}-n_{i} \ln n_{i}+n_{i}\right] \\
\delta \ln W_{M B} & =\sum\left[n_{i} \cdot 0+\ln g_{i} \delta n_{i}-n_{i} \frac{\delta n_{i}}{n_{i}}-\ln n_{i} \delta n_{i}+\delta n_{i}\right] \\
& =\sum\left[\ln g_{i} \delta n_{i}-\delta n_{i}-\ln n_{i} \delta n_{i}+\delta n_{i}\right] \\
& =\sum\left[\ln \left(\frac{g_{i}}{n_{i}}\right) \delta n_{i}\right]=\sum\left[\ln \left(\frac{g_{i}}{n_{i}}-a\right) \delta n_{i}\right]
\end{aligned}
$$

- Now equation (9) becomes,

$$
\begin{array}{r}
\sum_{i}\left[\ln \left(\frac{g_{i}}{n_{i}}-a\right)-\alpha-\beta \varepsilon_{i}\right]_{n=n^{*}} \quad \delta n_{i}=0 \\
\ln \left(\frac{g_{i}}{n_{i}{ }^{*}}-a\right)-\alpha-\beta \varepsilon_{i}=0 \\
\ln \left(\frac{g_{i}}{n_{i}{ }^{*}}-a\right)=\alpha+\beta \varepsilon_{i} \\
\frac{g_{i}}{n_{i}{ }^{*}}-a=e^{\alpha+\beta \varepsilon_{i}} \\
\hline
\end{array}
$$

$$
\begin{gather*}
\frac{g_{i}}{n_{i}{ }^{*}}=e^{\alpha+\beta \varepsilon_{i}}+a \\
\frac{n_{i}{ }^{*}}{g_{i}}=\frac{1}{e^{\alpha+\beta \varepsilon_{i}+a}}  \tag{11}\\
n_{i}{ }^{*}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}+a}}  \tag{12}\\
\frac{s}{k} \approx \ln W\left(n_{i}{ }^{*}\right)=\sum_{i}\left[n_{i}{ }^{*} \ln \left(\frac{g_{i}}{n_{i}{ }^{*}}-a\right)-\frac{g_{i}}{a} \ln \left(1-a \frac{n_{i}{ }^{*}}{g_{i}}\right)\right] \\
=\sum_{i}\left[n_{i}{ }^{*}\left(\alpha+\beta \varepsilon_{i}\right)-\frac{g_{i}}{a} \ln \left(1-\frac{a}{e^{\alpha+\beta \varepsilon_{i}}+a}\right)\right] \\
=\sum_{i}\left[n_{i}{ }^{*}\left(\alpha+\beta \varepsilon_{i}\right)-\frac{g_{i}}{a} \ln \left(\frac{e^{\alpha+\beta \varepsilon_{i}}}{e^{\alpha+\beta \varepsilon_{i}+a}}\right)\right] \\
\quad=\sum_{i}\left[n_{i}{ }^{*}\left(\alpha+\beta \varepsilon_{i}\right)-\frac{g_{i}}{a} \ln \left(\frac{1}{1+a e^{-\left(\alpha+\beta \varepsilon_{i}\right)}}\right)\right] \\
=\sum\left[n_{i}{ }^{*}\left(\alpha+\beta \varepsilon_{i}\right)+\frac{g_{i}}{a} \ln \left[1+a e^{-\alpha-\beta \varepsilon_{i}}\right]\right] \tag{13}
\end{gather*}
$$

- The first sum on RHS of (13) is $\alpha \mathrm{N}$ while the second sum is $\beta \mathrm{E}$. For the third sum, we have

$$
\begin{array}{r}
\frac{1}{a} \sum g_{i} \ln \left[1+a e^{\alpha+\beta \varepsilon_{i}}\right]=\frac{S}{k}-\alpha N-\beta E  \tag{14}\\
\alpha=-\frac{\mu}{k T} \text { and } \beta=\frac{1}{k T}
\end{array}
$$

- The RHS of equation (14) is equal to,

$$
\frac{S}{k}+\frac{\mu N}{k T}-\frac{E}{k T}=\frac{G-(E-T S)}{k T}=\frac{P V}{k T}
$$

- The thermodynamic pressure of the system is given by

$$
\begin{align*}
P V & =\frac{k T}{a} \sum_{i}\left[g_{i} \ln \left[1+a e^{-\alpha-\beta \varepsilon_{i}}\right]\right]  \tag{15}\\
\frac{P V}{k T} & =a^{-1} \sum_{i}\left[g_{i} \ln \left[1+a e^{-\alpha-\beta \varepsilon_{i}}\right]\right] \tag{16}
\end{align*}
$$

- In M-B case $(a \rightarrow 0)$, equation (15) takes the form

$$
\begin{align*}
& \quad P V=k T \sum g_{i} e^{-\alpha-\beta \varepsilon_{i}} \\
& \quad=k T \sum_{i} n_{i}^{*} \\
& =N k T \tag{17}
\end{align*}
$$

- Which is the familiar equation of state of the classical ideal gas. Equation (17) for the M-B case holds irrespective of $\varepsilon_{i}$. The RHS of equation (16) is to be identical to the q-potential of the ideal gas.


### 5.9 AN IDEAL GAS IN A QUANTUM MECHANICAL GRAND CANONICAL ENSEMBLE:

- In canonical ensemble, the thermodynamics of a given system is derived from its partition function

$$
\begin{align*}
& Q_{N}(V, T)=\sum_{E} e^{-\beta E}  \tag{1}\\
& \quad \mathrm{E} \rightarrow \text { energy eigen values of the system. } \\
& \quad \text { and } \beta=1 / k T
\end{align*}
$$

- E can be expressed in terms of the single-particle energies $\varepsilon$. For instance

$$
\begin{align*}
& E=\sum_{\varepsilon} n_{\varepsilon} \varepsilon \ldots .(2  \tag{2}\\
& n_{\varepsilon}=\text { number of particles in the single-particle energy }
\end{align*}
$$

state $\varepsilon$.

$$
\begin{equation*}
\text { Also } \sum_{\varepsilon} n_{\varepsilon}=N \tag{3}
\end{equation*}
$$

- Now equation (1) can be written as,

$$
\begin{equation*}
Q_{N}(V, T)=\sum_{\left\{n_{\varepsilon}\right\}}^{\prime} g\left\{n_{\varepsilon}\right\} e^{-\beta \sum_{\varepsilon} n_{\varepsilon} \varepsilon} \tag{4}
\end{equation*}
$$

$g\left\{n_{\varepsilon}\right\}=$ statistical weight factor appropriate to the distribution set $\left\{n_{\varepsilon}\right\}$
$\Sigma^{\prime} \rightarrow$ goes over all distribution sets that conform to the restrictive condition(3).

- The statistical weight factor is given by

$$
\begin{align*}
g_{B-E}\left\{n_{\varepsilon}\right\} & =1  \tag{5}\\
g_{F-D}\left\{n_{\varepsilon}\right\} & =1  \tag{6}\\
& =0
\end{align*} \quad\left\{\begin{array}{l}
\text { if all } n_{\varepsilon}=0 \\
\text { Otherwise }
\end{array} \text { (or) } 1\right.
$$

and

$$
\begin{equation*}
g_{M-B}\left\{n_{\varepsilon}\right\}=\prod_{\varepsilon} \frac{1}{n_{\varepsilon}!} \tag{7}
\end{equation*}
$$

- Here we are dealing with single-particle states as individual states without requiring them to be grouped into cells.
- Take M-B case and substituting equation (7) into (4) we get

$$
\begin{gather*}
Q_{N}(V, T)=\sum_{\left\{n_{\varepsilon}\right\}}^{\prime}\left[\left(\prod_{\varepsilon} \frac{1}{n_{\varepsilon}!}\right) \prod_{\varepsilon}\left(e^{-\beta \varepsilon}\right)^{n_{\varepsilon}}\right] \\
=\frac{1}{N!} \sum_{\left\{n_{\varepsilon}\right\}}^{\prime}\left[\frac{N!}{\prod_{\varepsilon} n_{\varepsilon}!} \prod_{\varepsilon}\left(e^{-\beta \varepsilon}\right)^{n_{\varepsilon}}\right] \tag{8}
\end{gather*}
$$

- Evaluated with the help of the multinomial theorem

$$
\begin{gather*}
Q_{N}(V, T)=\frac{1}{N!}\left[\sum_{\varepsilon} e^{-\beta \varepsilon}\right]^{N} \\
=\frac{1}{N!}\left[Q_{1}(V, T)\right]^{N} \tag{9}
\end{gather*}
$$

- The number of single particle states with energies lying between $\varepsilon$ and $\varepsilon+\mathrm{d} \varepsilon$ is,

$$
\begin{align*}
& Q_{1}(V, T)=\sum_{\varepsilon} e^{-\beta \varepsilon} \\
& \qquad \begin{array}{l}
\approx \frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \int_{0}^{\infty} e^{-\beta \varepsilon} \varepsilon^{1 / 2} d \varepsilon \\
\\
=\frac{2 \pi V}{h^{3}}(2 m)^{3 / 2} \frac{1}{2} \sqrt{\frac{\pi}{\beta^{3}}}
\end{array} \tag{10}
\end{align*}
$$

$$
\begin{align*}
& =V \frac{(2 \pi m k T)^{3 / 2}}{h^{3}}=\frac{V}{\lambda^{3}} \\
\text { where } \lambda & =h /(2 \pi m k T)^{1 / 2} \\
& =\text { mean thermal wavelength of the particles. } \tag{11}
\end{align*}
$$

- Hence, $Q_{N}(V, T)=\frac{V^{N}}{N!!^{3 N}}$
- From which complete thermodynamics of this system can be derived.
- We obtain for the grand partition function of this system,

$$
\begin{align*}
& \mathbf{Q}(z, V, T)= \\
& \quad \sum_{N=0}^{\infty} Z^{N} Q_{N}(V, T) \\
& \quad=\sum_{N=0}^{\infty} z^{N} \frac{1}{N!} \frac{V^{N}}{\lambda^{3 N}}=\frac{1}{N!} \sum_{N=0}^{\infty}\left(\frac{Z V}{\lambda^{3}}\right)^{N}  \tag{12}\\
& =\exp \left(z V / \lambda^{3}\right)
\end{align*}
$$

- B-E and F-D cases:

$$
\begin{equation*}
Q_{N}(V, T)=\sum_{\left\{n_{\varepsilon}\right\}}^{\prime}\left(e^{-\beta \sum_{\varepsilon} n_{\varepsilon} \varepsilon}\right) \tag{13}
\end{equation*}
$$

- Now complete thermodynamics of this system can be derived.
- The Grand partition function $\mathbf{Q}$ turns out to be

$$
\begin{align*}
& \mathbf{Q}(z, V, T)=\sum_{N=o}^{\infty}\left[z^{N} \sum_{\left\{n_{\varepsilon}\right\}}^{\prime}\left(e^{-\beta \sum_{\varepsilon} n_{\varepsilon} \varepsilon}\right)\right] \\
& =\sum_{N=0}^{\infty}\left[\sum_{\left\{n_{\varepsilon}\right\}}^{\prime} \prod_{\varepsilon}\left(z e^{-\beta \varepsilon}\right)^{n_{\varepsilon}}\right] \tag{14}
\end{align*}
$$

- The double summation in (14) over the number $n_{\varepsilon}$ constrained by a fixed value of the total number N and then over all possible values of N , which is equivalent to a summation over all possible values of $n_{\varepsilon}$ independently of one another.
- Hence,

$$
\begin{align*}
& \mathbf{Q}(z, V, T)=\sum_{n_{0}, n_{1}, \ldots . . .}\left[\left(z e^{-\beta \varepsilon_{0}}\right)^{n_{0}}\left(z e^{-\beta \varepsilon_{1}}\right)^{n_{1}} \ldots\right] \\
& \quad=\left[\sum_{n_{0}}\left(z e^{-\beta \varepsilon_{0}}\right)^{n_{0}}\right]\left[\sum_{n_{1}}\left(z e^{-\beta \varepsilon_{1}}\right)^{n_{1}}\right] \tag{15}
\end{align*}
$$

- In B-E case $n_{\varepsilon}$ can be either 0 or 1 or 2 or $\ldots .$.
- In F-D case $n_{\varepsilon}$ can be only 0 or 1 .

$$
\mathbf{Q}(z, V, T)= \begin{cases}\prod_{\varepsilon} \frac{1}{\left(1-z e^{-\beta \varepsilon}\right)} & \text { in B-E case with } z e^{-\beta \varepsilon}<1 .  \tag{16}\\ \prod_{\varepsilon}\left(1+z e^{-\beta \varepsilon}\right) & \text { in F-D case }\end{cases}
$$

The q potential of the system is thus given by,

$$
\begin{align*}
q(z, V, T) & =\frac{P V}{k T}=\ln Q(z, V, T) \\
& =\mp \sum_{\varepsilon} \ln \left(1 \mp z e^{-\beta \varepsilon}\right)  \tag{17}\\
\text { with } g_{i} & =1
\end{align*}
$$

- The identification of the fugacity z with the quantity $e^{-\alpha}$ is quite natural. $\alpha=$ $-\frac{\mu}{k T}$
- The upper sign in equation (17) corresponds to Bose case.
- The lower sign in equation (17) corresponds to Fermi case.
- Now in general,

$$
\begin{equation*}
q(z, V, T)=\frac{P V}{k T}=\frac{1}{a} \sum_{\varepsilon} \ln \left(1+a z e^{-\beta \varepsilon}\right) \tag{18}
\end{equation*}
$$

- Where $a=-1,+1$ or 0 depending on the statistics governing the system.
- In classical case $a \rightarrow 0$ gives,

$$
\begin{align*}
q_{M-B} & =z \sum_{\varepsilon} e^{-\beta \varepsilon}=z Q_{1}  \tag{19}\\
\bar{N} & \equiv z\left(\frac{\partial q}{\partial z}\right)_{V, T} \\
& =z \frac{1}{a} \sum \frac{a e^{-\beta \varepsilon}}{1+a z e^{-\beta \varepsilon}} \\
& =\sum \frac{z}{e^{\beta \varepsilon}+a z} \\
& =\sum \frac{1}{z^{-1} e^{\beta \varepsilon}+a}  \tag{20}\\
\bar{E} & \equiv-\left(\frac{\partial q}{\partial \beta}\right)_{z, V} \\
& =-\frac{1}{a} \sum \frac{\left(a z e^{-\beta \varepsilon}\right)(-\varepsilon)}{1+a z e^{-\beta \varepsilon}} \\
= & \sum \frac{\varepsilon}{z^{-1} e^{\beta \varepsilon}+a} \tag{21}
\end{align*}
$$

- At the same time, the mean occupation number $\left\langle n_{\varepsilon}\right\rangle$ of level $\varepsilon$ turns out to be,

$$
\begin{align*}
\left\langle n_{\varepsilon}\right\rangle & =\frac{1}{\mathbf{Q}}\left[-\frac{1}{\beta}\left(\frac{\partial \mathbf{Q}}{\partial \varepsilon}\right)_{z, T, \text { all other } \varepsilon}\right] \\
& =-\frac{1}{\beta}\left(\frac{\partial q}{\partial \varepsilon}\right)_{z, T, \text { all other } \varepsilon} \\
& =-\frac{1}{\beta} \frac{1}{a} \frac{a z e^{-\beta \varepsilon}(-\beta)}{1+a z e^{-\beta \varepsilon}} \\
& =\frac{z e^{-\beta \varepsilon}}{1+a z e^{-\beta \varepsilon}} \\
& =\frac{1}{z^{-1} e^{\beta \varepsilon}+a} \tag{22}
\end{align*}
$$

Thus the mean value $<\mathrm{n}>$ and the most probable value $\mathrm{n}^{*}$ of the occupation number n of a single particle state are identical.

### 5.10 STATISTICS OF THE OCCUPATION NUMBERS :

- The mean occupation number of a single particle with energy $\varepsilon$ as an explicit function of the quantity $(\varepsilon-\mu) / k T$ :

$$
\begin{equation*}
\left\langle n_{\varepsilon}\right\rangle=\frac{1}{e^{(\varepsilon-\mu) / k T}+a} \tag{1}
\end{equation*}
$$

- The functional behaviour of this number is shown in figure.
- In the Fermi-Dirac case $(a=+1)$, the mean occupation number never exceeds unity, for the variable $\mathrm{n}_{\varepsilon}$, itself cannot have a value other than 0 or 1 .
- Moreover $\varepsilon<\mu$ and $|\varepsilon-\mu| \gg k T$, the mean occupation number tends to its maximum possible
 value 1
- In the Bose-Einstein case $(a=-1)$ we must have $\mu<$ all $\varepsilon$. When $\mu$ becomes equal to the lowest value of $\varepsilon\left(\varepsilon_{0}\right)$, the occupancy level becomes high which leads to Bose-Einstein condensation.
- For $\mu<\varepsilon_{0}$ all $(\varepsilon-\mu)$ are positive and the behaviour of all $\left\langle n_{\varepsilon}\right\rangle$ is nonsingular. Finally in Maxwell-Boltzmann case $(a=0)$, the mean occupation number takes the form

$$
\begin{equation*}
\left\langle n_{\varepsilon}\right\rangle_{M B}=\exp \{(\mu-\varepsilon) / k T\} \propto \exp (-\varepsilon / k T) \tag{2}
\end{equation*}
$$

- We note here that the distinction between the quantum statistics and the classical statistics becomes imperceptible when for all values of $\varepsilon$,

$$
\begin{equation*}
\exp \{(\mu-\varepsilon) / k T\} \gg 1 . \tag{3}
\end{equation*}
$$

- Now equation (1) reduces to (2) and we may write $\left\langle n_{\varepsilon}\right\rangle \ll 1$.
- Condition (4) implies that the probability of any of the $n_{\varepsilon}$ being greater than unity is quite negligible.
- The distinction between the classical treatment and the quantum-mechanical treatment then becomes rather insignificant.
- Correspondingly for large values of $(\varepsilon-\mu) / k T$ the quantum curves 1 and 2 essentially merge into the classical curve 3 .
- Condition (3) also implies that $\mu$, the chemical potential of the system must be negative and large in magnitude. This means that the fugacity $z \mid \equiv \exp (\mu / k T)$ of the system must be much smaller than unity.
- This is further equivalent to $\frac{N \lambda^{3}}{V} \ll 1$
- Now we examine statistical fluctuations in the variable $\mathrm{n}_{\varepsilon}$. We have

$$
\begin{equation*}
\left\langle n_{\varepsilon}^{2}\right\rangle=\frac{1}{Q}\left[\left(-\frac{1}{\beta} \frac{\partial}{\partial \varepsilon}\right)^{2} Q\right]_{z, T, \text { all other } \varepsilon} \tag{6}
\end{equation*}
$$

- It follows that

$$
\begin{align*}
\left\langle n_{\varepsilon}^{2}\right\rangle-\left\langle n_{\varepsilon}\right\rangle^{2} & =\left[\left(-\frac{1}{\beta} \frac{\partial}{\partial \varepsilon}\right)^{2} \ln Q\right]_{z, T, \text { all other } \varepsilon} \\
& =\left[\left(-\frac{1}{\beta} \frac{\partial}{\partial \varepsilon}\right)\left\langle n_{\varepsilon}\right\rangle\right]_{z, T} \tag{7}
\end{align*}
$$

- For the relative mean-square fluctuation we obtain

$$
\begin{equation*}
\frac{\left\langle n_{\varepsilon}^{2}\right\rangle-\left\langle n_{\varepsilon}\right\rangle^{2}}{\left\langle n_{\varepsilon}\right\rangle^{2}}=\left(\frac{1}{\beta} \frac{\partial}{\partial \varepsilon}\right)\left\{\frac{1}{\left\langle n_{\varepsilon}\right\rangle}\right\}=z^{-1} e^{\beta \varepsilon} \tag{8}
\end{equation*}
$$

- The actual value of this quantity will depend on the statistics of the particles because for a given particle density ( $\mathrm{N} / \mathrm{V}$ ) and a given temperature T , the value of z will be different for different statistics.
- Equation (8) can be written in the form

$$
\begin{equation*}
\frac{\left\langle n_{\varepsilon}^{2}\right\rangle-\left\langle n_{\varepsilon}\right\rangle^{2}}{\left\langle n_{\varepsilon}\right\rangle^{2}}=\frac{1}{\left\langle n_{\varepsilon}\right\rangle}-a \tag{9}
\end{equation*}
$$

- In the classical case $(a=0)$, the relative fluctuation is normal.
- In the Fermi-Dirac case it is given by $1 /\left\langle n_{\varepsilon}\right\rangle-1$, which is below normal and tends to vanish as $\left\langle n_{\varepsilon}\right\rangle \rightarrow 1$.
- In the Bose-Einstein case , the fluctuation is above normal .
- This result would apply to a gas of photons and hence to the oscillators states in the black-body radiation.
- To understand the statistics of the occupation numbers, we evaluate the quantity $p_{\varepsilon}(n)$, the probability that there are exactly n particles in a state of energy $\varepsilon$.
- We know that $p_{\varepsilon}(n) \propto\left(z e^{-\beta \varepsilon}\right)^{n}$. On normalization, it becomes in the BoseEinstein case

$$
\begin{align*}
& \left.p_{\varepsilon}(n)\right|_{B . E}=\left(z e^{-\beta \varepsilon}\right)^{n}\left[1-z e^{-\beta \varepsilon}\right] \\
& \quad=\left(\frac{\left\langle n_{\varepsilon}\right\rangle}{\left\langle n_{\varepsilon}\right\rangle+1}\right)^{n} \frac{1}{\left\langle n_{\varepsilon}\right\rangle+1}=\frac{\left(\left\langle n_{\varepsilon}\right\rangle\right)^{n}}{\left(\left\langle n_{\varepsilon}\right\rangle+1\right)^{n+1}} \tag{10}
\end{align*}
$$

- In the Fermi-Dirac case, we get

$$
\begin{align*}
\left.p_{\varepsilon}(n)\right|_{F . D} & =\left(z e^{-\beta \varepsilon}\right)^{n}\left[1+z e^{-\beta \varepsilon}\right]^{-1} \\
& =\left\{\begin{array}{lll}
1-\left\langle n_{\varepsilon}\right\rangle & \text { for } & n=0 \\
\left\langle n_{\varepsilon}\right\rangle & \text { for } & n=1
\end{array}\right. \tag{11}
\end{align*}
$$

- In the Maxwell-Boltzmann case, we have $p_{\varepsilon}(n) \propto\left(z e^{-\beta \varepsilon}\right)^{n} / n$ !
- On normalization we get

$$
\begin{equation*}
\left.p_{\varepsilon}(n)\right|_{M \cdot B}=\frac{\left(z e^{-\beta \varepsilon}\right)^{n} / n!}{\exp \left(z e^{-\beta \varepsilon}\right)}=\frac{\left(\left\langle n_{\varepsilon}\right\rangle\right)^{n}}{n!} e^{-\left\langle n_{\varepsilon}\right\rangle} \tag{12}
\end{equation*}
$$

- Equation (12) is clearly a Poisson distribution for which the mean square deviation of the variable is equal to the mean value itself.
- It also resembles the distribution of the total particle number N in a grand canonical ensemble consisting of ideal, classical systems.
- Here we seen that the ratio $p_{\varepsilon}(n) / p_{\varepsilon}(n-1)$ varies inversely with n , which is a "normal" statistical behaviour of uncorrelated events.
- The distribution in the Bose-Einstein case is geometric with a common ratio $\left\langle n_{\varepsilon}\right\rangle /\left(\left\langle n_{\varepsilon}\right\rangle+1\right)$.
- This means that the probability of a state $\varepsilon$ acquiring one more particle for itself is independent of the number of particles already occupying the state.
- In comparison with "normal" statistical behaviour, bosons exhibit a special tendency of "bunching" together. That is a positive statistical correlation among them. Fermions exhibit negative statistical correlation.


### 5.11 IDEAL BOSE-EINSTEIN GAS:

- Consider a perfect Bose-Einstein gas of n bosons.
- These particles be divided into quantum groups such that there are $n_{1}, n_{2}, \ldots, n_{i}, \ldots$ number of particles with energies $\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{i}, \ldots$ respectively.
- $g_{i}$ be the number of eigen states in the $\mathrm{i}^{\text {th }}$ level.
- For the most probable distribution

$$
\begin{aligned}
& n_{i}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}-1}} \text { here } \alpha=\frac{-\mu}{k T} \text { and } \beta=\frac{1}{k T} \\
&=\frac{g_{i}}{\frac{1}{A} e^{\beta \varepsilon_{i}}} \\
& \text { where, } A=e^{-\alpha}
\end{aligned}
$$

- Since the number of particles cannot be negative, we must always have

$$
n_{i} \geq 0 \quad \frac{1}{A} e^{\beta \varepsilon_{i}} \geq 0
$$

- The constant $\alpha$ can be determined by the condition

$$
\begin{align*}
& \quad n=\sum n_{i}=\sum \frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i-1}}} \\
& =\sum \frac{g_{i}}{\frac{1}{A} \beta \varepsilon_{i-1}} \tag{1}
\end{align*}
$$

- Since the particles in a box are normal size and the translational levels are closely spaced and hence now the summation is replaced by integration.
- The number of particles states $g(p) d p$ between momentum p and $\mathrm{p}+\mathrm{dp}$ is given by

$$
=g_{s} \frac{4 \pi p^{2} d p}{h^{3} / V}=g_{s} \frac{4 \pi V p^{2} d p}{h^{3}}
$$

- $g_{s}=$ degenaracy factor $=1$

$$
\begin{equation*}
\text { Now } g(p) d p=\frac{4 \pi V p^{2} d p}{h^{3}} \tag{2}
\end{equation*}
$$

- Then equation (1) can be rewritten as

$$
\begin{align*}
n(p) d p & =\frac{g(p) d p}{e^{\alpha+\beta \varepsilon_{i}-1}} \\
& =\frac{4 \pi V p^{2} d p}{h^{3}} \frac{1}{e^{\alpha+\beta \varepsilon_{i-1}}}  \tag{3}\\
\varepsilon & =\varepsilon_{i}=\frac{p^{2}}{2 m} \\
p^{2} & =2 m \varepsilon \\
2 p d p & =2 m d \varepsilon
\end{align*}
$$

$$
\begin{aligned}
d p & =\frac{m}{p} d \varepsilon \\
& =\frac{m}{\sqrt{2 m \varepsilon}} d \varepsilon \\
& =\left(\frac{m}{2 \varepsilon}\right)^{1 / 2} d \varepsilon
\end{aligned}
$$

- Now equation (3) becomes

$$
\begin{align*}
n(\varepsilon) d \varepsilon & =\frac{4 \pi V}{h^{3}}(2 m \varepsilon)\left(\frac{m}{2 \varepsilon}\right)^{1 / 2} d \varepsilon \frac{1}{e^{\alpha+\varepsilon / k T}-1} \\
& =\frac{4 \pi m V}{h^{3}}(2 m \varepsilon)^{1 / 2} \frac{d \varepsilon}{e^{\alpha+\varepsilon / k T}-1}  \tag{4}\\
\frac{\varepsilon}{k T} & =x \\
\varepsilon & =k T x \\
d \varepsilon & =k T d x \\
n(\varepsilon) d \varepsilon & =\frac{4 \pi m V}{h^{3}}(2 m k T x)^{1 / 2} \frac{k T d x}{e^{\alpha+x}-1} \\
& =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1} \tag{5}
\end{align*}
$$

- The total number of particles is given by

$$
\begin{align*}
& \qquad \begin{aligned}
n & =\int_{0}^{\infty} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1} \\
& =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1} \\
n & =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \\
\text { where } f_{1}(\alpha) & =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1}
\end{aligned} \text { ( }
\end{align*}
$$

- The total energy is given by

$$
\begin{aligned}
E & =\int_{0}^{\infty} \varepsilon n(\varepsilon) d \varepsilon \\
& =\int_{0}^{\infty} k T x \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1}
\end{aligned}
$$

$$
\begin{align*}
& =\frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}-1} \\
& =\frac{3}{2} \frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} \frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}-1} \\
& =\frac{3}{2} \frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} f_{2}(\alpha)  \tag{8}\\
f_{2}(\alpha) & =\frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}-1} \tag{9}
\end{align*}
$$

- For $A<1, f_{1}(\alpha)$ and $f_{2}(\alpha)$ may be evaluated as follows:

$$
\begin{align*}
f_{1}(\alpha) & =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}-1} \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{\left(\frac{e^{x}}{A}-1\right)} \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} x^{1 / 2}\left(\frac{e^{x}}{A}-1\right)^{-1} d x \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} x^{1 / 2} A e^{-x}\left(1-A e^{-x}\right)^{-1} d x \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} x^{1 / 2} A e^{-x}\left[1+A e^{-x}+A^{2} e^{-2 x}+\cdots\right] d x \\
& =\frac{2}{\sqrt{\pi}}\left[\int_{0}^{\infty} x^{1 / 2} A e^{-x} d x+\int_{0}^{\infty} x^{1 / 2} A^{2} e^{-2 x} d x+\cdots\right] \\
& =\frac{2}{\sqrt{\pi}}\left[\sqrt{\frac{\pi}{2}}\left[A+\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots . .\right]\right] \\
& =A+\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots \ldots \ldots \ldots \\
f_{1}(\alpha) & =\sum_{r=1}^{\infty} \frac{A^{r}}{r^{3 / 2}} \tag{10}
\end{align*}
$$

- Similarly

$$
\begin{align*}
f_{2}(\alpha) & =\frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{\left(e^{-(\alpha+x)}-1\right)} \\
& =A+\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots \\
f_{2}(\alpha) & =\sum_{r=1}^{\infty} \frac{A^{r}}{r^{5 / 2}} \tag{11}
\end{align*}
$$

$$
\begin{align*}
\text { Now } \begin{aligned}
n & =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \\
& =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2}\left[A+\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots\right] \\
E & =\frac{3}{2} k T \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{2}(\alpha) . \\
E & =\frac{3}{2} k T \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2}\left[A+\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots\right] \\
\frac{E}{n} & =\frac{3}{2} k T\left[A+\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots\right]\left[A+\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots\right]^{-1} \\
& =\frac{3}{2} k T\left[1+\frac{A}{2^{5 / 2}}+\frac{A^{2}}{3^{5 / 2}}+\cdots\right]\left[1+\frac{A}{2^{3 / 2}}+\frac{A^{2}}{3^{3 / 2}}+\cdots\right]^{-1} \\
& =\frac{3}{2} k T\left[1-\frac{A}{2^{5 / 2}}+\frac{A^{2}}{3^{5 / 2}}+\cdots\right] \\
E & =\frac{3}{2} n k T\left[1-\frac{A}{2^{5 / 2}}+\frac{A^{2}}{3^{5 / 2}}+\cdots\right]
\end{aligned}, \ldots(1
\end{align*}
$$

- The value of $\alpha$ (or) A can be determined by equation (6) as

$$
\begin{aligned}
n & =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \\
f_{1}(\alpha) & =\frac{n}{V} \frac{h^{3}}{(2 \pi m k T)^{3 / 2}}
\end{aligned}
$$

- Here $f_{1}(\alpha)$ is directly proportional to particle density $\mathrm{n} / \mathrm{v}$ and inversely proportional to temperature as $T^{3 / 2}$.
- For $A \ll 1, f_{1}(\alpha)=A$

$$
\begin{equation*}
A=\frac{n}{V} \frac{h^{3}}{(2 \pi m k T)^{3 / 2}} \tag{15}
\end{equation*}
$$

- Obviously A would be small for high temperatures (low density).


## M-B distribution as a limiting case of B-E distribution:

- For $A \ll 1, e^{\alpha+\beta \varepsilon i}$ becomes very large compared to 1 .
- Now B-E distribution $n_{i}=\frac{g_{i}}{e^{\alpha+\beta} \varepsilon_{i-1}}$ becomes $n_{i}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}}}$ which is well known M$B$ distribution.
- For $A \ll 1, f_{1}(\alpha)=f_{2}(\alpha)=A$
- Equation (12) becomes

$$
n=\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \times A
$$

- Equation (13) becomes

$$
E=\frac{3}{2} k T \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \times A
$$

$$
\frac{E}{n}=\frac{3}{2} k T \Rightarrow E=\frac{3}{2} n k T
$$

- Which is well known expression for energy in M-B statistics.


### 5.12 BOSE-EINSTEIN CONDENSATION AND ITS CRITICAL CONDITIONS:

- The degeneracy parameter A is given by,

$$
\begin{equation*}
A=e^{-\alpha}=\frac{n}{V} \frac{(2 \pi m k T)^{3 / 2}}{h^{3}} \tag{1}
\end{equation*}
$$

- And $n=\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha)$
- If the particle density is increased or the temperature is decreased then A increases.
- Now the behaviour of perfect gas departs from the classical perfect gas.
- This is due to the fact that the velocities of the particles are subjected to quantum statistics.
- The gas under this condition is said to be degenerate gas and A is called the degeneracy parameter.
- 'A' contains three variables $\mathrm{n} / \mathrm{V}$ - the particle density, m - mass of each boson and

T -temperature of the gas.

- The degeneracy criterion will be based on the magnitude $\frac{n / V}{(m T)^{1 / 2}}$
- Thus the degree of degeneracy will be large when T is low, $\mathrm{n} / \mathrm{V}$ is large and m is small.
- For low energy values $\mathrm{A}=1$ and $\alpha=0$.
- Then $\left[f_{1}(\alpha)\right]_{\max }=f_{1}(0)=1+\frac{1}{2^{3 / 2}}+\frac{1}{3^{3 / 2}}+\cdots$

$$
\begin{equation*}
=2.612 \tag{4}
\end{equation*}
$$

- Now $\left(\frac{n}{V}\right)_{\max }=\frac{(2 \pi \pi m k T)^{3 / 2}}{h^{3}}$ (2.612)
- Equation (4) corresponds to the limiting case of Bose-Einstein degeneration.
- The solution of equation (2) can exist for

$$
\begin{equation*}
\frac{n}{V}>\frac{(2 \pi m k T)^{3 / 2}}{h^{3}}(2.612) \tag{5}
\end{equation*}
$$

- $\mathrm{n} / \mathrm{v}$ can be alternatively expressed in terms of critical temperature $T_{o}$ defined as

$$
\begin{align*}
\frac{n}{V} & =\frac{\left(2 \pi m k T_{0}\right)^{3 / 2}}{h^{3}}(2.612)  \tag{6}\\
\left(2 \pi m k T_{0}\right)^{3 / 2} & =h^{3} \frac{n}{V} \frac{1}{2.612} \\
2 \pi m k T_{0} & =h^{2}\left[\frac{n}{V} \frac{1}{2.612}\right]^{2 / 3} \\
T_{0} & =\frac{h^{2}}{2 \pi m k}\left[\frac{n}{V} \frac{1}{2.612}\right]^{2 / 3}
\end{align*}
$$

- $\mathrm{T}_{0}$ is the lower temperature for which a solution of equation (2) is possible.
- There is no solution for $T<T_{0}$
- i.e. the degeneracy starts at $\mathrm{T}_{0}$.
- A graph is drawn between the energy E and temperature T of the gas.
- Why there is no solution $T<T_{0}$
- Because we have assumed continuous distribution and replaced the summation by integration.
- But at low temperature, the number of particles begin to crowd into lower energy levels.
- Hence a large number of particles may occupy the
 ground state $\varepsilon_{0}=0$.
- The number of particles between the energy range $\varepsilon$ and $\varepsilon+d \varepsilon$ is given by,

$$
\begin{align*}
& n(\varepsilon) d \varepsilon=\frac{g(\varepsilon) d \varepsilon}{e^{\alpha+\varepsilon / k T}-1}  \tag{8}\\
& g(\varepsilon) d \varepsilon=\frac{4 \pi m v}{h^{3}}(2 m \varepsilon)^{1 / 2} d \varepsilon \tag{9}
\end{align*}
$$

- For ground state actually $\varepsilon_{0}=0$ andg $(\varepsilon)=1$ but not $g(\varepsilon)=0$
- For $\varepsilon \neq 0$ and $g(\varepsilon) \neq 0$, the distribution given by equation (8) is correct.
- But for $\varepsilon=0, g(\varepsilon)=0$ the law gives incorrect result.
- For a single state,$\quad n_{i}=\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i-1}}}$

$$
\begin{aligned}
& \varepsilon_{i}=\varepsilon_{0}=0 \\
& g_{i}=g\left(\varepsilon_{i}\right)=1
\end{aligned}
$$

$$
\begin{equation*}
n=n_{0}=\frac{1}{e^{\alpha}-1} \tag{10}
\end{equation*}
$$

- This gives the number of particles in the ground state.
- Now the total number of particles for the degenerate gas,

$$
\begin{align*}
n & =n_{0}+\int n(\varepsilon) d \varepsilon \\
& =n_{0}+\int_{0}^{\infty} \frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\alpha+\varepsilon / k T}-1} \\
& =n_{0}+n^{\prime}  \tag{11}\\
n^{\prime} & =\frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2} \int_{0}^{\infty} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\alpha+\varepsilon / k T}-1}  \tag{12}\\
n^{\prime} & =\frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \tag{13}
\end{align*}
$$

- From equation (6) $\frac{n}{V}=\frac{\left(2 \pi m k T_{0}\right)^{3 / 2}}{h^{3}}(2.612)$

$$
\frac{V}{h^{3}}\left(2 \pi m k T_{0}\right)^{3 / 2}=n \frac{1}{2.612}
$$

- Now

$$
\begin{equation*}
n^{\prime}=n\left(\frac{T}{T_{0}}\right)^{3 / 2} \frac{f_{1}(\alpha)}{2.612} \tag{14}
\end{equation*}
$$

- As $f_{1}(\alpha)<f_{1}(0), n^{\prime}$ acquires its maximum value when $\alpha=0$.
- Hence $f_{1}(\alpha)=2.612$ for maximum value.

$$
\begin{array}{rlrl}
n^{\prime} & =n\left(\frac{T}{T_{0}}\right)^{3 / 2} & \text { for } T<T_{0} \\
n & =n_{0}+n^{\prime} & \\
n & =n_{0}+n\left(\frac{T}{T_{0}}\right)^{3 / 2} & \\
n_{o} & =n-n\left(\frac{T}{T_{0}}\right)^{3 / 2} & \\
n_{0} & =n\left[1-\left(\frac{T}{T_{0}}\right)^{3 / 2}\right] & & \text { for } T<T_{0} \tag{15}
\end{array}
$$

- $n_{0}$ gives the number of particles condensed in the ground state.
- When the temperature is lowered below $\mathrm{T}_{0}$, the number of particles in the ground state rapidly increases.
- This rapid increase in the population of the ground state below the critical temperature $T_{0}$ for a Bose - Einstein gas is called Bose - Einstein condensation.
- Obviously $\mathrm{T}_{0}$ depends on the particle density $\mathrm{n} / \mathrm{V}$.
- Equation (15) is plotted in figure which represents the fraction of particles condensed in the ground state for $T<T_{0}$.
- At the ground state $\varepsilon=0$, the particles condensed in the ground state do not contribute to the energy.
- For above $\mathrm{T}_{\mathrm{o}},(\alpha \neq 0)$ there is negligible number of particles in the ground state and the gas is said to be classical or non - degenerate gas.
- Example: For Helium $\mathrm{T}_{0}$ can be calculated to have the value 3.12 K .
- Therefore the degeneration and condensation of Helium must start at 3.12 K .
- But experimental observation shows that the condensation of Helium starts at 2.19 K.
- i.e. the lambda point transition observed in liquid helium at 2.19 K is essentially a Bose-Einstein condensation.


### 5.13 BOSE - EINSTEIN CONDENSATION IN ULTRACOLD ATOMIC GASES :

- The first demonstration of Bose- Einstein condensation in ultracold atomic gases came in 1995.
- Since 1995, many isotopes have been Bose condensed including ${ }^{7} \mathrm{Li},{ }^{23} \mathrm{Na},{ }^{41} \mathrm{~K}$, ${ }^{52} \mathrm{Cr},{ }^{84} \mathrm{Sr},{ }^{85} \mathrm{Rb},{ }^{87} \mathrm{Rb},{ }^{133} \mathrm{Cs}$ and ${ }^{174} \mathrm{Yb}$.
- The first molecular Bose -Einstein condensates were created in 2003 by the research groups of Rudoif Grimm at the University of Innsbruck.
- The first step of the cooling of the atomic vapour uses three sets of counterpropagating laser beams oriented along cartesian axes that are tuned just below the resonant frequency of the atoms in the trap.
- Atoms that are stationary are just off resonance and so rarely absorb a photon.
- Moving atoms are Doppler shifted on resonance to the laser beam that is propagating opposite to the velocity vector of the atom.
- Those atoms preferentially absorb photons from that direction and then reemit in random directions, resulting in a net momentum kick opposite to the direction of motion.
- This results in an "optical molasses" that slows the atoms.
- This cooling method is constrained by the "recoil limit" in which the atoms have a minimum momentum of the order of the momentum of the photons used to cool the gas.

- This gives a limiting temperature of $(h f)^{2} / 2 m c^{2} k \approx 1 \mu K$, where $f$ is the frequency of the spectral line used for cooling and $m$ is the mass of an atom.
- In the next step of the cooling process, the lasers are turned off and a spatially varying magnetic field creates an attractive anisotropic harmonic oscillator potential near the center of the magnetic trap

$$
\begin{equation*}
V(r)=\frac{1}{2} m\left(\omega_{1}^{2} \mathrm{x}^{2}+\omega_{2}^{2} y^{2}+\omega_{3}^{2} z^{2}\right) \tag{1}
\end{equation*}
$$

- The frequencies of the trap $\omega_{\alpha}$ are controlled by the applied magnetic field. One can then lower the trap barrier using a resonant transition to remove the highest energy atoms in the trap. If the atoms in the vapor are sufficiently coupled to one other, then the remaining atoms in the trap are cooled by evaporation.
- If the interactions between the atoms in the gas can be neglected, the energy of each atom in the harmonic oscillator potential is

$$
\begin{equation*}
\varepsilon_{l_{1}, l_{2}, l_{3}}=\hbar \omega_{1} l_{1}+\hbar \omega_{2} l_{2}+\hbar \omega_{3} l_{3}+\frac{1}{2} \hbar\left(\omega_{1}+\omega_{2}+\omega_{3}\right) \tag{2}
\end{equation*}
$$

- where $l_{\alpha}(=0,1,2, \ldots . \infty)$ are the quantum numbers of the harmonic oscillator. If the three frequencies are all the same, then the quantum degeneracy of a level with energy $\varepsilon=\hbar \omega(1+3 / 2)$ is $(1+1)(1+2) / 2$
- For the general anisotropic case, the smoothed density of states as a function of energy (suppressing the zero point energy and assuming $\varepsilon \gg \hbar \omega_{\alpha}$ ) is given by

$$
\begin{equation*}
a(\varepsilon)=\int_{0}^{\infty} \int_{0}^{\infty} \int_{0}^{\infty} \delta\left(\varepsilon-\hbar \omega_{1} l_{1}-\hbar \omega_{2} l_{2}-\hbar \omega_{3} l_{3}\right) d l_{1} d l_{2} d l_{3}=\frac{\varepsilon^{2}}{2\left(\hbar \omega_{0}\right)^{3}} \tag{3}
\end{equation*}
$$

- where $\omega_{0}=\left(\omega_{1} \omega_{2} \omega_{3}\right)^{1 / 3}$; this assumes a single spin state per atom. The thermodynamic potential $\Pi$ for bosons in the trap is then given by

$$
\begin{equation*}
\Pi(\mu, T)=-\frac{(k T)^{4}}{2\left(\hbar \omega_{0}\right)^{3}} \int_{0}^{\infty} \mathrm{x}^{2} \ln \left(1-e^{-\mathrm{x}} e^{\beta \mu}\right) d \mathrm{x}=\frac{(k T)^{4}}{\left(\hbar \omega_{0}\right)^{3}} g_{4}(z) \tag{4}
\end{equation*}
$$

- where $\mathrm{z}=\exp (\beta \mu)$ is the fugacity. Volume is not a parameter in the thermodynamic potential since the atoms are confined by the harmonic trap. The average number of atoms in the excited states in the trap is

$$
\begin{equation*}
N(\mu T)=\left(\frac{\partial \Pi}{\partial \mu}\right)_{T}=\left(\frac{k T}{\hbar \omega_{0}}\right) g_{3}(z) \tag{5}
\end{equation*}
$$

- For fixed $N$, the chemical potential monotonically increases as temperature is lowered until Bose-Einstein condensation occurs when $\mu=0(z=1)$. The critical temperature for $N$ trapped atoms is then given by

$$
\begin{equation*}
\frac{k T_{c}}{\hbar \omega_{0}}=\left(\frac{N}{\varsigma(3)}\right)^{1 / 3} \tag{6}
\end{equation*}
$$

- where $\varsigma(3)=\mathrm{g}_{3}(1) \approx 1.202$. While the spacing of the energy levels is of order $\hbar \omega_{0}$, the critical temperature for condensation is much larger than the energy spacing of the lowest levels for $N \gg 1$.
- For $\mathrm{T}<\mathrm{T}_{\mathrm{c}}$ the number of atoms in the excited states is

$$
\begin{equation*}
\frac{N_{\text {excited }}}{N}=\frac{\varsigma(3)}{N}\left(\frac{k T}{\hbar \omega_{0}}\right)^{3}=\left(\frac{T}{T_{c}}\right)^{3} \tag{7}
\end{equation*}
$$

- so the fraction of atoms that condense into the ground state of the harmonic oscillator is

$$
\begin{equation*}
\frac{N_{0}}{N}=1-\left(\frac{T}{T_{c}}\right)^{3} \tag{8}
\end{equation*}
$$

(a) Detection of the Bose-Einstein condensate:

- The linear size of the ground state wave function in Cartesian direction $\alpha$ is

$$
\begin{equation*}
a_{\alpha}=\sqrt{\frac{\hbar}{m \omega_{\alpha}}}, \tag{9}
\end{equation*}
$$

- while the linear size of the thermal distribution of the noncondensed atoms in that direction is

$$
\begin{equation*}
a_{\text {thermal }}=\sqrt{\frac{k T}{m \omega_{\alpha}^{2}}}=a_{\alpha} \sqrt{\frac{k T}{\hbar \omega_{\alpha}}} \tag{10}
\end{equation*}
$$

- At trap frequency $f=100 \mathrm{~Hz}$ and temperature $T=100 \mathrm{nK}$, these sizes are about 1 $\mu \mathrm{m}$ and $5 \mu \mathrm{~m}$, respectively.
- Instead of measuring the atoms directly in the trapping potential, experimenters usually measure the momentum distribution of the ultracold gas by a time-offlight experiment.
- At time $t=0$, the magnetic field is turned off suddenly, eliminating the trapping potential.
- The atomic cloud then expands according to the momentum distribution the atoms had in the harmonic trap. The cloud is allowed to expand for about 100 milliseconds.
- The speed of the atoms at this temperature is a few millimeters per second, so the cloud expands to a few hundred microns in this period of time.
- The cloud is then illuminated with a laser pulse on resonance with the atoms, leaving a shadow on a CCD in the image plane of the optics.
- The size and shape of the light intensity pattern directly measures the momentum distribution the atoms had in the trap at $t=0$.
- The expanding cloud can be divided into two components, the $\mathrm{N}_{\mathrm{o}}$ atoms that had been Bose-condensed into the ground state and the remaining $N-N_{o}$ atoms that were in the excited states of the harmonic oscillator potential.
- The Bose-condensed atoms have smaller momenta than the atoms that were in the excited states.
- After time $t$, the quantum evolution of the ground state has a spatial number density

$$
\begin{equation*}
n_{0}(r, t)=N_{o}\left|\psi_{0}(r, t)\right|^{2}=\frac{N_{0}}{\pi^{3 / 2}} \prod_{\alpha=1}^{3}\left[\frac{1}{a_{\alpha} \sqrt{1+\omega_{\alpha}^{2} t^{2}}} \exp \left(\frac{-r_{\alpha}^{2}}{a_{\alpha}^{2}\left(1+\omega_{\alpha}^{2} t^{2}\right)}\right)\right] \tag{11}
\end{equation*}
$$

- The atoms that are not condensed into the ground state can be treated semi classically, that is, the position-momentum distribution function is treated classically while the density follows the Bose-Einstein distribution function:

$$
\begin{equation*}
\boldsymbol{f}(\boldsymbol{r}, \boldsymbol{p}, 0)=\frac{1}{\exp \left(\frac{\beta p^{2}}{2 m}+\frac{\beta m}{2}\left(\omega_{1}^{2} \mathrm{x}^{2}+\omega_{2}^{2} y^{2}+\omega_{3}^{2} z^{2}\right)-\beta u\right)-1} \tag{12}
\end{equation*}
$$

- After the potential is turned off at $t=0$, the distribution evolves ballistically:

$$
\begin{equation*}
f(r, p, 0)=f\left(r+\frac{p t}{m}, p, 0\right) \tag{13}
\end{equation*}
$$

- The spatial number density of atoms in the excited states is

$$
\begin{equation*}
n_{\text {excied }}(r, t)=\frac{1}{h^{3}} \int \mathrm{f}\left(r+\frac{p t}{m}, p, t\right) d p \tag{14}
\end{equation*}
$$

- which can be integrated to give

$$
\begin{equation*}
n_{\text {excited }}(r, t)=\frac{1}{\lambda^{3}} \sum_{j=1}^{\infty} \frac{e^{\beta \mu j}}{j^{3 / 2}}\left\{\prod_{\alpha=1}^{3}\left[\frac{1}{\sqrt{1+\omega_{\alpha}^{2} t^{2}}} \exp \left(\frac{-\beta j m \omega_{\alpha}^{2} r_{\alpha}^{2}}{2\left(1+\omega_{\alpha}^{2} t^{2}\right)}\right)\right]\right\} \tag{15}
\end{equation*}
$$

- where $\lambda=h / \sqrt{2 \pi m k T}$ is the thermal deBroglie wavelength. The integrals over the condensed state and the excited states correctly count all the atoms:

$$
\begin{align*}
N_{0} & =\int n_{o}(r, t) d r  \tag{16a}\\
N-N_{o} & =\int n_{\text {excited }}(r, t) d r=N_{\text {excied. }} . \tag{16b}
\end{align*}
$$

- Note that at early times $\omega_{\alpha} t \ll 1$ both the condensed and the excited distributions are anisotropic due to the anisotropic trapping potential.
- However, at late times $\omega_{\alpha} t \gg 1$, the atoms from the excited states form a spherically symmetric cloud because of the isotropic momentum dependence of the $t=0$ distribution function.
- By contrast, the atoms that were condensed into the ground state expand anisotropically due to the different spatial extents of the ground state wavefunction at $t=0$.
- The direction that has the largest $\omega_{0}$ is quantum mechanically squeezed the most at $t=0$; so, according to the uncertainty principle, it expands the fastest.
- This is an important feature of the experimental data that confirms the onset of Bose-Einstein condensation.
(b) Thermodynamic properties of the Bose-Einstein condensate :
- The temperature, condensate fraction, and internal energy can all be observed using time- of-flight measurements. The internal energy can also be written in terms of the function $g_{v}(z)$ :

$$
\begin{equation*}
U(\mu, T)=\int_{0}^{\infty} \frac{\varepsilon^{3}}{2\left(\hbar \omega_{0}\right)^{3}} \frac{1}{e^{\beta(\varepsilon-\mu)}-1} d \varepsilon=3 \frac{(k T)^{4}}{\left(\hbar \omega_{0}\right)^{3}} g_{4}(z) \tag{17}
\end{equation*}
$$

- The heat capacity at constant number can be written as

$$
\begin{align*}
\mathrm{C}_{\mathrm{N}}(\mathrm{~T})=\left(\frac{\partial \mathrm{U}}{\partial \mathrm{~T}}\right)_{\mathrm{N}} & =\left(\frac{\partial \mathrm{U}}{\partial \mathrm{~T}}\right)_{\mu}+\left(\frac{\partial \mathrm{U}}{\partial \mu}\right)_{\mathrm{T}}\left(\frac{\partial \mu}{\partial \mathrm{~T}}\right)_{\mathrm{N}} \\
& =\left(\frac{\partial U}{\partial T}\right)_{\mu}-\frac{\left(\frac{\partial U}{\partial T}\right)_{\mu}\left(\frac{\partial N}{\partial T}\right)_{\mu}}{\left(\frac{\partial N}{\partial \mu}\right)_{T}} \tag{18}
\end{align*}
$$

- Equations (5) and (6) can be used to determine the fugacity z numerically, as shown in Figure (a). The fugacity can then be used in equation (17) to obtain the scaled internal energy. [Figure (b)]



$$
\frac{U}{N k T_{c}}= \begin{cases}3\left(\frac{T}{T_{3}}\right)^{4} \frac{\varsigma(4)}{\varsigma(3)} & \text { for } T \leq T_{c,}  \tag{19}\\ 3\left(\frac{T}{T_{c}}\right)^{4} \frac{g_{4}(z)}{\varsigma(3)} & \text { for } T \geq T_{c ;}\end{cases}
$$

- The scaled specific heat is given by

$$
\frac{C_{N}}{N k}= \begin{cases}\frac{12 \varsigma(4)}{\varsigma(3)}\left(\frac{T}{T_{c}}\right)^{3} & \text { for } T<T_{c}  \tag{20}\\ \frac{1}{\varsigma(3)}\left(\frac{T}{T_{c}}\right)\left(12 g_{4}(z)-\frac{9 g_{3}^{2}(z)}{g_{2}(z)}\right) & \text { for } T>T_{c}\end{cases}
$$

and shown in figure (c).

- Unlike the case of Bose-Einstein condensation of free particles in a box the specific heat of a condensate in a harmonic trap displays a discontinuity at the critical temperature.


$$
\frac{C_{N}}{N k} \rightarrow \begin{cases}\frac{12 \varsigma(4)}{\varsigma(3)} \approx 10.805 & \text { as } T \rightarrow T_{c}^{-}  \tag{21}\\ \frac{12 \varsigma(4)}{\varsigma(3)}-\frac{9 \varsigma(3)}{\varsigma(2)} \approx 4.228 & \text { as } T \rightarrow T_{c}^{+}\end{cases}
$$

- Equation (15) is called the Virial equation of state.
- This equation can also be written in terms of the pair correlation function and is also used in computer simulations to determine the pressure of the system.


### 5.14 IDEAL FERMI-DIRAC GAS:

- Consider a perfect Fermi-Dirac gas of n Fermions.
- These particles be divided into quantum groups such that there are $n_{1}, n_{2}, \ldots, n_{i}, \ldots$ number of particles with energy is $\varepsilon_{1}, \varepsilon_{2}, \ldots, \varepsilon_{i}, \ldots$ respectively.
- $g_{i}$ be the number of eigen states in the $\mathrm{i}^{\text {th }}$ level.
- For the most probable distribution

$$
\begin{aligned}
n_{i} & =\frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}+1}} \text { here } \alpha=\frac{-\mu}{k T} \text { and } \beta=\frac{1}{k T} \\
& =\frac{g_{i}}{\bar{A}^{1} e^{\beta \varepsilon_{i}}+1}
\end{aligned} \text { where, } A=e^{-\alpha}
$$

$\alpha$ may be positive or negative.

- The constant $\alpha$ can be determined by the condition

$$
\begin{align*}
n & =\sum n_{i}=\sum \frac{g_{i}}{e^{\alpha+\beta \varepsilon_{i}}+1} \\
& =\sum \frac{g_{i}}{\frac{1}{A} e^{\beta \varepsilon_{i}}+1} \tag{1}
\end{align*}
$$

- Since the particles in a box are normal size and the translational levels are closely spaced and hence now the summation is replaced by integration.
- The number of particle states $g(p) d p$ between momentum p and $\mathrm{p}+\mathrm{dp}$ is given by

$$
=g_{s} \frac{4 \pi p^{2} d p}{h^{3} / V}=g_{s} \frac{4 \pi V p^{2} d p}{h^{3}}
$$

- $g_{s}=$ degenaracy factor $=(2 s+1)$

$$
\begin{equation*}
\text { Now } g(p) d p=g_{s} \frac{4 \pi V p^{2} d p}{h^{3}} \tag{2}
\end{equation*}
$$

- Then equation (1) can be rewritten as

$$
n(p) d p=\frac{g(p) d p}{e^{\alpha+\beta \varepsilon_{i}+1}}
$$

$$
\begin{align*}
& =g_{s} \frac{4 \pi V p^{2} d p}{h^{3}} \frac{1}{e^{\alpha+\beta \varepsilon_{i}+1}}  \tag{3}\\
\varepsilon & =\varepsilon_{i}=\frac{p^{2}}{2 m} \\
p^{2} & =2 m \varepsilon \\
2 p d p & =2 m d \varepsilon \\
d p & =\frac{m}{p} d \varepsilon \\
& =\frac{m}{\sqrt{2 m \varepsilon}} d \varepsilon \\
& =\left(\frac{m}{2 \varepsilon}\right)^{1 / 2} d \varepsilon
\end{align*}
$$

- Now equation (3) becomes

$$
\begin{align*}
n(\varepsilon) d \varepsilon & =g_{s} \frac{4 \pi V}{h^{3}}(2 m \varepsilon)\left(\frac{m}{2 \varepsilon}\right)^{1 / 2} d \varepsilon \frac{1}{e^{\alpha+\varepsilon / k T}+1} \\
& =g_{s} \frac{4 \pi m V}{h^{3}}(2 m \varepsilon)^{1 / 2} \frac{d \varepsilon}{e^{\alpha+\varepsilon / k T}+1}  \tag{4}\\
\frac{\varepsilon}{k T} & =x \\
\varepsilon & =k T x \\
d \varepsilon & =k T d x \\
n(\varepsilon) d \varepsilon & =g_{s} \frac{4 \pi m V}{h^{3}}(2 m k T x)^{1 / 2} \frac{k T d x}{e^{\alpha+x}+1} \\
& =g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \tag{5}
\end{align*}
$$

- The total number of particles is given by

$$
\begin{align*}
n & =\int_{0}^{\infty} g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \\
& =g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \\
n & =g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \tag{6}
\end{align*}
$$

$$
\begin{equation*}
\text { where } f_{1}(\alpha)=\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \tag{7}
\end{equation*}
$$

- The total energy is given by

$$
\begin{align*}
E & =\int_{0}^{\infty} \varepsilon n(\varepsilon) d \varepsilon \\
& =\int_{0}^{\infty} k T x g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \\
& =g_{s} \frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} \frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}+1} \\
& =\frac{3}{2} g_{s} \frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} \frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}+1} \\
& =\frac{3}{2} g_{s} \frac{V}{h^{3}} k T(2 \pi m k T)^{3 / 2} f_{2}(\alpha)  \tag{8}\\
f_{2}(\alpha) & =\frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{e^{\alpha+x}+1} \tag{9}
\end{align*}
$$

- $f_{1}(\alpha)$ and $f_{2}(\alpha)$ must be evaluated for both positive and negative values of $\alpha$.
- Now we introduce the Fermi-Dirac distribution function $f(\varepsilon)$ defined by,

$$
\begin{align*}
f(\varepsilon) & =\frac{n(\varepsilon)}{g(\varepsilon)} \\
& =\frac{1}{e^{\alpha+\varepsilon / k T}+1} \\
& =\frac{1}{\left.e^{(\varepsilon-\varepsilon}\right) / k T}+1 \tag{10}
\end{align*}
$$

- Where $\alpha=-\frac{\mu}{k T}=-\frac{\varepsilon_{F}}{k T}$
- At T=0 K, $f(\varepsilon)=1$ for $\varepsilon<\varepsilon_{F}(0)$

$$
\begin{aligned}
& =0 \text { for } \varepsilon>\varepsilon_{F}(0) \\
& =\frac{1}{2} \text { for } \varepsilon=\varepsilon_{F}
\end{aligned}
$$

- This is shown in the figure.
- $\varepsilon_{F}$ is determined by the condition that the total number of particles is constant at a given
 temperature T .
- The number of fermions in the energy range between $\varepsilon$ and $\varepsilon+d \varepsilon$ is given by,

$$
n(\varepsilon) d \varepsilon=\int f(\varepsilon) g(\varepsilon) d \varepsilon
$$

$$
\begin{equation*}
=g_{s} \frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F)} / k T\right.}+1} \tag{11}
\end{equation*}
$$

- At absolute zero, all states with $0<\varepsilon<\varepsilon_{F}(0)$ are completely filled and all states with $\varepsilon>\varepsilon_{F}(0)$ are empty.
- $\varepsilon_{F}$ at $\mathrm{T}=0 \mathrm{~K}$ i.e. $\varepsilon_{F}(0)$ is determined by,

$$
\begin{align*}
n & =\int_{0}^{\varepsilon_{F}(0)} n(\varepsilon) d \varepsilon \\
& =\int_{0}^{\varepsilon_{F}(0)} f(\varepsilon) g(\varepsilon) d \varepsilon \\
& =\int_{0}^{\varepsilon_{F}(0)} g(\varepsilon) d \varepsilon \\
& =\int_{0}^{\varepsilon_{F}(0)} g_{s} \frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2} \varepsilon^{1 / 2} d \varepsilon \\
& =g_{s} \frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2} \int_{0}^{\varepsilon_{F}(0)} \varepsilon^{1 / 2} d \varepsilon \\
n & =g_{s} \frac{4 \pi m V}{h^{3}}(2 m)^{1 / 2}\left[\frac{2}{3} \varepsilon_{F}(0)^{3 / 2}\right] \\
{\left[\varepsilon_{F}(0)\right]^{3 / 2} } & =\frac{3 n}{4 \pi V g_{s}} \frac{h^{3}}{(2 m)^{3 / 2}} \\
\varepsilon_{F}(0) & =\frac{h^{2}}{2 m}\left[\frac{3 n}{4 \pi V g_{s}}\right] 2 / 3 \tag{12}
\end{align*}
$$

- This gives the Fermi-energy at $\mathrm{T}=0 \mathrm{~K}$.
- For particles with spin equal to $1 / 2, g_{s}=2$ ie, one particle with spin up and another with spin down.
- Now we define Fermi temperature $T_{F}$ as,

$$
\begin{align*}
T_{F} & =\frac{\varepsilon_{F}(0)}{k} \\
& =\frac{h^{2}}{2 m k}\left(\frac{3 n}{4 \pi V g_{s}}\right)^{2 / 3} \\
\rho & =\frac{m n}{V} \Rightarrow \frac{n}{V}=\frac{\rho}{m} \\
T_{F} & =\frac{h^{2}}{2 m k}\left(\frac{3 \rho}{4 \pi m g_{s}}\right)^{2 / 3} \\
T_{F} & =\frac{h^{2}}{2 m^{5 / 3} k}\left[\frac{3 \rho}{4 \pi g_{s}}\right]^{2 / 3} \tag{13}
\end{align*}
$$

- $T \ll T_{F} \quad$ strong degeneracy $\quad \alpha$ is negative
- $T>T_{F} \quad$ weak degeneracy $\quad \alpha$ is positive
- $T \gg T_{F} \quad$ non degeneracy $\quad \alpha$ is positive


## (A) Degeneracy:

## i. Weak degeneracy: (High temperature and low density)

$T>T_{F} ; \varepsilon_{F}$ is negative ; $\alpha$ is positive and hence $A<1$.
For $A<1$, we can write

$$
\begin{align*}
\frac{1}{\frac{1}{A} e^{x}+1} & =\left(\frac{1}{A} e^{x}+1\right)^{-1} \\
& =A e^{-x}\left[1+A e^{-x}\right]^{-1} \\
& =A e^{-x}\left[1-A e^{-x}+A^{2} e^{-2 x}+\cdots\right] \\
f_{1}(\alpha) & =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{e^{\alpha+x}+1} \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} \frac{x^{1 / 2} d x}{\left(\frac{1}{A} e^{x}+1\right)} \\
& =\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} x^{1 / 2} d x A e^{-x}\left[1-A e^{-x}+A^{2} e^{-2 x}+\cdots\right] \\
=\frac{2}{\sqrt{\pi}}\left[A \int_{0}^{\infty} x^{1 / 2} e^{-x} d x\right. & \left.-A^{2} \int_{0}^{\infty} x^{1 / 2} e^{-2 x} d x+A^{3} \int_{0}^{\infty} x^{1 / 2} e^{-3 x} d x+\cdots\right] \\
& =A-\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots \tag{1}
\end{align*} .
$$

- Similarly

$$
\begin{align*}
f_{2}(\alpha) & =\frac{4}{3 \sqrt{\pi}} \int_{0}^{\infty} \frac{x^{3 / 2} d x}{\left(\frac{1}{A} e^{x}+1\right)} \\
& =A-\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots \tag{2}
\end{align*}
$$

- Now

$$
\begin{align*}
n & =g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2} f_{1}(\alpha) \\
& =g_{s} \frac{V}{h^{3}}(2 \pi m k T)^{3 / 2}\left[A-\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots\right]  \tag{3}\\
E & =\frac{3}{2} g_{s} \frac{v}{h^{3}}(2 \pi m k T)^{3 / 2} k T f_{2}(\alpha) \\
& =\frac{3}{2} g_{s} \frac{v}{h^{3}}(2 \pi m k T)^{3 / 2}\left[A-\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots\right]  \tag{4}\\
\frac{E}{n} & =\frac{3}{2} k T\left[A-\frac{A^{2}}{2^{5 / 2}}+\frac{A^{3}}{3^{5 / 2}}+\cdots\right]\left[A-\frac{A^{2}}{2^{3 / 2}}+\frac{A^{3}}{3^{3 / 2}}+\cdots\right]^{-1} \\
& =\frac{3}{2} k T\left[1+\frac{A}{2^{5 / 2}}-\frac{A^{2}}{3^{5 / 2}}+\cdots\right] \tag{5}
\end{align*}
$$

- To find first approximation we can get,

$$
\frac{E}{n}=\frac{3}{2} k T
$$

$$
\begin{equation*}
E=\frac{3}{2} n k T \tag{6}
\end{equation*}
$$

- which is well known relation for E in classical statistics.
- Comparison of equations (5) and (6) shows that the ideal Fermi-Dirac gas deviates from a classical perfect gas and this deviation is known as degeneracy.
- A is the degeneracy function and greater the value of A , more will be the degeneracy.


## ii. Strong degeneracy: (low temperature and high density)

- Here we discuss the degeneracy case in two temperature ranges.
- (a) At absolute zero(T=0 K)
- (b) Above absolute zero
(a) At absolute zero( $\mathbf{T}=0 \mathrm{~K}$ ):
- In this case the Fermi-dirac gas is completely degenerate.
- At T $=0 \mathrm{~K}, \quad f(\varepsilon)=\frac{1}{\frac{1}{A} e^{\varepsilon / k T}+1}$

$$
\begin{aligned}
& =\frac{1}{\frac{A^{e}\left(\varepsilon-\varepsilon_{F}\right) / k T}{}+1} \\
& =1 \\
& =1 \\
& \text { for }
\end{aligned} \quad 0 \leq \varepsilon \leq \varepsilon_{F}(0)
$$

- So that $\quad n(\varepsilon) d \varepsilon=g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2} \varepsilon^{1 / 2} d \varepsilon \quad$ for $0 \leq \varepsilon \leq \varepsilon_{F}(0)$

$$
=0 \quad \text { for } \varepsilon>\varepsilon_{F}(0)
$$

- The total internal energy of Fermi-Dirac gas at $\mathrm{T}=0 \mathrm{~K}$ gives zero point energy.

$$
\begin{aligned}
E_{0} & =\int_{0}^{\varepsilon_{F}(0)} \varepsilon n(\varepsilon) d \varepsilon \\
& =\int_{0}^{\varepsilon_{F}(0)} g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2} \varepsilon^{1 / 2} d \varepsilon \\
& =g_{S}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2} \int_{0}^{\varepsilon_{F}(0)} \varepsilon^{3 / 2} d \varepsilon \\
& =g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2} \frac{\left[\varepsilon_{F}(0)\right]^{5 / 2}}{5 / 2} \\
& =\frac{2}{5} g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2}\left[\varepsilon_{F}(0)\right]^{5 / 2}
\end{aligned}
$$

$$
\begin{align*}
& =\frac{2}{5} g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{1 / 2}\left[\frac{h^{2}}{2 m}\left(\frac{3 n}{4 \pi v g_{s}}\right)^{2 / 3}\right]^{5 / 2} \\
& =\frac{3 n}{5}\left(\frac{4 \pi V g_{s}}{3 n}\right)\left(\frac{2 m}{h^{2}}\right)^{3 / 2} \frac{h^{5}}{(2 m)^{5 / 2}}\left(\frac{3 n}{4 \pi v g_{s}}\right)^{5 / 3} \\
& =\frac{3 n}{5} \frac{h^{2}}{2 m}\left(\frac{3 n}{4 \pi V g_{s}}\right)^{2 / 3} \\
E_{0} & =\frac{3 n}{5} \varepsilon_{F}(0) \tag{7}
\end{align*}
$$

- Zero point pressure $p_{0}=\frac{2}{3} \frac{E_{0}}{V}$

$$
\begin{align*}
& =\frac{2}{3} \frac{1}{V} \frac{3 n}{5} \varepsilon_{F}(0) \\
p_{0} & =\frac{2}{5} \frac{n}{V} \varepsilon_{F}(0) \tag{8}
\end{align*}
$$

- Thus a strongly degenerate Fermi-Dirac gas possesses energy and pressure even at absolute zero.
(b) Above absolute zero: $\boldsymbol{A} \gg 1$ and $T \ll \boldsymbol{T}_{\boldsymbol{F}}$
- The Fermi gas is strongly degenerate and $\varepsilon$ is still positive.
- The number of particles in the energy range between $\varepsilon$ and $\varepsilon+d \varepsilon$ is given by,

$$
\begin{align*}
n(\varepsilon) d \varepsilon & =g_{s}\left(\frac{4 \pi m V}{h^{3}}\right)(2 m)^{\frac{1}{2}} \frac{\varepsilon^{\frac{1}{2}} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}  \tag{9}\\
& =3 n\left(\frac{4 \pi V g_{s}}{3 n}\right)\left(\frac{2 m^{3}}{h^{6}}\right)^{1 / 2} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}
\end{align*}
$$

- We have Fermi energy

$$
\begin{aligned}
\varepsilon_{F}(0) & =\frac{h^{2}}{2 m}\left(\frac{3 n}{4 \pi v g_{s}}\right)^{2 / 3} \\
\left(\frac{3 n}{4 \pi v g_{s}}\right)^{2 / 3} & =\left[\frac{2 m \varepsilon_{F}(0)}{h^{2}}\right] \\
\left(\frac{3 n}{4 \pi v g_{s}}\right) & =\left[\frac{2 m \varepsilon_{F}(0)}{h^{2}}\right]^{3 / 2} \\
\left(\frac{4 \pi v g_{s}}{3 n}\right) & =\left[\frac{2 m \varepsilon_{F}(0)}{h^{2}}\right]^{-3 / 2}
\end{aligned}
$$

$$
\begin{align*}
& =\left[\frac{h^{2}}{2 m \varepsilon_{F}(0)}\right]^{3 / 2} \\
n(\varepsilon) d \varepsilon & =3 n\left[\frac{h^{2}}{2 m \varepsilon_{F}(0)}\right]^{3 / 2}\left(\frac{2 m^{3}}{h^{6}}\right)^{1 / 2} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1} \\
& =\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}  \tag{10}\\
n & =\int_{0}^{\infty} n(\varepsilon) d \varepsilon \\
& =\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}} \int_{0}^{\infty} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}  \tag{11}\\
E & =\int_{0}^{\infty} \varepsilon n(\varepsilon) d \varepsilon \\
& =\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}} \int_{0}^{\infty} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1} \tag{12}
\end{align*}
$$

- To solve the integrals in equation (11) and (12), we consider the general integral

$$
\begin{equation*}
I=\int_{0}^{\infty} \frac{\varphi(\varepsilon) d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1} \tag{13}
\end{equation*}
$$

- Here, $\varphi(\varepsilon)$ is a function of $\varepsilon$ such that $\varphi(\varepsilon)=0$ at $\varepsilon=0$.
- By Taylor series expansion,

$$
\begin{aligned}
& \int_{0}^{\infty} \frac{\varphi(\varepsilon) d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}=\int_{0}^{\varepsilon_{F}} \varphi(\varepsilon) d \varepsilon+\frac{(\pi k T)^{2}}{6}\left[\varphi^{\prime}\right]_{\varepsilon=\varepsilon_{F}}+\frac{7}{360}(\pi k T)^{4}\left(\varphi^{\prime \prime \prime}\right)_{\varepsilon=\varepsilon_{F}}+\cdots \\
& \text { Take } \varphi(\varepsilon)=\varepsilon^{1 / 2} \\
&\left.\varphi^{\prime}\right|_{\varepsilon=\varepsilon_{F}}=\frac{1}{2} \varepsilon_{F}^{-1 / 2} \\
&\left.\varphi^{\prime \prime \prime}\right|_{\varepsilon=\varepsilon_{F}}=-\frac{1}{4} \varepsilon_{F}^{-3 / 2} \\
&\left.\varphi^{\prime \prime \prime}\right|_{\varepsilon=\varepsilon_{F}}=\frac{3}{8} \varepsilon_{F}^{-5 / 2} \\
& n=\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}} \int_{0}^{\infty} \frac{\varepsilon^{1 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1} \\
&=\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}}\left[\frac{2}{3} \varepsilon_{F}^{3 / 2}+\frac{(\pi k T)^{2}}{6} \frac{1}{2} \varepsilon_{F}^{-1 / 2}+\frac{7}{360}(\pi k T)^{4} \frac{3}{8} \varepsilon_{F}^{-5 / 2}+\cdots\right]
\end{aligned}
$$

$$
\begin{aligned}
n & =n\left[\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right]^{3 / 2}\left[1+\frac{1}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}+\frac{7}{640}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{4}+\cdots \ldots \ldots\right] \\
{\left[\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right]^{3 / 2} } & =\left[1+\frac{1}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}+\frac{7}{640}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{4}+\cdots \ldots \cdots\right]
\end{aligned}
$$

- To the first approximation we get ,

$$
\begin{align*}
{\left[\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right]^{-3 / 2} } & =\left[1+\frac{1}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}\right] \\
{\left[\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right] } & =\left[1+\frac{1}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}\right]^{-2 / 3} \\
& =\left[1-\frac{1}{12}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}\right]  \tag{14}\\
\varepsilon_{F} & =\varepsilon_{F}(0)\left[1-\frac{1}{12}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}\right]
\end{align*}
$$

- By applying Crude approximation we get,

$$
\begin{equation*}
\varepsilon_{F}=\varepsilon_{F}(0)\left[1-\frac{1}{12}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \tag{16}
\end{equation*}
$$

Take $\quad \varphi(\varepsilon)=\varepsilon^{3 / 2}$

$$
\begin{aligned}
& \int_{0}^{\varepsilon_{F}} \varepsilon^{3 / 2} d \varepsilon=\frac{2}{5}\left(\varepsilon_{F}\right)^{5 / 2} \\
& \left.\varphi^{\prime}(\varepsilon)\right|_{\varepsilon=\varepsilon_{F}}=\frac{3}{2} \varepsilon_{F}^{1 / 2} \\
& \left.\varphi^{\prime \prime}(\varepsilon)\right|_{\varepsilon=\varepsilon_{F}}=\frac{3}{4} \varepsilon_{F}-1 / 2 \\
& \left.\varphi^{\prime \prime \prime}(\varepsilon)\right|_{\varepsilon=\varepsilon_{F}}=-\frac{3}{8} \varepsilon_{F}-3 / 2
\end{aligned}
$$

$$
E=\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}} \int_{0}^{\infty} \frac{\varepsilon^{3 / 2} d \varepsilon}{e^{\left(\varepsilon-\varepsilon_{F}\right) / k T}+1}
$$

$$
=\frac{3}{2} \frac{n}{\left[\varepsilon_{F}(0)\right]^{3 / 2}}\left[\frac{2}{5} \varepsilon_{F}^{5 / 2}+\frac{(\pi k T)^{2}}{6} \frac{3}{2} \varepsilon_{F}^{1 / 2}-\frac{7}{360}(\pi k T)^{4} \frac{3}{8} \varepsilon_{F}^{-3 / 2}+\cdots\right]
$$

$$
=\frac{3}{5} n \frac{\varepsilon_{F} 5 / 2}{\left[\varepsilon_{F}(0)\right]^{3 / 2}}\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}-\frac{7}{384}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{4}+\cdots\right]
$$

$$
=\frac{3}{5} n \varepsilon_{F}(0)\left(\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right)^{5 / 2}\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}-\frac{7}{384}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{4}+\cdots\right]
$$

- To the first approximation we get,

$$
\begin{equation*}
E=\frac{3}{5} n \varepsilon_{F}(0)\left(\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right)^{5 / 2}\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}}\right)^{2}\right] \tag{17}
\end{equation*}
$$

- By applying Crude approximation we get,

$$
\begin{equation*}
E=\frac{3}{5} n \varepsilon_{F}(0)\left(\frac{\varepsilon_{F}}{\varepsilon_{F}(0)}\right)^{5 / 2}\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \tag{18}
\end{equation*}
$$

- Using equation (16) we get,

$$
\begin{align*}
& =\frac{3}{5} n \varepsilon_{F}(0)\left[1-\frac{1}{12}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right]^{5 / 2}\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \\
& =\frac{3}{5} n \varepsilon_{F}(0)\left[1-\frac{5}{24}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right]\left[1+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \\
& =\frac{3}{5} n \varepsilon_{F}(0)\left[1-\frac{5}{24}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}+\frac{5}{8}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \\
& E=\frac{3}{5} n \varepsilon_{F}(0)\left[1+\frac{5}{12}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \tag{19}
\end{align*}
$$

- The corresponding pressure is

$$
\begin{align*}
p & =\frac{2}{3} \frac{E}{V} \\
& =\frac{2}{5} \frac{n \varepsilon_{F}(0)}{V}\left[1+\frac{5}{12}\left(\frac{\pi k T}{\varepsilon_{F}(0)}\right)^{2}\right] \tag{20}
\end{align*}
$$

- Equations (19) and (20) give the approximate energy and pressure of a strongly degenerate Fermi gas and also known as equation of state of an ideal Fermi gas.


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[^0]:    

[^1]:    Manonmaniam Sundaranar University, Directorate of Distance \& Continuing Education, Tirunelveli.

